



SC395: Image Generative Models in Computer Vision

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Lecture 4

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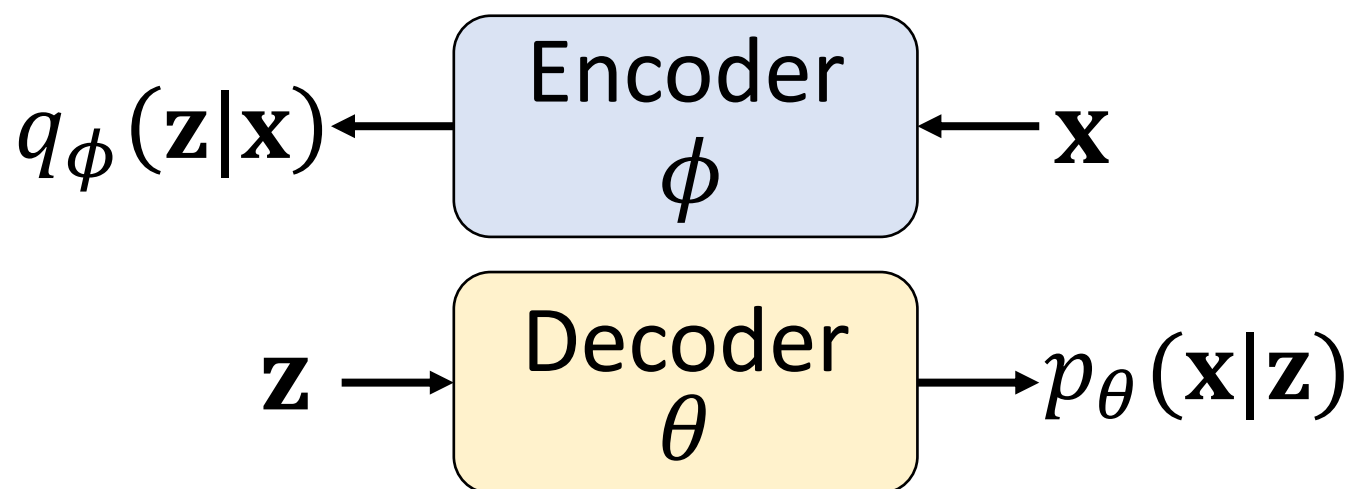
Diffusion Models

Guidance, LDMs, Efficiency, Adaptation



$$\log p(\mathbf{x}) \geq \mathbb{E}_{q(\mathbf{z}|\mathbf{x})} \left[\log \frac{p(\mathbf{x}, \mathbf{z})}{q(\mathbf{z}|\mathbf{x})} \right]$$

Evidence Evidence Lower Bound (ELBO)





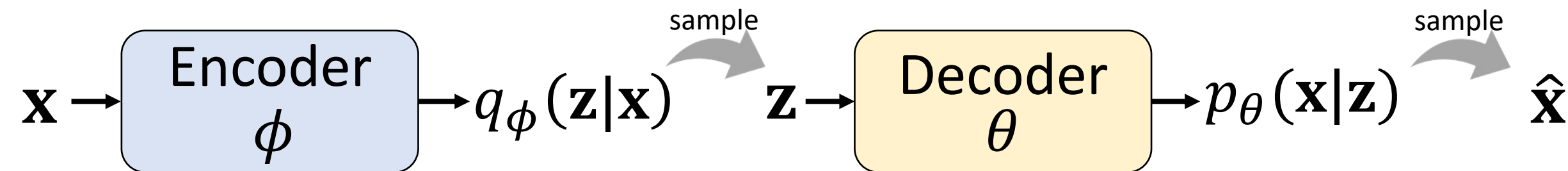
$$\log p(\mathbf{x}) \geq \mathbb{E}_{q(\mathbf{z}|\mathbf{x})} \left[\log \frac{p(\mathbf{x}, \mathbf{z})}{q(\mathbf{z}|\mathbf{x})} \right] \quad (\text{ELBO})$$

$$\begin{aligned} \mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x})} \left[\log \frac{p(\mathbf{x}, \mathbf{z})}{q_{\phi}(\mathbf{z}|\mathbf{x})} \right] &= \mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x})} \left[\log \frac{p_{\theta}(\mathbf{x}|\mathbf{z})p(\mathbf{z})}{q_{\phi}(\mathbf{z}|\mathbf{x})} \right] \\ &= \mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x})} [\log p_{\theta}(\mathbf{x}|\mathbf{z})] + \mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x})} \left[\log \frac{p(\mathbf{z})}{q_{\phi}(\mathbf{z}|\mathbf{x})} \right] \\ &= \underbrace{\mathbb{E}_{q_{\phi}(\mathbf{z}|\mathbf{x})} [\log p_{\theta}(\mathbf{x}|\mathbf{z})]}_{\text{Reconstruction term}} - \underbrace{D_{\text{KL}}(q_{\phi}(\mathbf{z}|\mathbf{x}) \parallel p(\mathbf{z}))}_{\text{Regularization term}} \end{aligned}$$

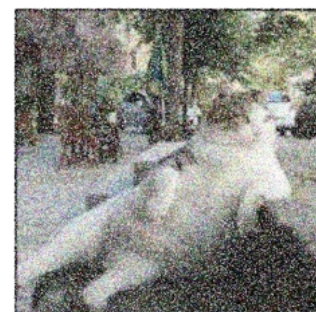
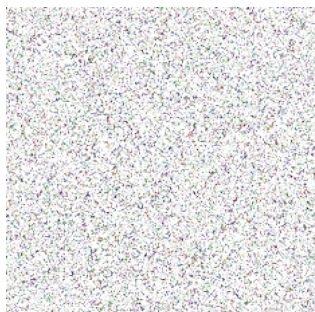
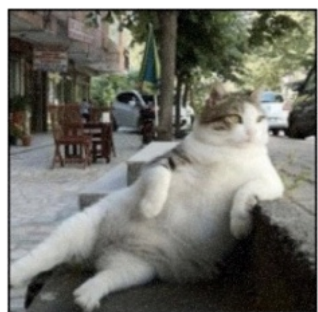
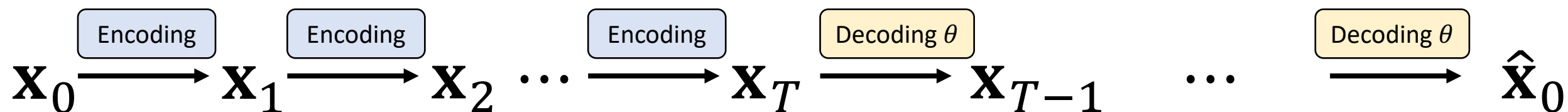
$$\|\mathbf{x} - \hat{\mathbf{x}}\|_2 = \|\mathbf{x} - DE(EN(\mathbf{z}))\|_2 - \frac{1}{2} \sum_{j=0}^{k-1} (\sigma_j + \mu_j^2 - 1 - \log \sigma_j)$$



Variational Autoencoder (VAE)

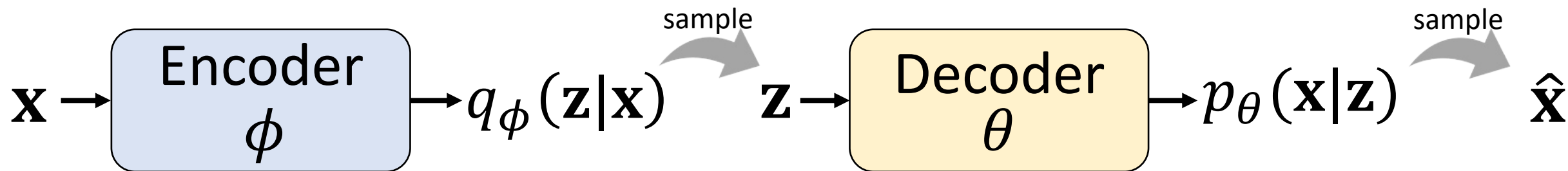


Diffusion models





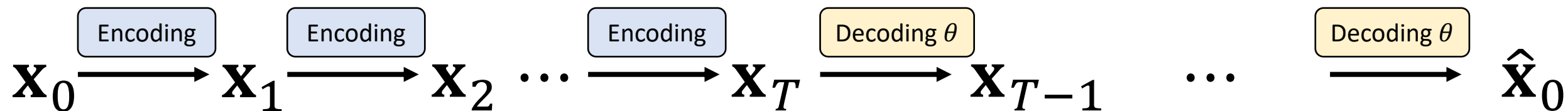
Variational Autoencoder (VAE)



Observed $\mathbf{x}$
 Latent $\mathbf{z}$

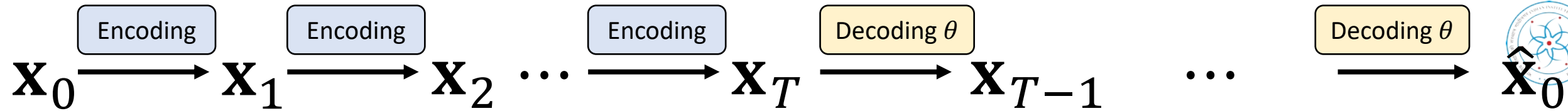
Maximize $\mathbb{E}_{q(\mathbf{z}|\mathbf{x})} \left[\log \frac{p(\mathbf{x}, \mathbf{z})}{q(\mathbf{z}|\mathbf{x})} \right]$

Diffusion models



Observed $\mathbf{x}_0$
 Latent $\mathbf{x}_1, \dots, \mathbf{x}_T$

Maximize $\mathbb{E}_{q(\mathbf{x}_1:\mathbf{x}_T|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_0:\mathbf{x}_T)}{q(\mathbf{x}_1:\mathbf{x}_T|\mathbf{x}_0)} \right]$



$$\text{Maximize } \mathbb{E}_{q(\mathbf{x}_1:\mathbf{x}_T|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_0:\mathbf{x}_T)}{q(\mathbf{x}_1:\mathbf{x}_T|\mathbf{x}_0)} \right]$$

$$q(\mathbf{x}_1:\mathbf{x}_T|\mathbf{x}_0) = \prod_{t=1}^T q(\mathbf{x}_t|\mathbf{x}_{t-1})$$

Encoding



$$q(\mathbf{x}_t|\mathbf{x}_{t-1})$$

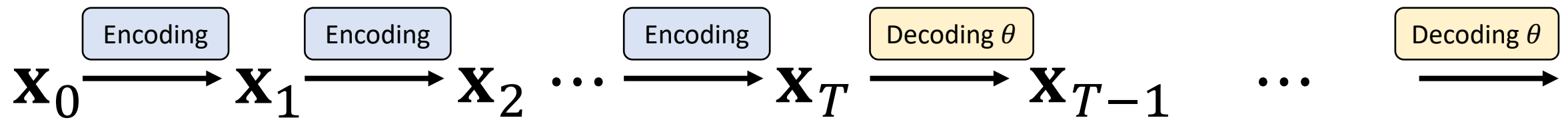
Encoding

$$= \mathcal{N}(\mathbf{x}_t; \sqrt{\alpha_t} \mathbf{x}_{t-1}, (1 - \alpha_t) \mathbf{I})$$

Mean

Variance

Slide from Jia-Bin Huang

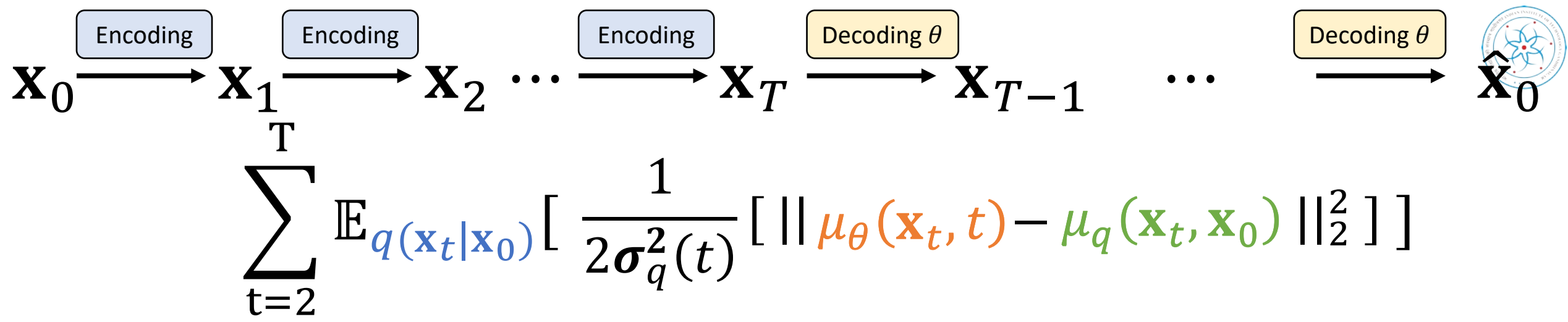


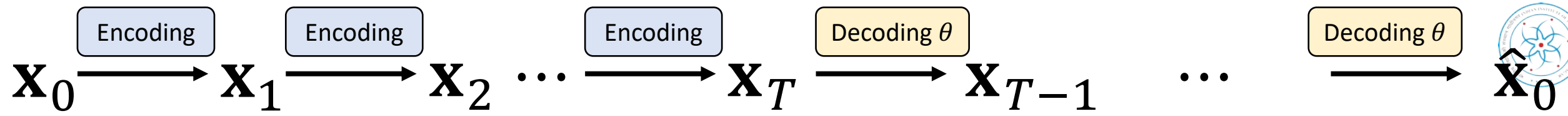
$$\mathbb{E}_{q(\mathbf{x}_1:\mathbf{x}_T|\mathbf{x}_0)} \left[\log \frac{p(\mathbf{x}_0:\mathbf{x}_T)}{q(\mathbf{x}_1:\mathbf{x}_T|\mathbf{x}_0)} \right]$$

① $-D_{\text{KL}}(q(\mathbf{x}_T|\mathbf{x}_0)||p(\mathbf{x}_T))$ **Prior matching**

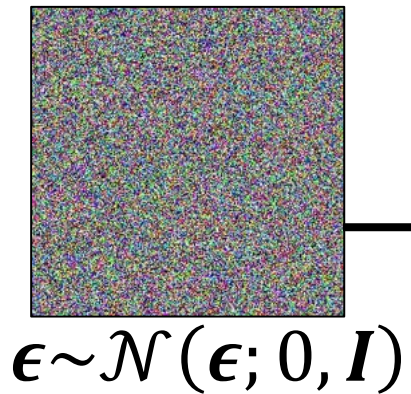
② $\mathbb{E}_{q(\mathbf{x}_1|\mathbf{x}_0)} [\log p_\theta(\mathbf{x}_0|\mathbf{x}_1)]$ **Reconstruction**

③ $-\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} [D_{\text{KL}}(q(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0)||p_\theta(\mathbf{x}_{t-1}|\mathbf{x}_t))] \mathbf{Denoising matching}$



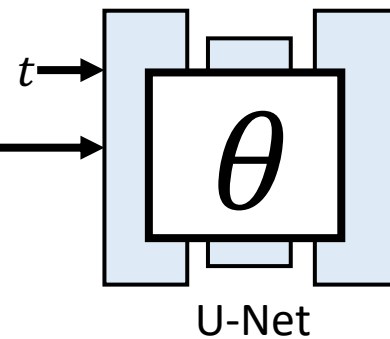
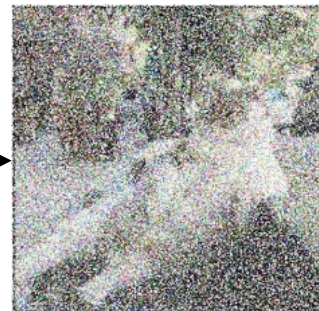
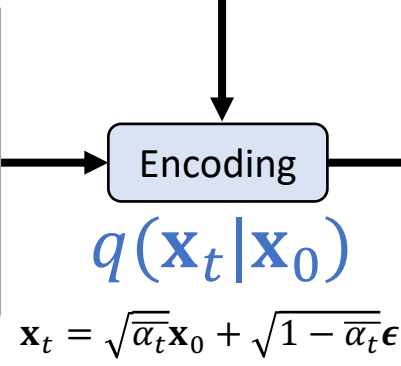


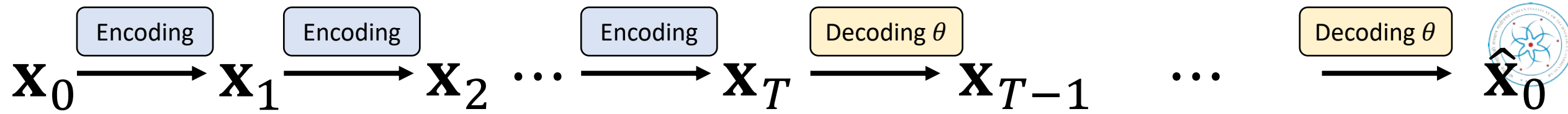
$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} [w(t) [|| \hat{\mathbf{x}}_{\theta}(\mathbf{x}_t, t) - \mathbf{x}_0 ||_2^2]]$$



$$\mu_q(\mathbf{x}_t, \mathbf{x}_0) = \frac{\sqrt{\alpha_t}(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t} \mathbf{x}_t + \frac{\sqrt{\bar{\alpha}_{t-1}}(1 - \alpha_t)}{1 - \bar{\alpha}_t} \mathbf{x}_0$$

$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{\sqrt{\alpha_t}(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t} \mathbf{x}_t + \frac{\sqrt{\bar{\alpha}_{t-1}}(1 - \alpha_t)}{1 - \bar{\alpha}_t} \hat{\mathbf{x}}_{\theta}(\mathbf{x}_t, t)$$

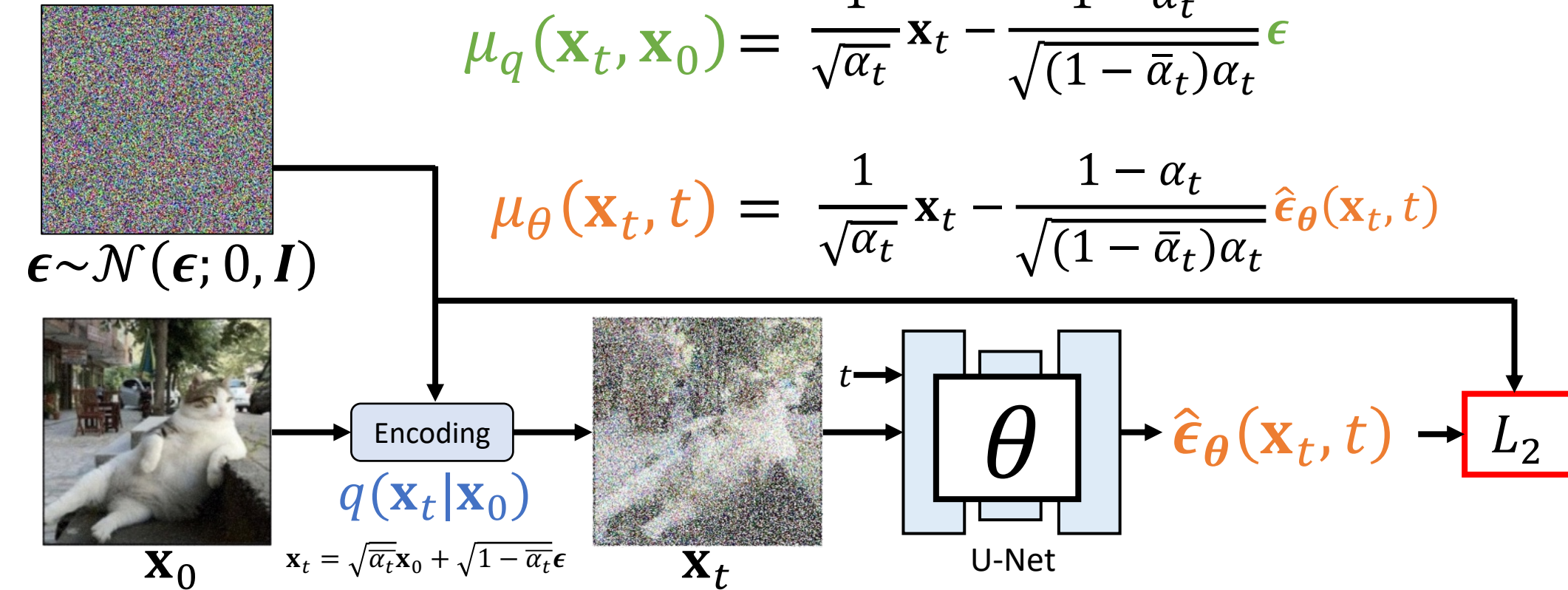


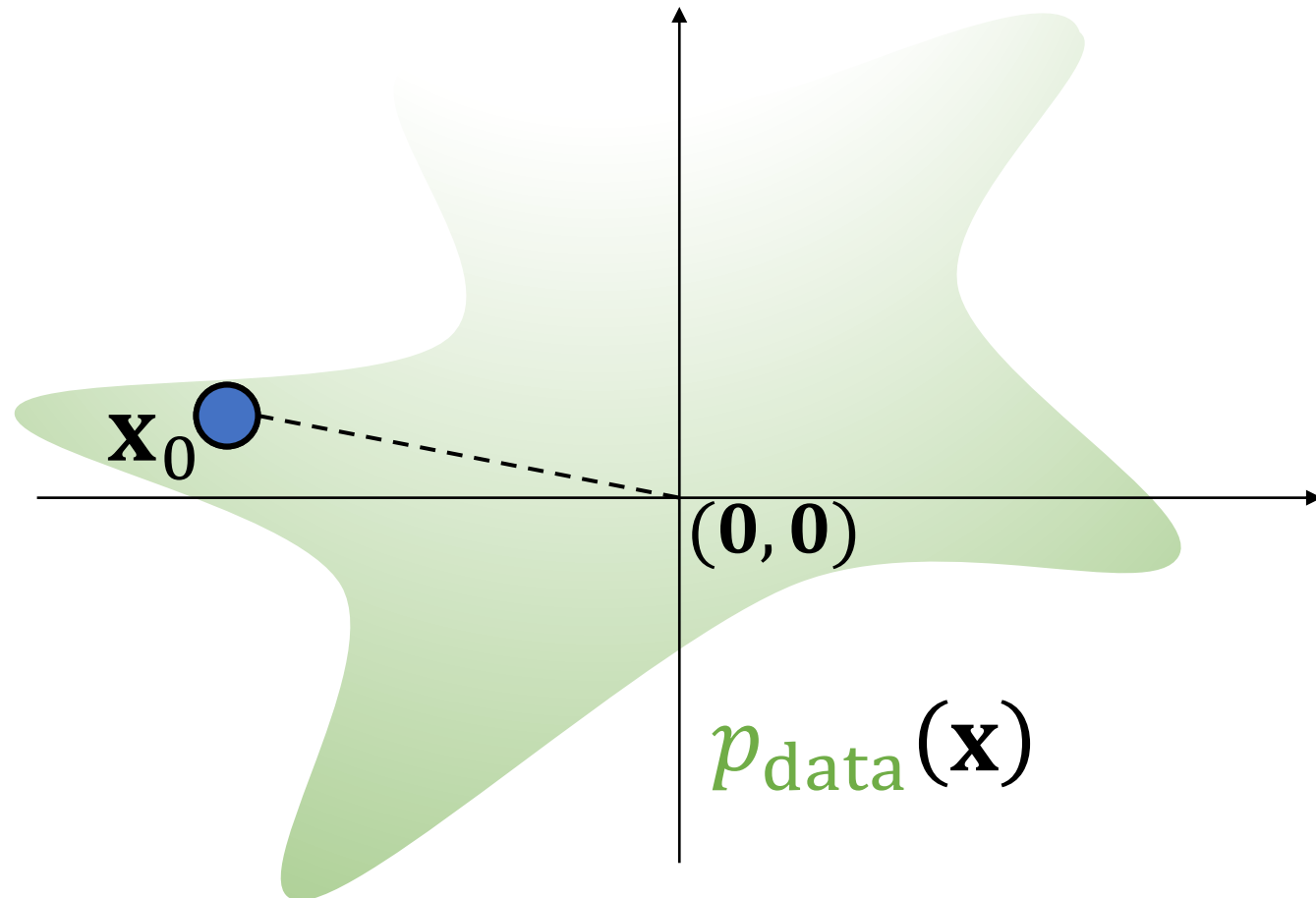


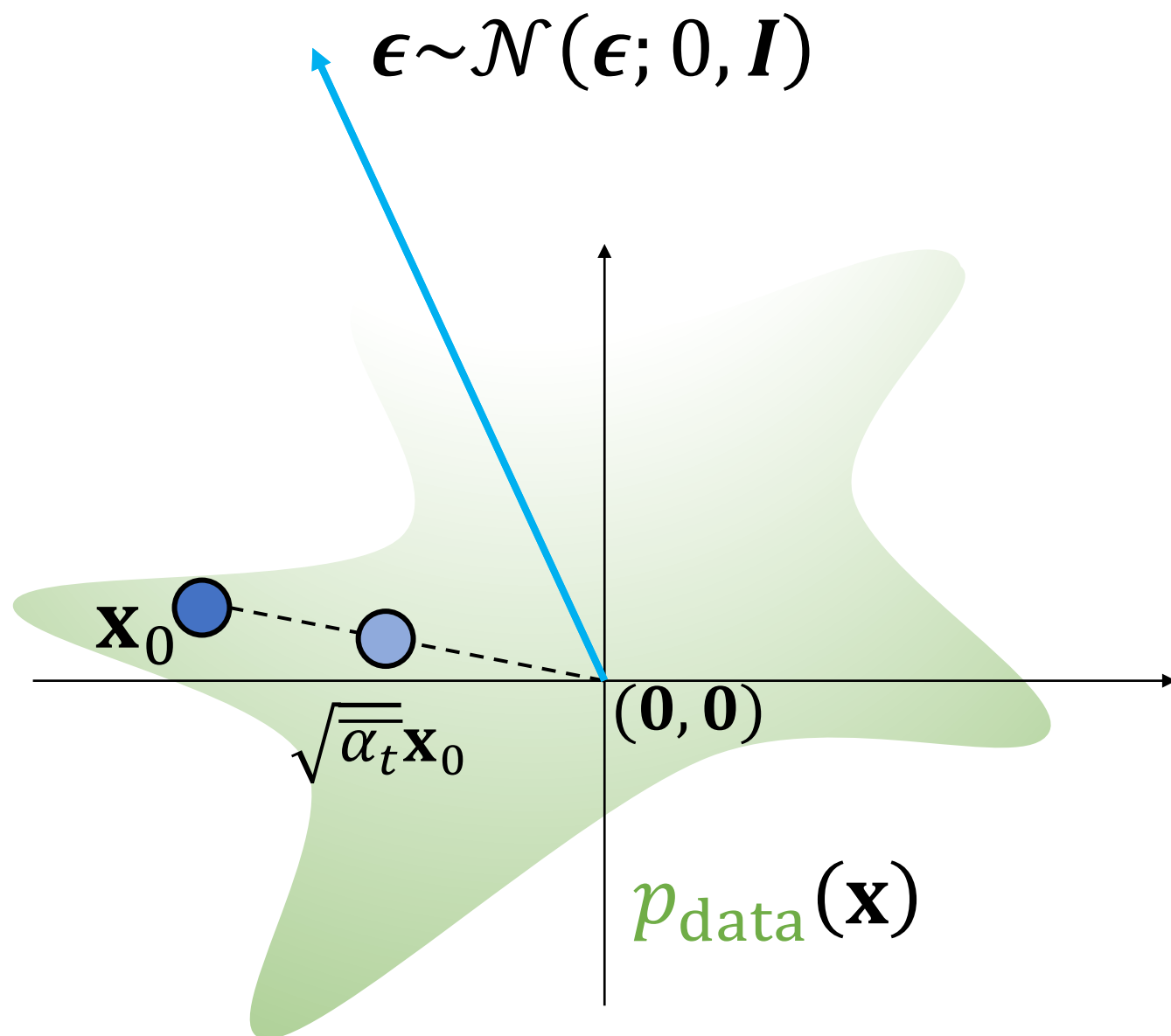
$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} [w(t) [|| \hat{\epsilon}_{\theta}(\mathbf{x}_t, t) - \epsilon ||_2^2]]$$

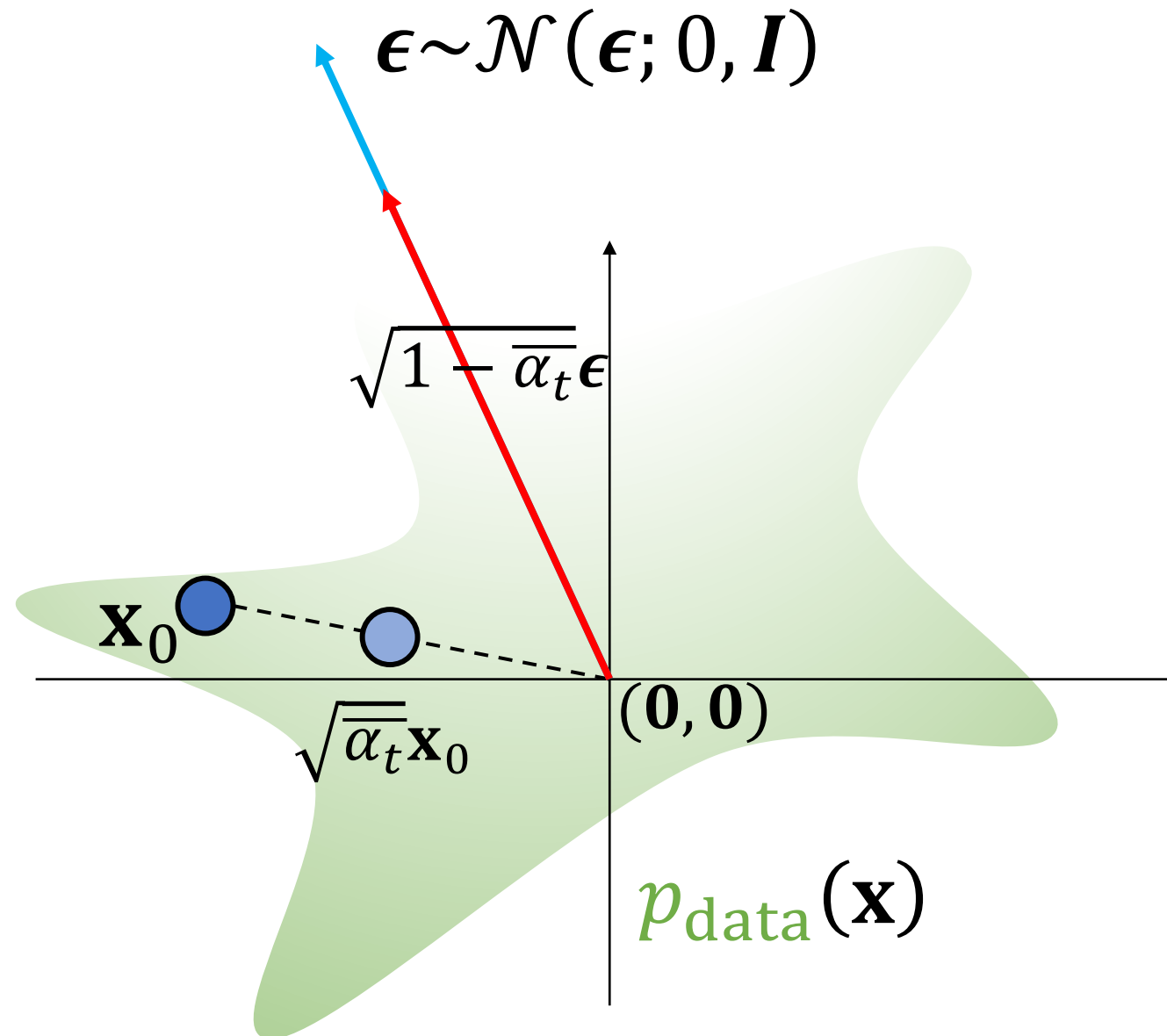
$$\mu_q(\mathbf{x}_t, \mathbf{x}_0) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{(1 - \bar{\alpha}_t)\alpha_t}} \epsilon$$

$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{(1 - \bar{\alpha}_t)\alpha_t}} \hat{\epsilon}_{\theta}(\mathbf{x}_t, t)$$



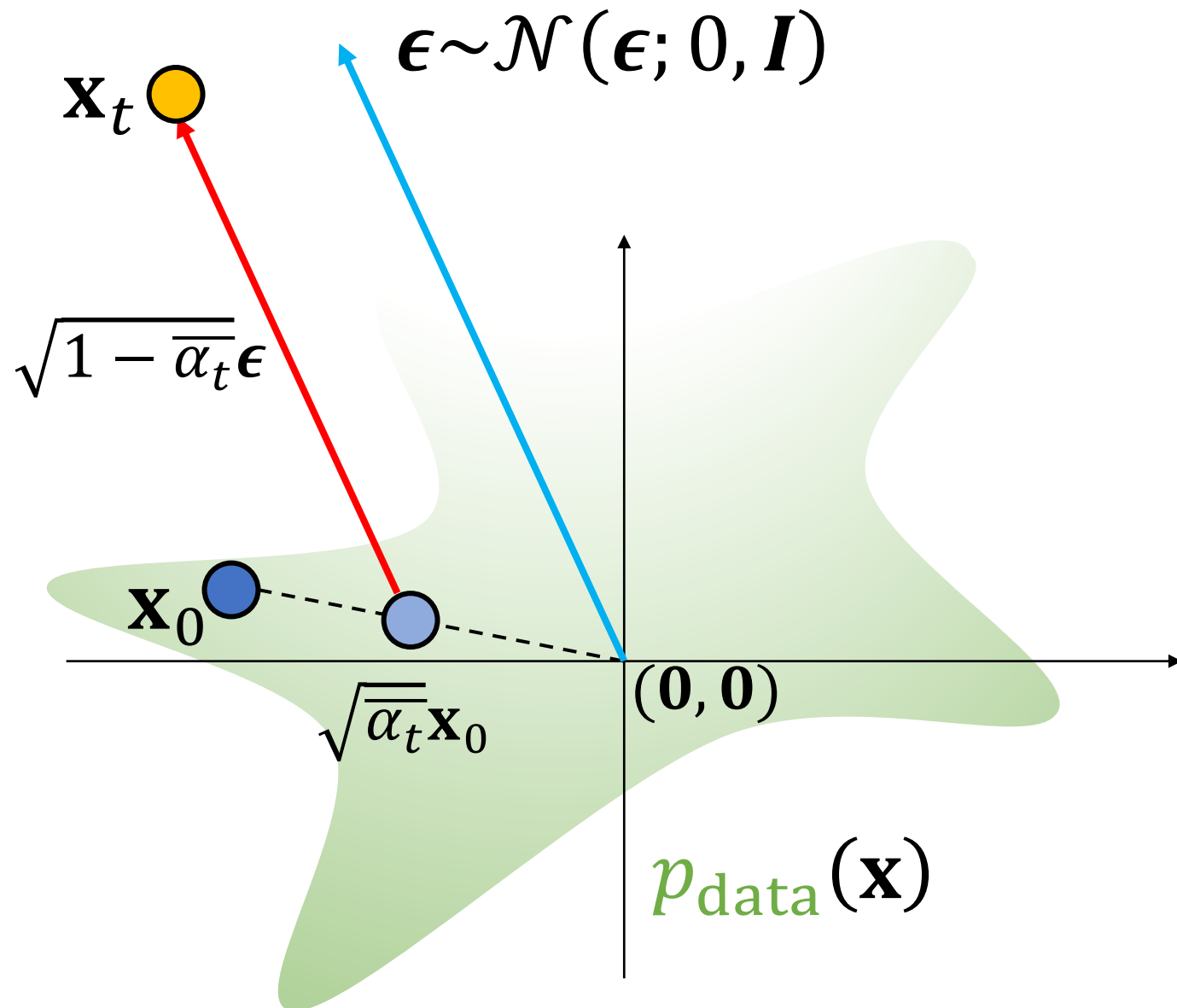




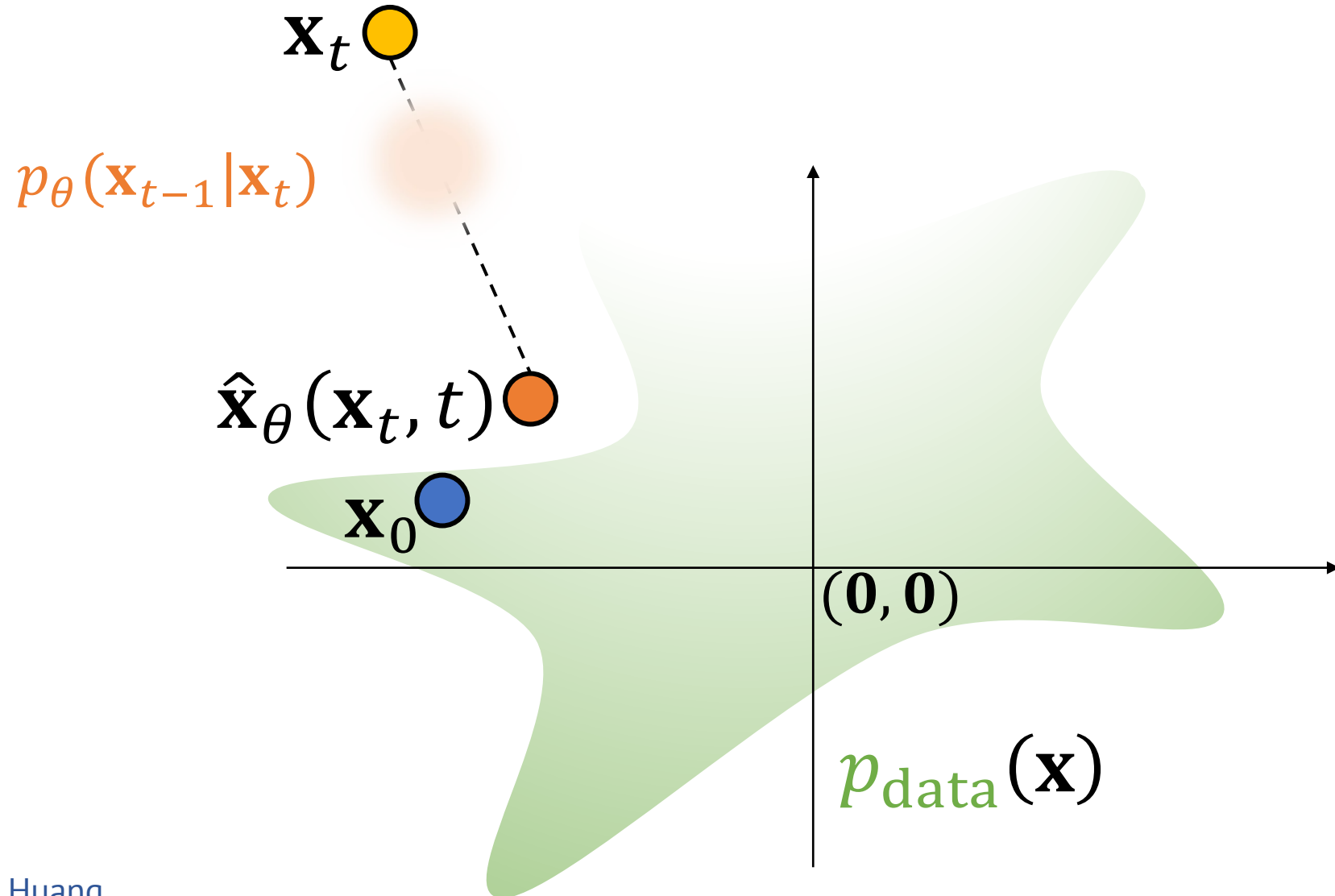




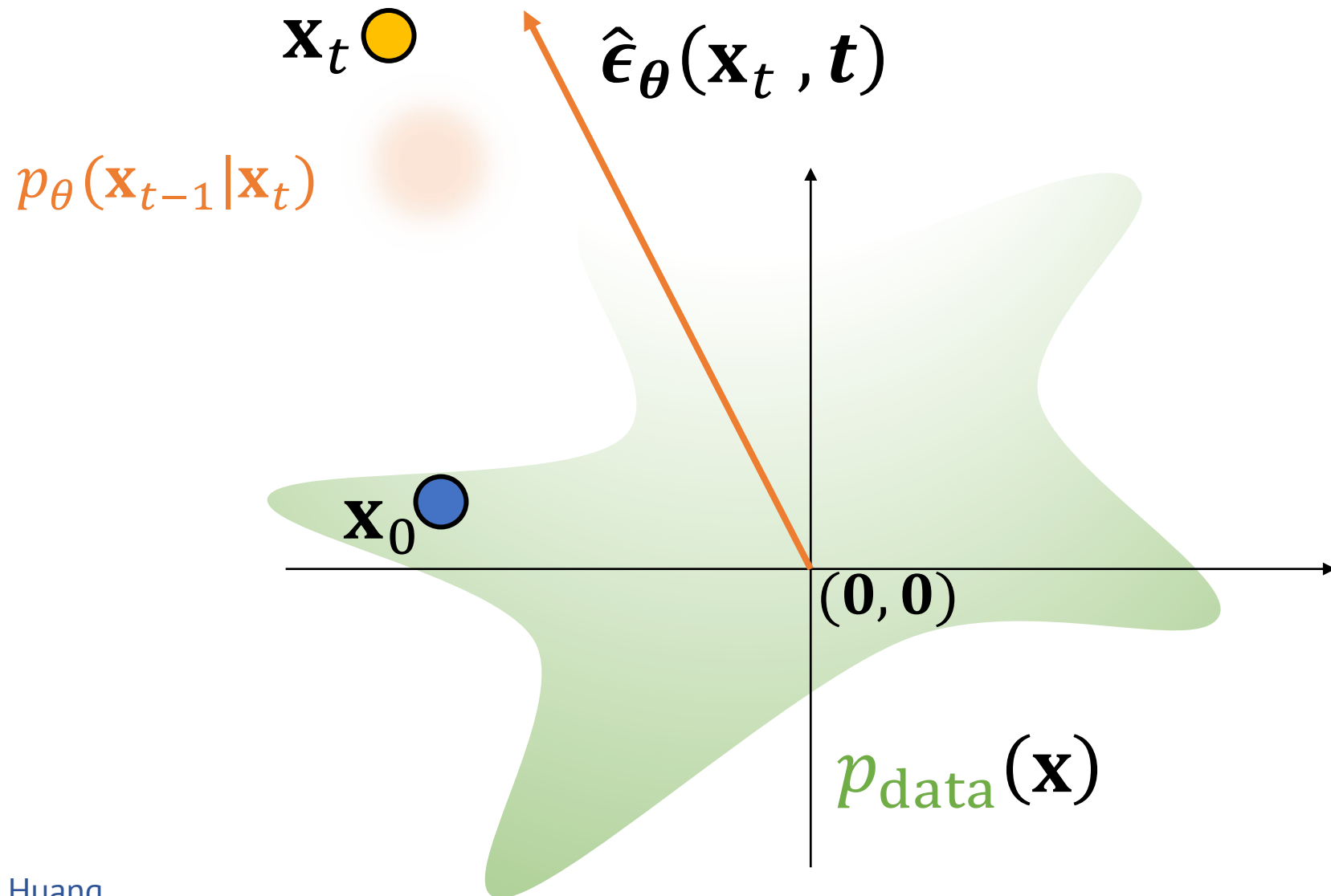
$$\mathbf{x}_t = \sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t} \boldsymbol{\epsilon}$$



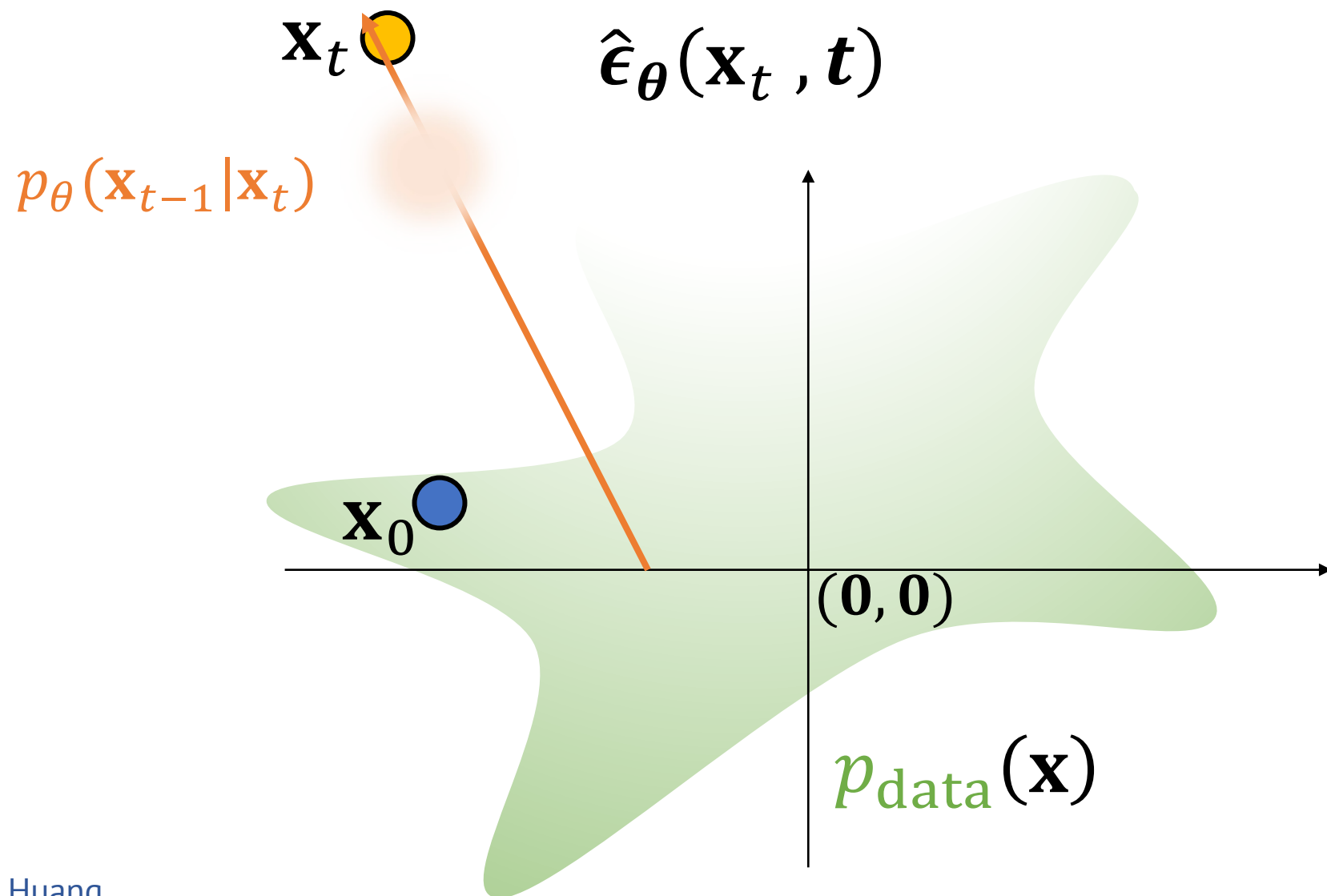
$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{\sqrt{\alpha_t}(1 - \bar{\alpha}_{t-1})}{1 - \bar{\alpha}_t} \mathbf{x}_t + \frac{\sqrt{\bar{\alpha}_{t-1}}(1 - \alpha_t)}{1 - \bar{\alpha}_t} \hat{\mathbf{x}}_{\theta}(\mathbf{x}_t, t)$$



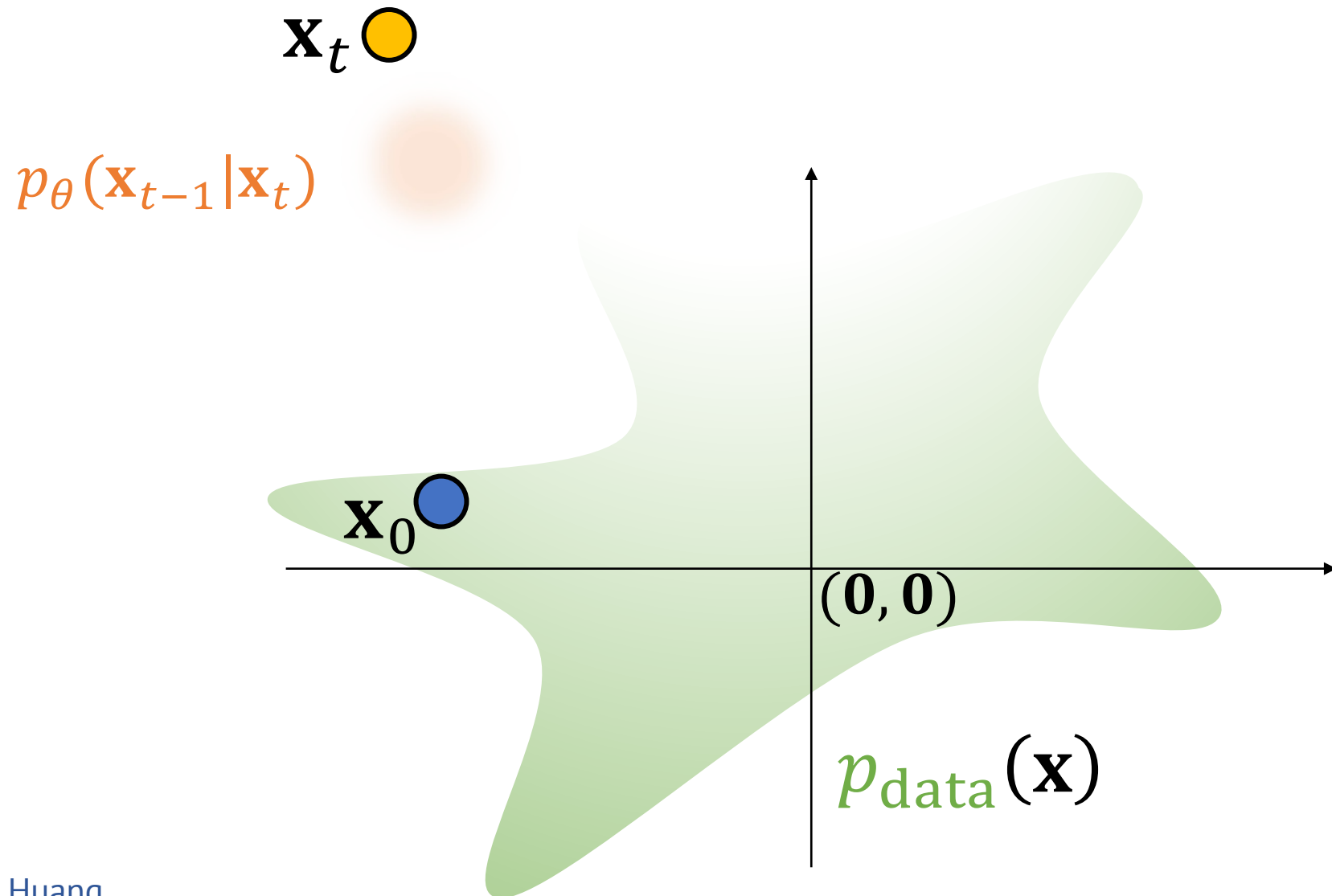
$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{(1 - \bar{\alpha}_t) \alpha_t}} \hat{\epsilon}_{\theta}(\mathbf{x}_t, t)$$



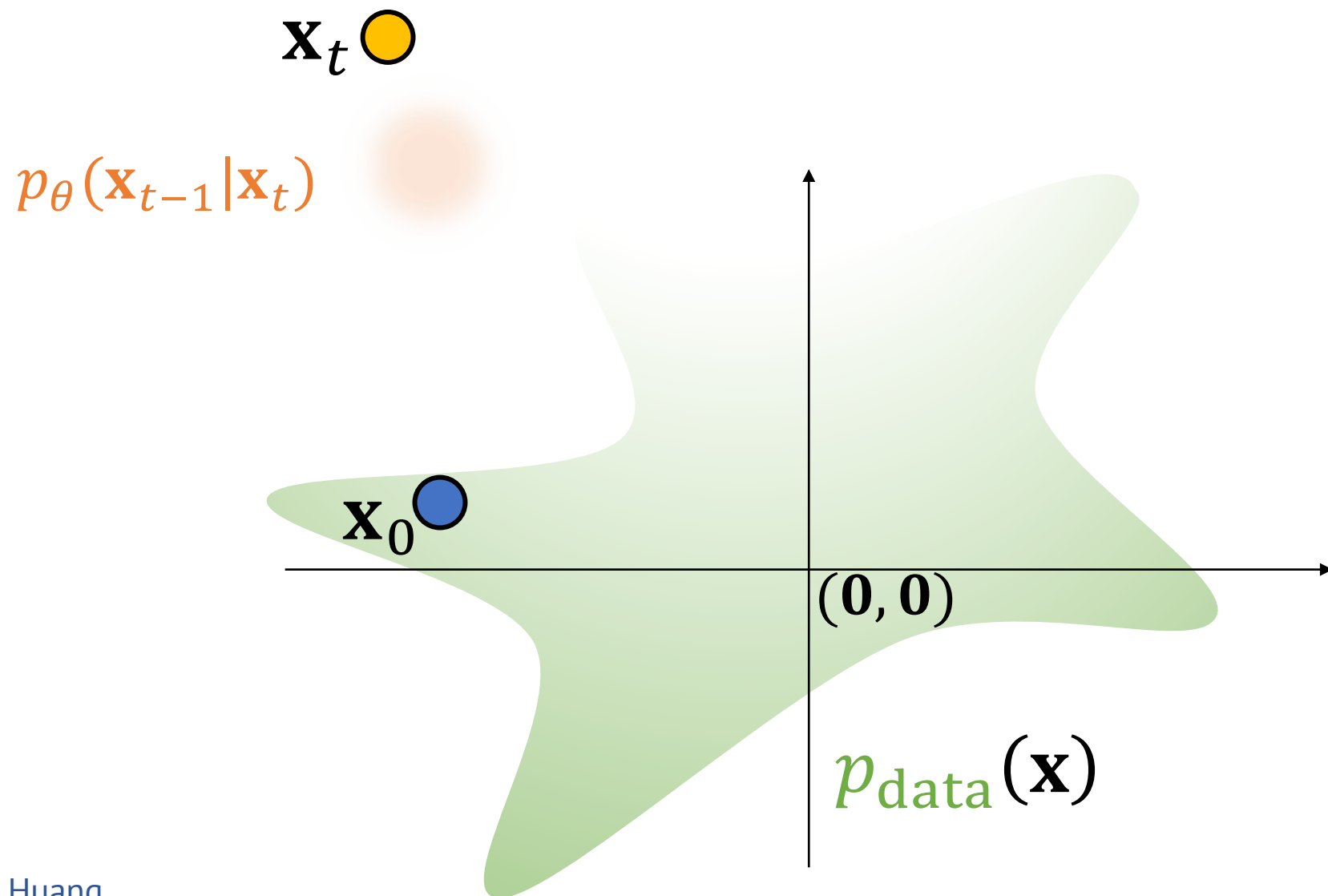
$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{(1 - \bar{\alpha}_t)\alpha_t}} \hat{\epsilon}_{\theta}(\mathbf{x}_t, t)$$



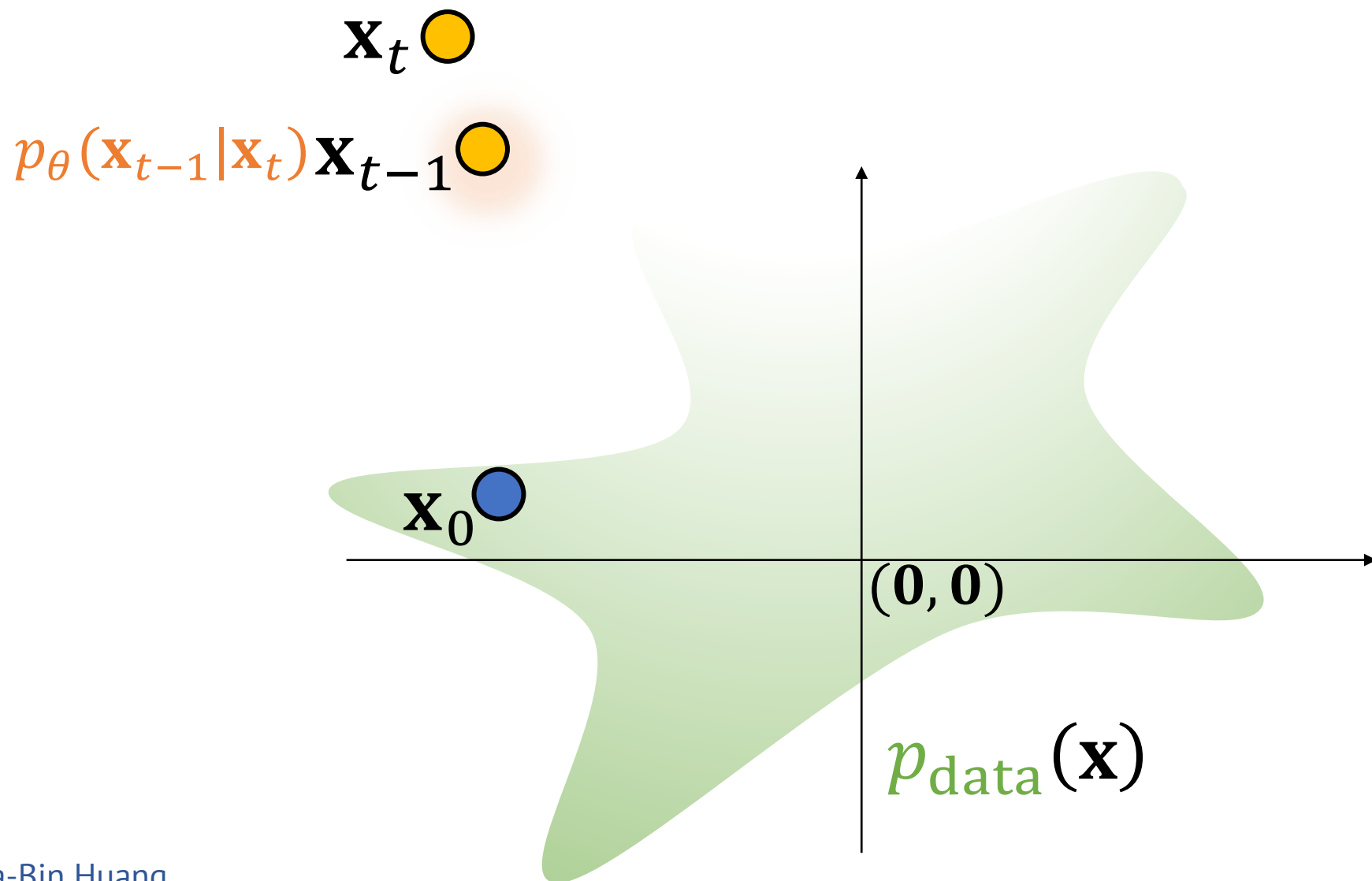
$$\mu_{\theta}(\mathbf{x}_t, t) =$$



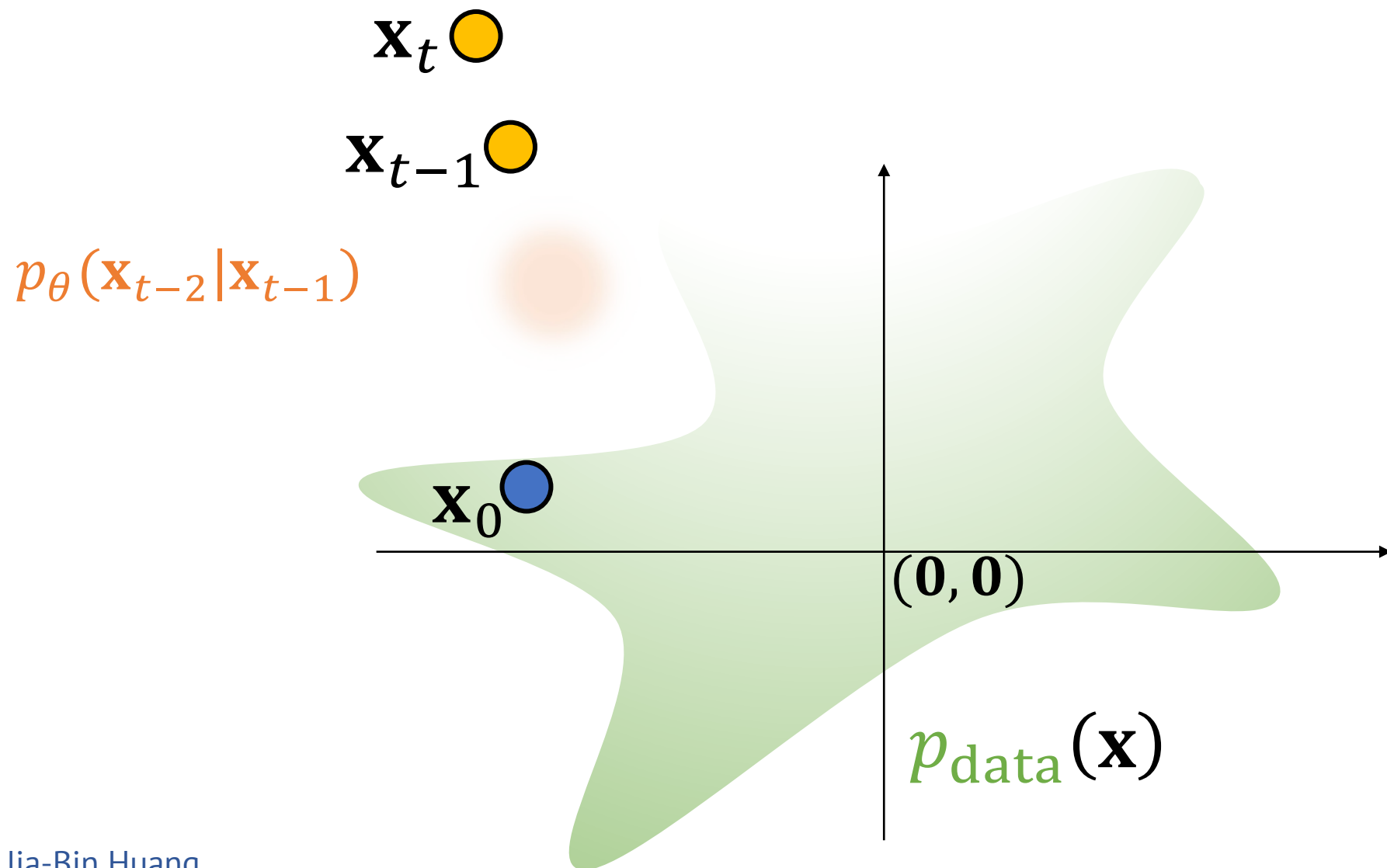
$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t + \frac{1 - \alpha_t}{\sqrt{\alpha_t}} \mathbf{s}_{\theta}(\mathbf{x}_t, t)$$



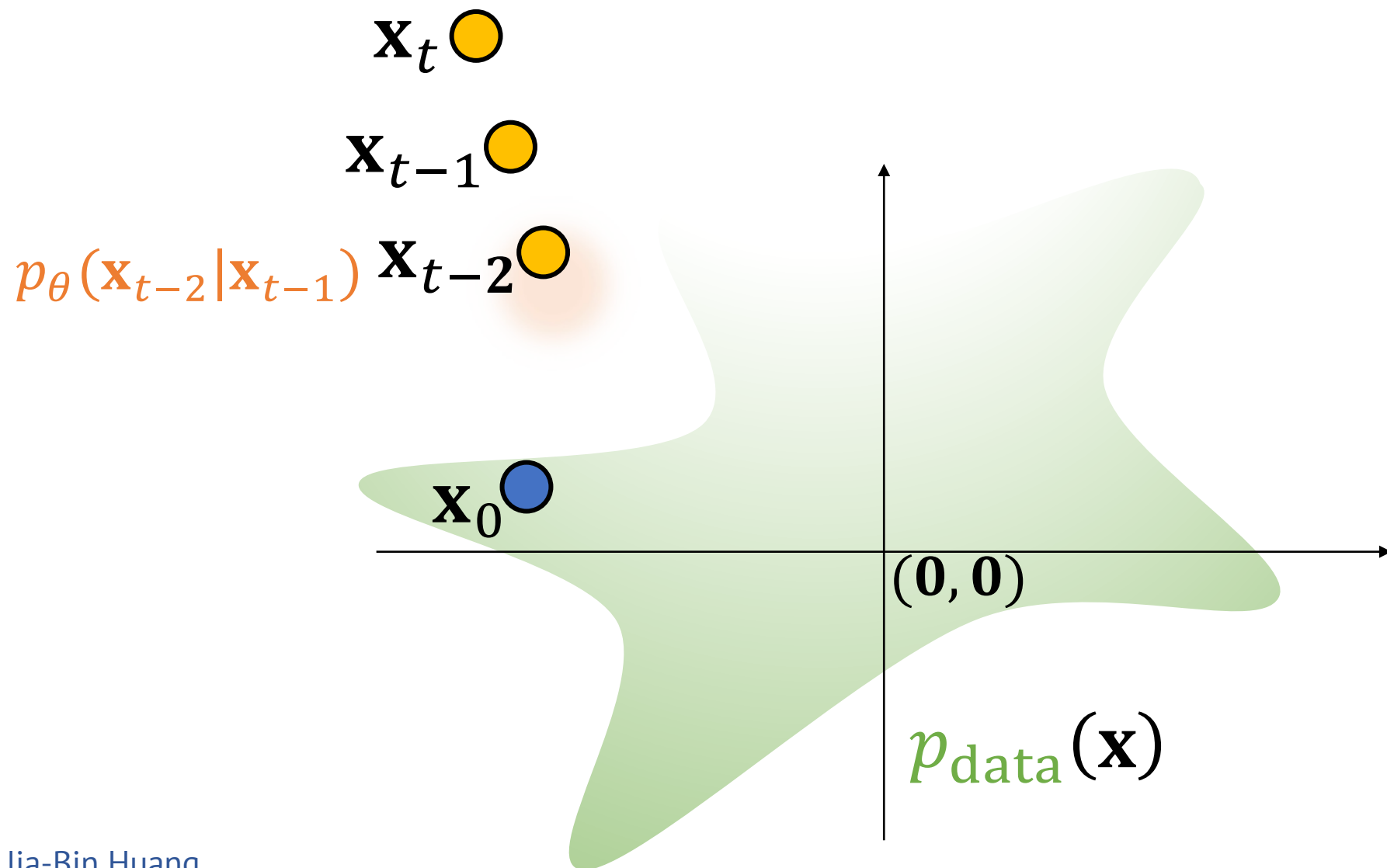
$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t + \frac{1 - \alpha_t}{\sqrt{\alpha_t}} \mathbf{s}_{\theta}(\mathbf{x}_t, t)$$



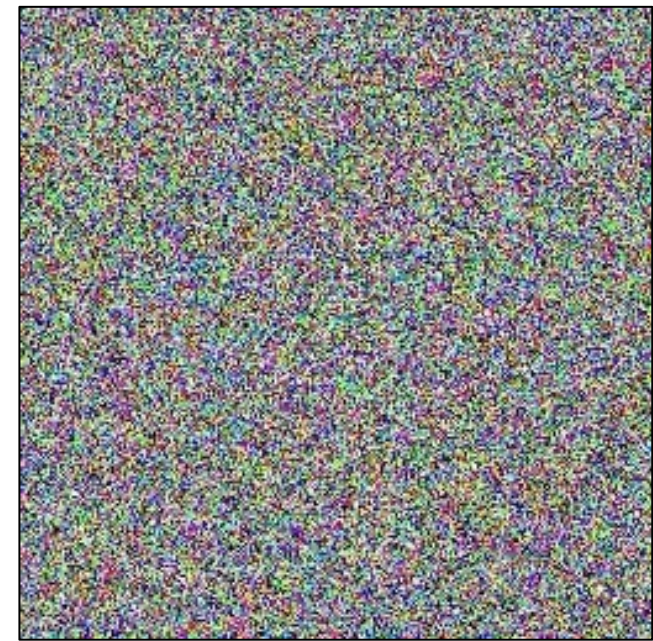
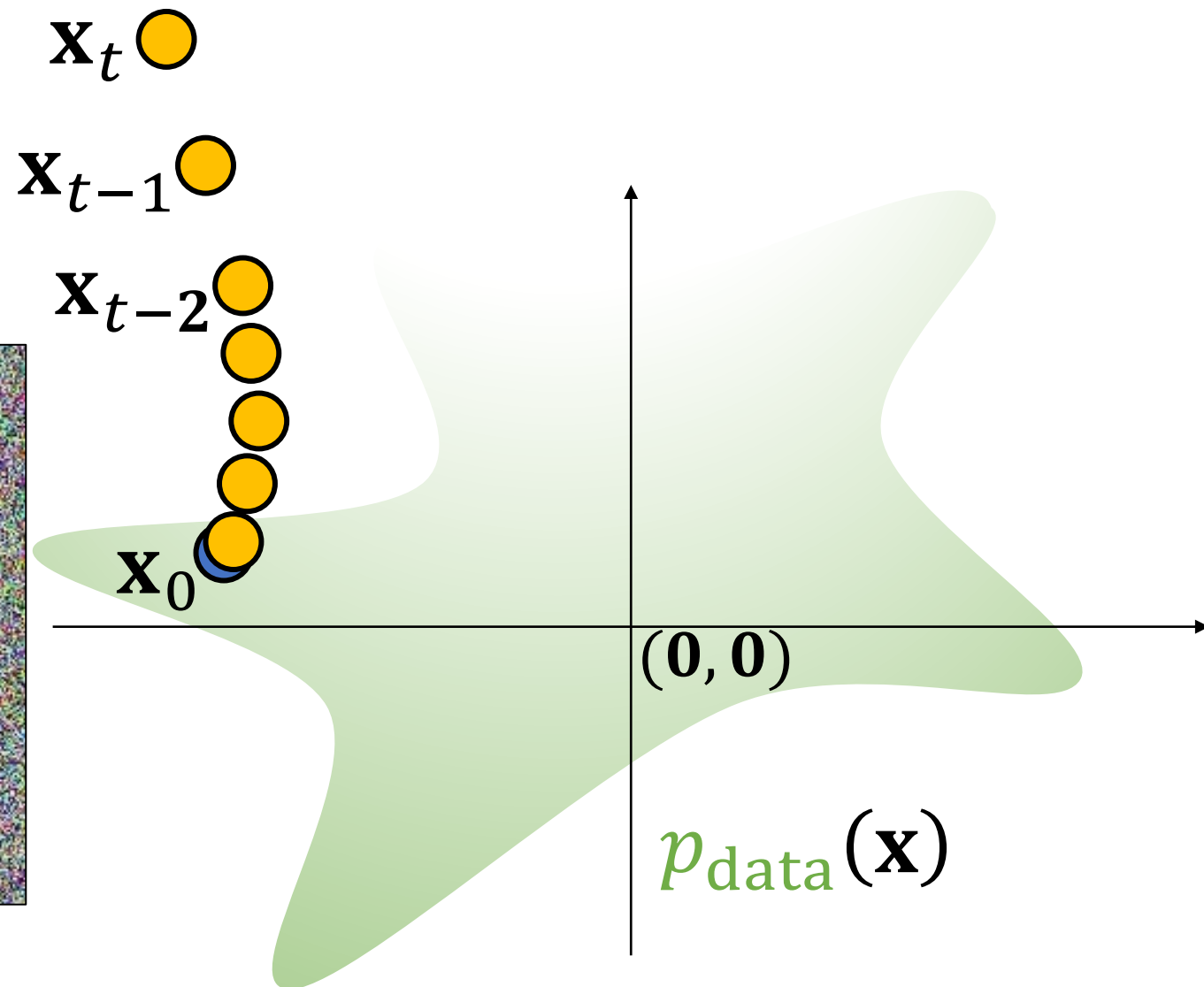
$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t + \frac{1 - \alpha_t}{\sqrt{\alpha_t}} \mathbf{s}_{\theta}(\mathbf{x}_t, t)$$



$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t + \frac{1 - \alpha_t}{\sqrt{\alpha_t}} \mathbf{s}_{\theta}(\mathbf{x}_t, t)$$



$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t + \frac{1 - \alpha_t}{\sqrt{\alpha_t}} \mathbf{s}_{\theta}(\mathbf{x}_t, t)$$





Denoising diffusion probabilistic models (DDPMs)

Denoising Diffusion Probabilistic Models

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Abstract

We present high quality image synthesis results using diffusion probabilistic models, a class of latent variable models inspired by considerations from nonequilibrium thermodynamics. Our best results are obtained by training on a weighted variational bound designed according to a novel connection between diffusion probabilistic models and denoising score matching with Langevin dynamics, and our models naturally admit a progressive lossy decompression scheme that can be interpreted as a generalization of autoregressive decoding. On the unconditional CIFAR10 dataset, we obtain an Inception score of 9.46 and a state-of-the-art FID score of 3.17. On 256x256 LSUN, we obtain sample quality similar to ProgressiveGAN. Our implementation is available at <https://github.com/hojonathanho/diffusion>.

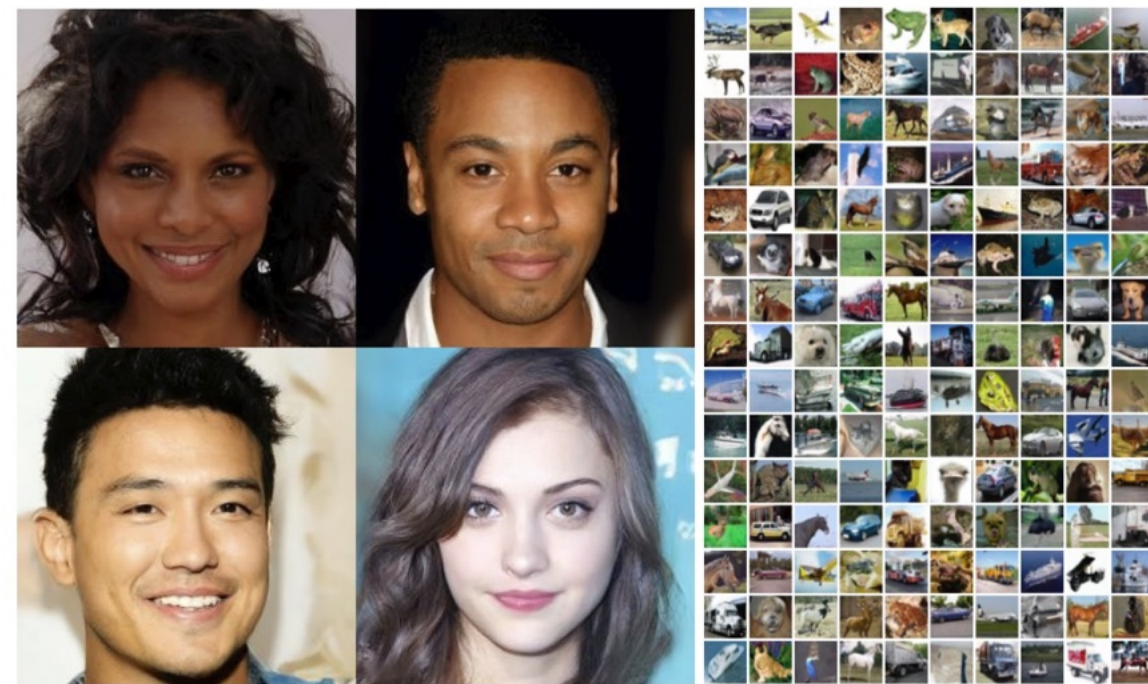
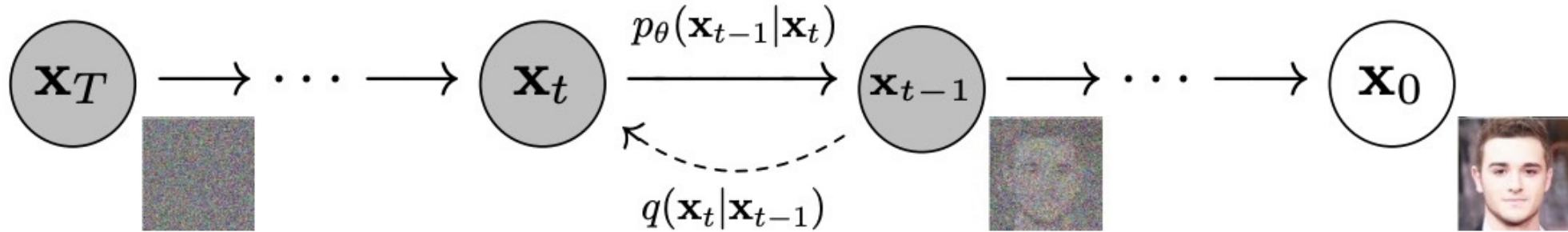


Figure 1: Generated samples on CelebA-HQ 256×256 (left) and unconditional CIFAR10 (right)

DDPMs: Basic idea



Unconditional CIFAR10 sample generation

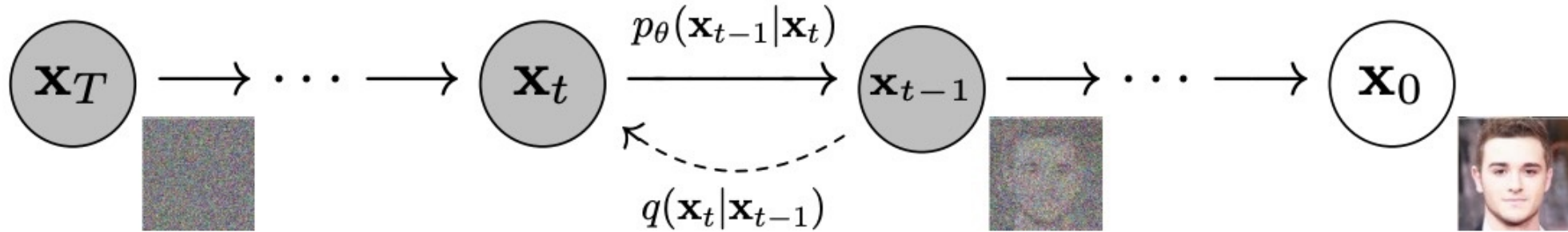


J. Ho et al. [Denoising diffusion probabilistic models](#). NeurIPS 2020

Blog introduction: <https://lilianweng.github.io/posts/2021-07-11-diffusion-models/>
[CVPR 2022 tutorial](#)

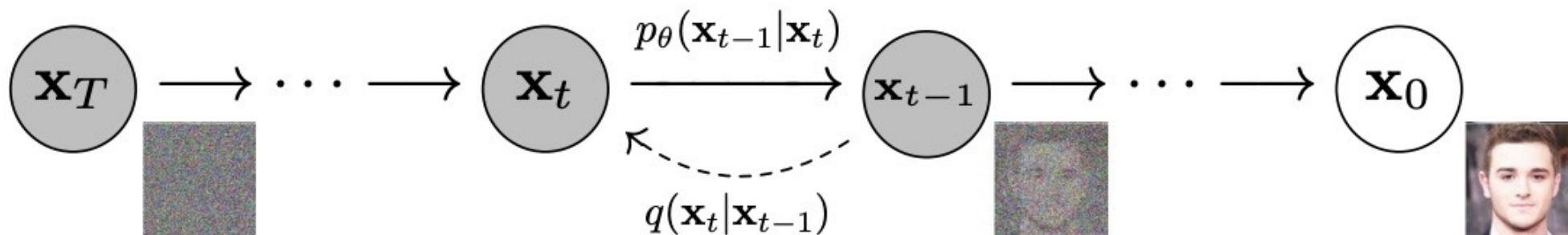


DDPMs: Basic idea



- *Forward process* q turns images into Gaussian noise
- *Reverse process* p turns noise into images
- Provided the increments of t are small enough, $p_\theta(x_{t-1} | x_t)$ is Gaussian and we can train a neural network to estimate the mean of x_{t-1} given x_t

DDPMs: Basic idea



Algorithm 1 Training

1: **repeat**

2: $\mathbf{x}_0 \sim q(\mathbf{x}_0)$

3: $t \sim \text{Uniform}(\{1, \dots, T\})$

4: $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$

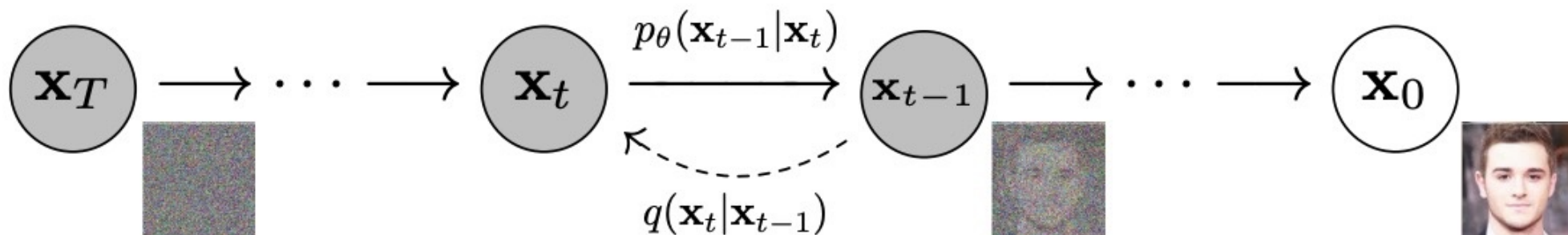
5: Take gradient descent step on

$$\nabla_{\theta} \|\epsilon - \epsilon_{\theta}(\boxed{x_t}, t)\|^2$$

6: **until** converged

- $\epsilon_{\theta}(x_t, t)$ is the predicted noise component of image x_t given noise level t
- Network parameters θ are updated to reduce L2 error between actual noise ϵ and predicted noise $\epsilon_{\theta}(x_t, t)$

DDPMs: Basic idea



Algorithm 1 Training

- 1: **repeat**
- 2: $\mathbf{x}_0 \sim q(\mathbf{x}_0)$
- 3: $t \sim \text{Uniform}(\{1, \dots, T\})$
- 4: $\epsilon \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- 5: Take gradient descent step on

$$\nabla_\theta \left\| \epsilon - \epsilon_\theta(\sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t} \epsilon, t) \right\|^2$$
- 6: **until** converged

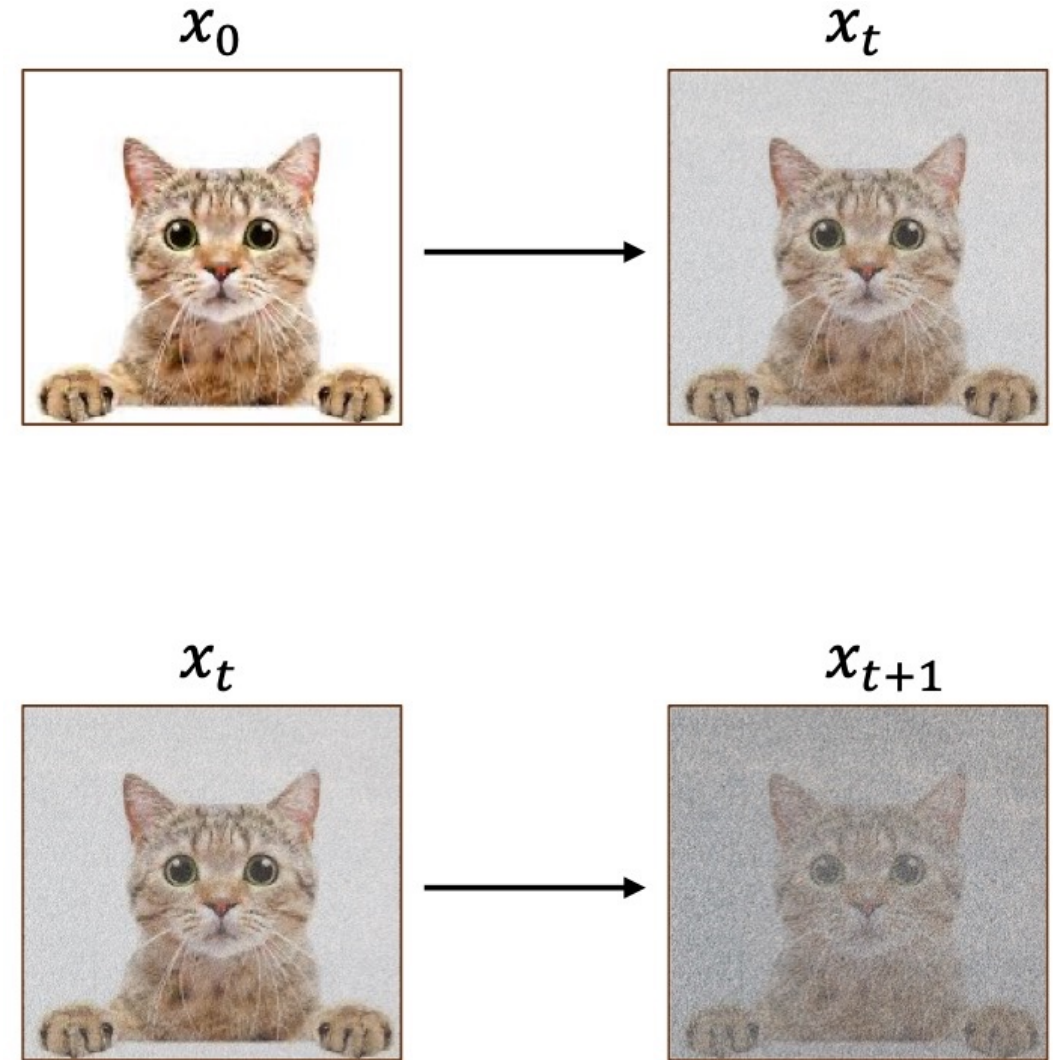
Algorithm 2 Sampling

- 1: $\mathbf{x}_T \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- 2: **for** $t = T, \dots, 1$ **do**
- 3: $\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$ if $t > 1$, else $\mathbf{z} = \mathbf{0}$
- 4: $\mathbf{x}_{t-1} = \frac{1}{\sqrt{\alpha_t}} \left(\mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{1 - \bar{\alpha}_t}} \epsilon_\theta(\mathbf{x}_t, t) \right) + \sigma_t \mathbf{z}$
- 5: **end for**
- 6: **return** $\mathbf{x}_0$



How do we do this in practice?

- Step 1: Sample image from the dataset, generate noisy image using forward process
- Step 2: Given noisy image, generate slightly noisier image





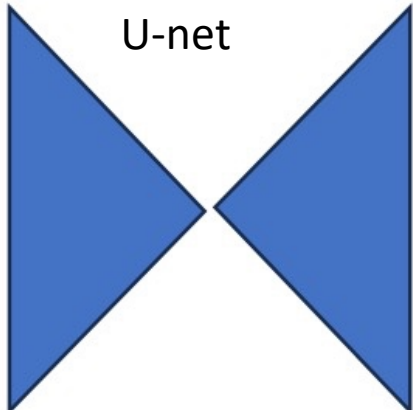
How do we do this in practice?

During Training

x_{t+1}



U-net



$\hat{x}_t$



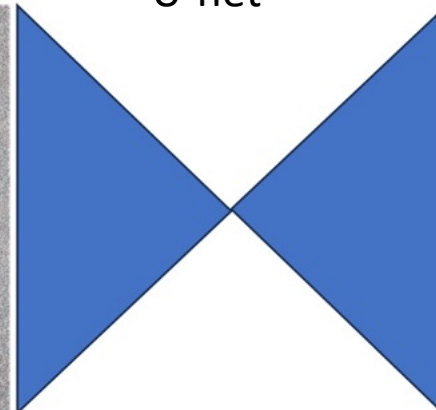
Loss: $\text{MSE}(x_t, \hat{x}_t)$

During Inference

Input



U-net



Output



U-net predicts the noise



Class-conditioned DDPMs

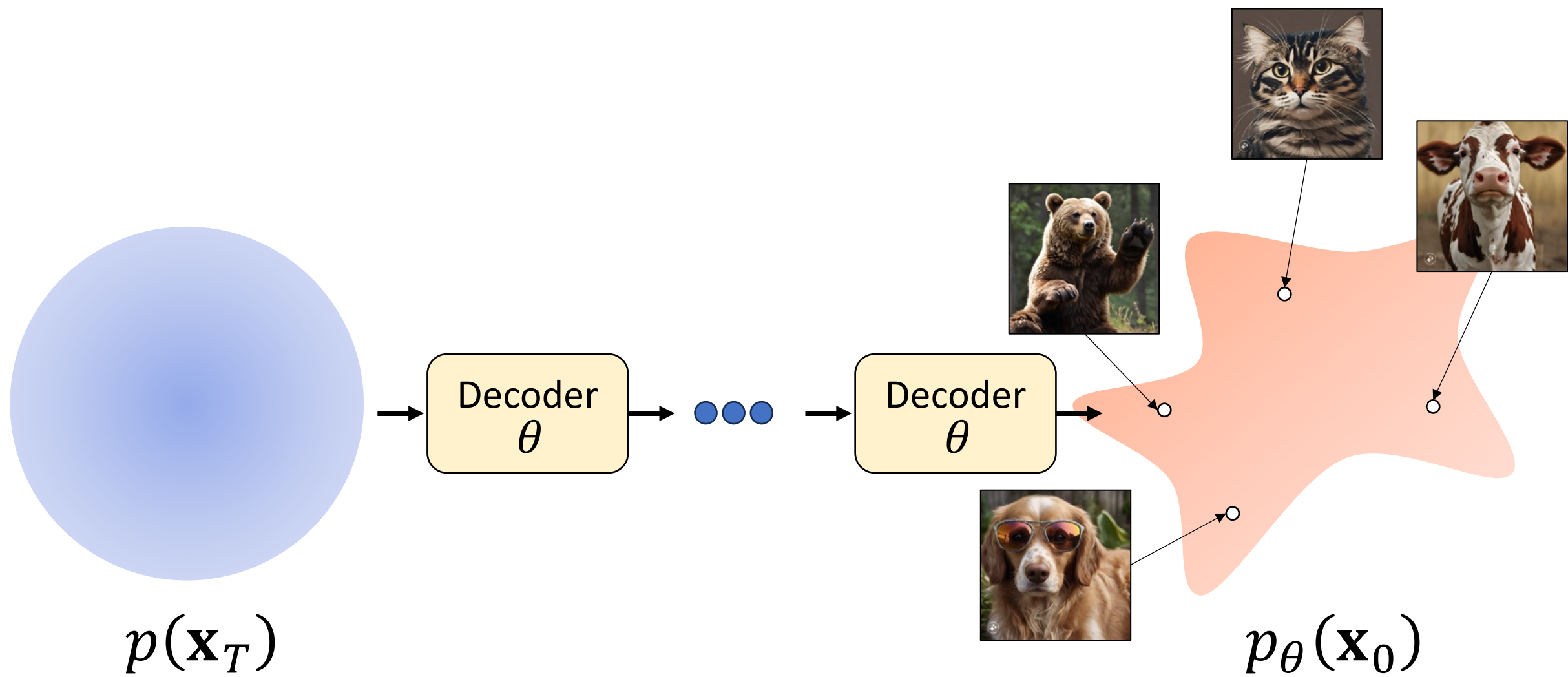
- “We can sample with as few as 25 forward passes while maintaining FIDs comparable to BigGAN”

Abstract



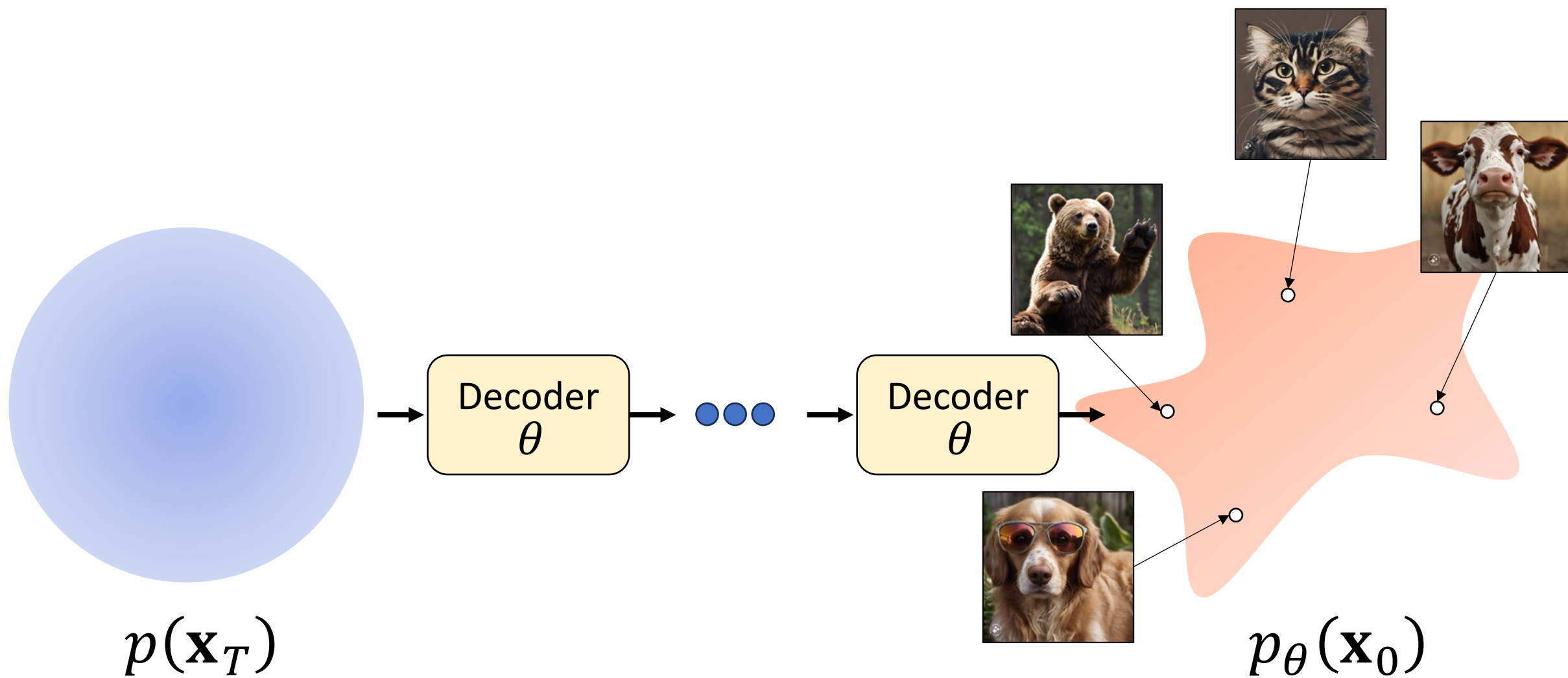
Figure 1: Selected samples from our best ImageNet 512×512 model (FID 3.85)

We show that diffusion models can achieve image sample quality superior to the current state-of-the-art generative models. We achieve this on unconditional image synthesis by finding a better architecture through a series of ablations. For conditional image synthesis, we further improve sample quality with classifier guidance: a simple, compute-efficient method for trading off diversity for fidelity using gradients from a classifier. We achieve an FID of 2.97 on ImageNet 128×128 , 4.59 on ImageNet 256×256 , and 7.72 on ImageNet 512×512 , and we match BigGAN-deep even with as few as 25 forward passes per sample, all while maintaining better coverage of the distribution. Finally, we find that classifier guidance combines well with upsampling diffusion models, further improving FID to 3.94 on ImageNet 256×256 and 3.85 on ImageNet 512×512 . We release our code at <https://github.com/openai/guided-diffusion>.



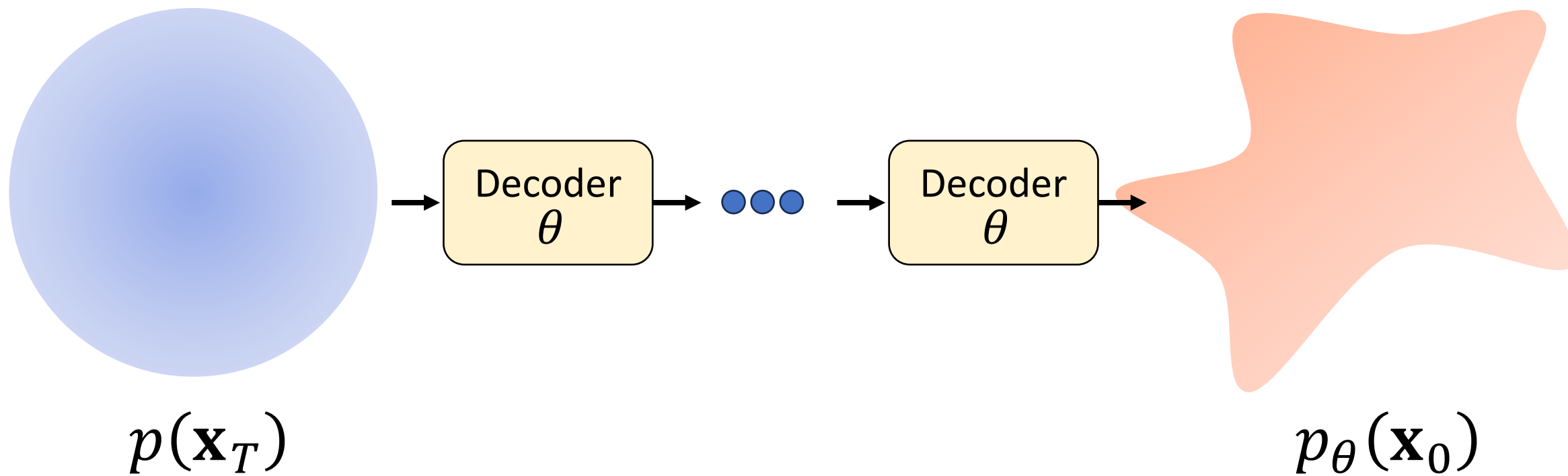


Unconditional generation



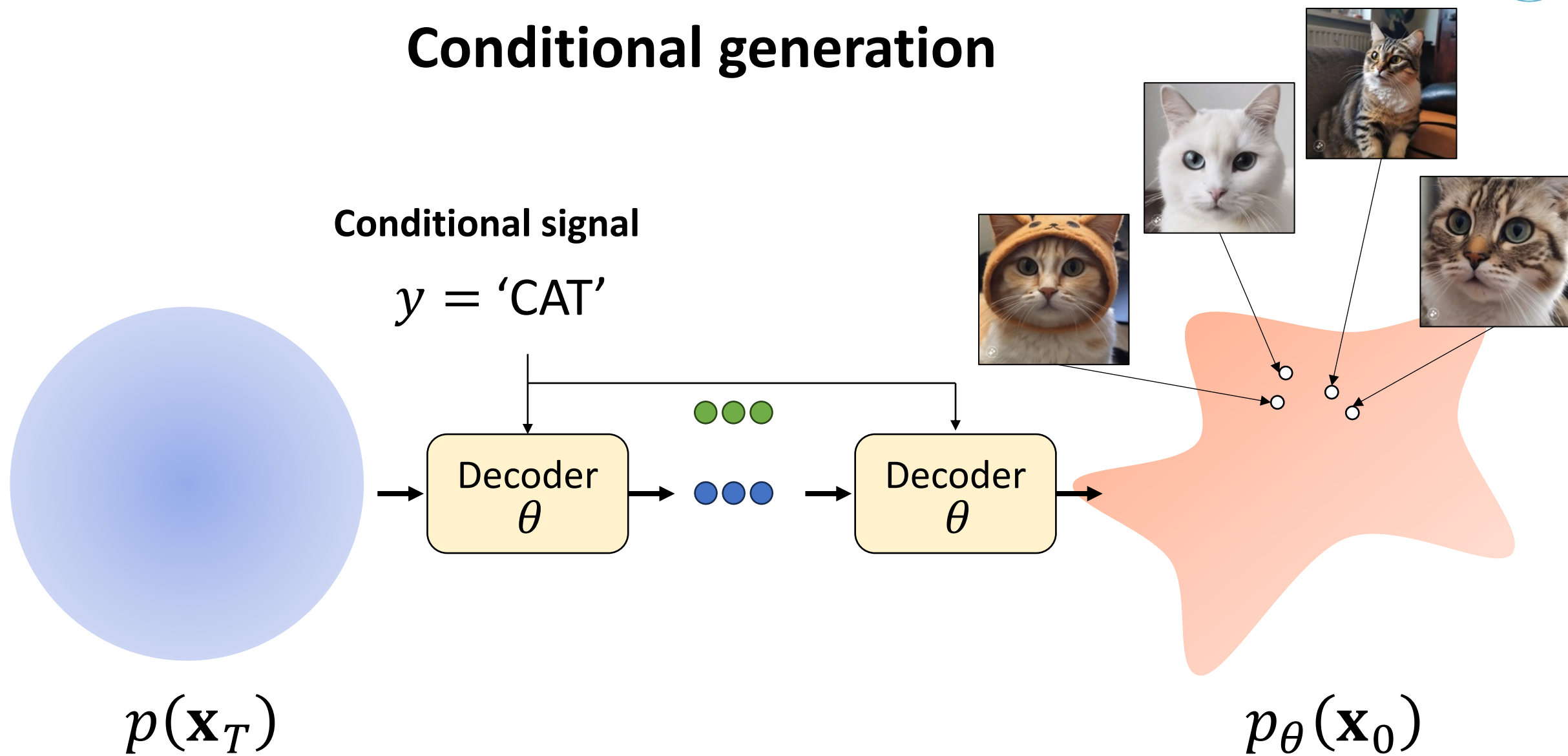


Conditional generation





Conditional generation

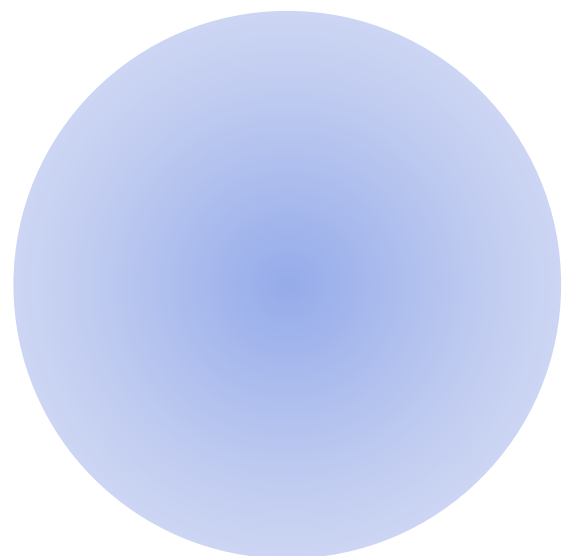




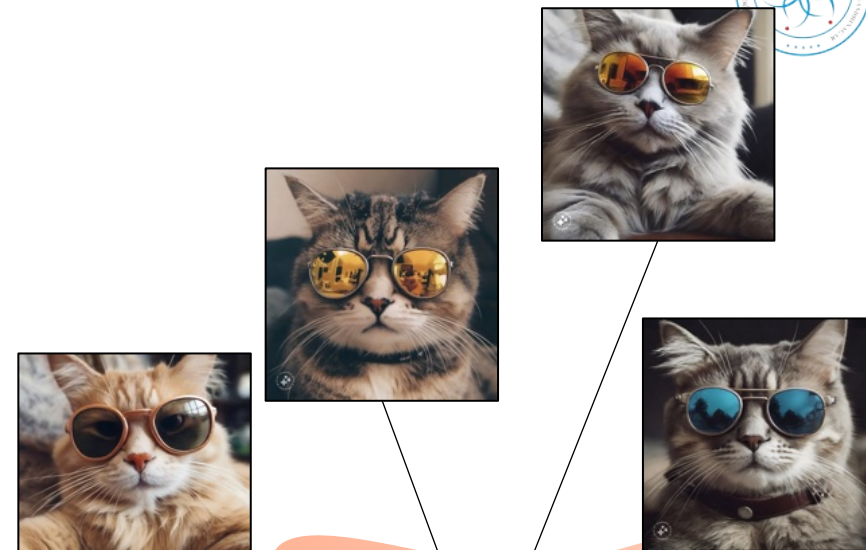
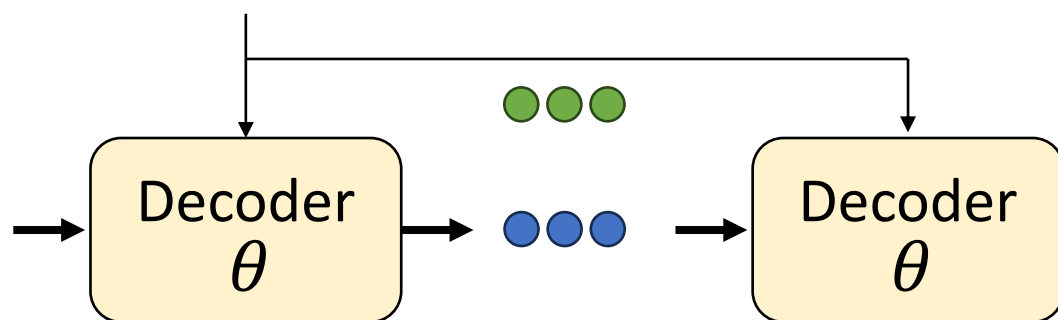
Conditional generation

Conditional signal

$y = \text{"A cat wearing sunglasses"}$



$p(\mathbf{x}_T)$



$p_{\theta}(\mathbf{x}_0)$

Unconditional generation



$\mathbf{x}_t$

$p_\theta(\mathbf{x}_{t-1}|\mathbf{x}_t)$

$$\mathbf{s}_\theta(\mathbf{x}_t, t) \approx \nabla \log p(\mathbf{x}_t)$$

Unconditional score

$$\mu_\theta(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t + \frac{1 - \alpha_t}{\sqrt{\alpha_t}} \mathbf{s}_\theta(\mathbf{x}_t, t)$$

$p_{\text{data}}(\mathbf{x})$

Conditional generation



$\mathbf{x}_t$



$$s_{\theta}(\mathbf{x}_t, t, \mathbf{y}) \approx \nabla \log p(\mathbf{x}_t | \mathbf{y})$$

Conditional score



$p_{\text{data}}(\mathbf{x})$

Conditional generation



$\mathbf{x}_t$

$$s_{\theta}(\mathbf{x}_t, t, \mathbf{y}) \approx \nabla \log p(\mathbf{x}_t | \mathbf{y})$$

Conditional score

$p_{\text{data}}(\mathbf{x})$

Conditional generation



$\mathbf{x}_t$

$$s_{\theta}(\mathbf{x}_t, t, \mathbf{y}) \approx \nabla \log p(\mathbf{x}_t | \mathbf{y})$$

Conditional score

$$\nabla \log p(\mathbf{x}_t | \mathbf{y}) = \nabla \log \left(\frac{p(\mathbf{x}_t) p(\mathbf{y} | \mathbf{x}_t)}{p(\mathbf{y})} \right)$$

Conditional score

$p_{\text{data}}(\mathbf{x})$

Conditional generation



$\mathbf{x}_t$

$$s_{\theta}(\mathbf{x}_t, t, \mathbf{y}) \approx \nabla \log p(\mathbf{x}_t | \mathbf{y})$$

Conditional score

$$\begin{aligned} \nabla \log p(\mathbf{x}_t | \mathbf{y}) &= \nabla \log p(\mathbf{x}_t) + \nabla \log p(\mathbf{y} | \mathbf{x}_t) \\ &\quad - \nabla \log p(\mathbf{y}) \end{aligned}$$

Conditional score

$p_{\text{data}}(\mathbf{x})$

Conditional generation



Classifier Guidance

$\mathbf{x}_t$

$$s_{\theta}(\mathbf{x}_t, t, \mathbf{y}) \approx \nabla \log p(\mathbf{x}_t | \mathbf{y})$$

Conditional score

$$\nabla \log p(\mathbf{x}_t | \mathbf{y}) = \nabla \log p(\mathbf{x}_t) + \nabla \log p(\mathbf{y} | \mathbf{x}_t)$$

Conditional score

Unconditional score

Adversarial gradient

$p_{\text{data}}(\mathbf{x})$

Conditional generation



Classifier Guidance

$\mathbf{x}_t$

$$s_{\theta}(\mathbf{x}_t, t, \mathbf{y}) \approx \nabla \log p(\mathbf{x}_t | \mathbf{y})$$

Conditional score

$$\nabla \log p_{\gamma}(\mathbf{x}_t | \mathbf{y}) = \nabla \log p(\mathbf{x}_t) + \gamma \nabla \log p(\mathbf{y} | \mathbf{x}_t)$$

Conditional score

Unconditional score

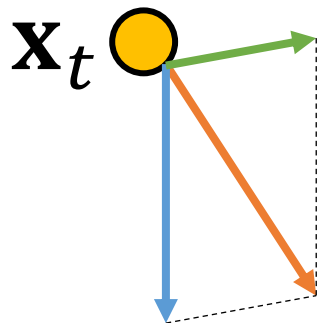
Adversarial gradient

$p_{\text{data}}(\mathbf{x})$

Conditional generation



Classifier Guidance



$$s_{\theta}(\mathbf{x}_t, t, \mathbf{y}) \approx \nabla \log p(\mathbf{x}_t | \mathbf{y})$$

Conditional score

$$\nabla \log p_{\gamma}(\mathbf{x}_t | \mathbf{y}) = \nabla \log p(\mathbf{x}_t) + \gamma \nabla \log p(\mathbf{y} | \mathbf{x}_t)$$

Conditional score

Unconditional score

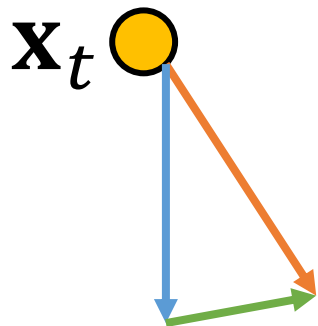
Adversarial gradient

$p_{\text{data}}(\mathbf{x})$

Conditional generation



Classifier Guidance



$$s_{\theta}(\mathbf{x}_t, t, \mathbf{y}) \approx \nabla \log p(\mathbf{x}_t | \mathbf{y})$$

Conditional score

$$\nabla \log p_{\gamma}(\mathbf{x}_t | \mathbf{y}) = \nabla \log p(\mathbf{x}_t) + \gamma \nabla \log p(\mathbf{y} | \mathbf{x}_t)$$

Conditional score

Unconditional score

Adversarial gradient

$p_{\text{data}}(\mathbf{x})$

Conditional generation



Classifier Guidance



Classifier guidance scale = 1



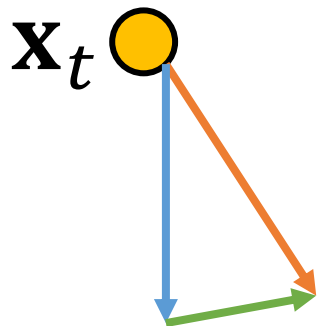
Classifier guidance scale = 10

$p_{\text{data}}(\mathbf{x})$
 $y = \text{"Pembroke Welsh corgi"}$

Conditional generation



Classifier Guidance



$$s_{\theta}(\mathbf{x}_t, t, \mathbf{y}) \approx \nabla \log p(\mathbf{x}_t | \mathbf{y})$$

Conditional score

$$\nabla \log p_{\gamma}(\mathbf{x}_t | \mathbf{y}) = \nabla \log p(\mathbf{x}_t) + \gamma \nabla \log p(\mathbf{y} | \mathbf{x}_t)$$

Conditional score

Unconditional score

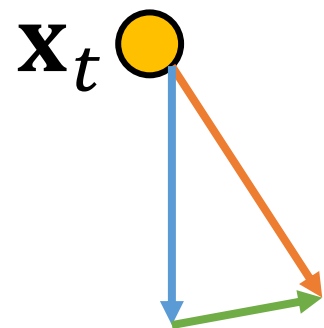
Adversarial gradient

$p_{\text{data}}(\mathbf{x})$

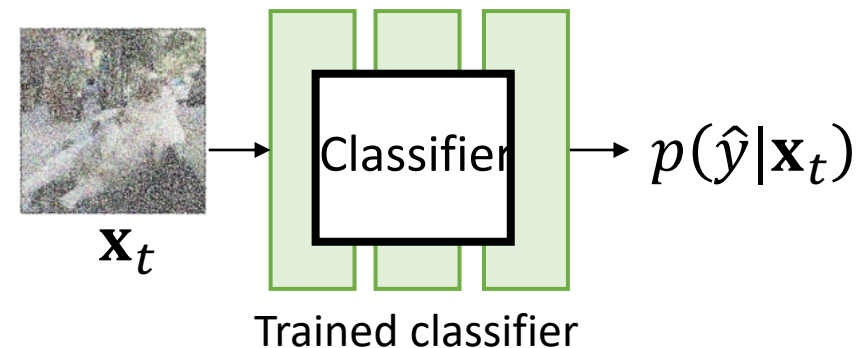
Conditional generation



Classifier Guidance



$$\underbrace{\nabla \log p_{\gamma}(\mathbf{x}_t | \mathbf{y})}_{\text{Conditional score}} = \underbrace{\nabla \log p(\mathbf{x}_t)}_{\text{Unconditional score}} + \underbrace{\gamma \nabla \log p(\mathbf{y} | \mathbf{x}_t)}_{\text{Adversarial gradient}}$$

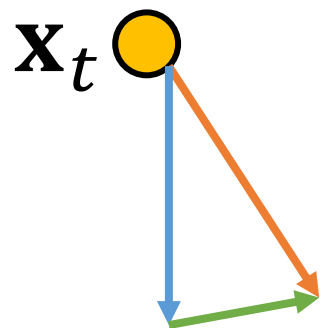


$p_{\text{data}}(\mathbf{x})$

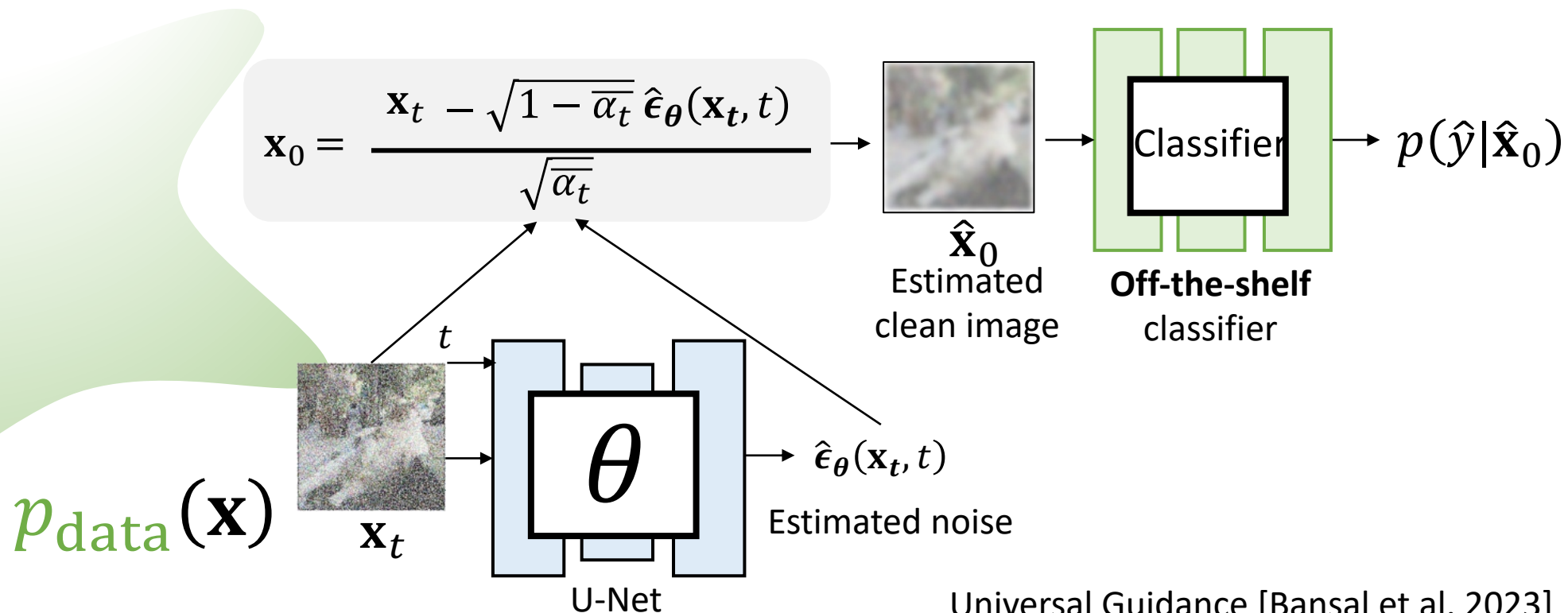
Conditional generation



Classifier Guidance



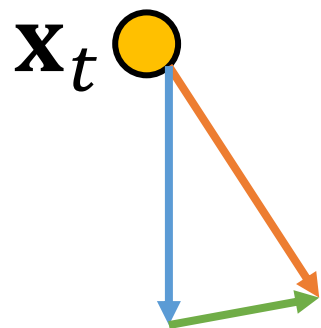
$$\underbrace{\nabla \log p_\gamma(\mathbf{x}_t | \mathbf{y})}_{\text{Conditional score}} = \underbrace{\nabla \log p(\mathbf{x}_t)}_{\text{Unconditional score}} + \underbrace{\gamma \nabla \log p(\mathbf{y} | \hat{\mathbf{x}}_0)}_{\text{Adversarial gradient}}$$



Conditional generation



Classifier Guidance



$$\underbrace{\nabla \log p_{\gamma}(\mathbf{x}_t | \mathbf{y})}_{\text{Conditional score}} = \underbrace{\nabla \log p(\mathbf{x}_t)}_{\text{Unconditional score}} + \underbrace{\gamma \nabla \log p(\mathbf{y} | \mathbf{x}_t)}_{\text{Adversarial gradient}}$$

$p_{\text{data}}(\mathbf{x})$

Conditional generation



$\mathbf{x}_t$ ●

$$\nabla \log p_\gamma(\mathbf{x}_t|\textcolor{red}{y}) = \nabla \log p(\mathbf{x}_t) + \gamma \nabla \log p(\textcolor{red}{y}|\mathbf{x}_t)$$

Conditional score

Unconditional score

Adversarial gradient

$$\nabla \log p(\textcolor{red}{y}|\mathbf{x}_t) = \nabla \log \left(\frac{p(\mathbf{x}_t|\textcolor{red}{y}) p(\textcolor{red}{y})}{p(\mathbf{x}_t)} \right)$$

$p_{\text{data}}(\mathbf{x})$

Conditional generation



$\mathbf{x}_t$ ●

$$\nabla \log p_{\gamma}(\mathbf{x}_t | \mathbf{y}) = \nabla \log p(\mathbf{x}_t) + \gamma \nabla \log p(\mathbf{y} | \mathbf{x}_t)$$

Conditional score

Unconditional score

Adversarial gradient

$$\begin{aligned} \nabla \log p(\mathbf{y} | \mathbf{x}_t) &= \nabla \log p(\mathbf{x}_t | \mathbf{y}) - \nabla \log p(\mathbf{x}_t) \\ &\quad + \nabla \log p(\mathbf{y}) \end{aligned}$$

$p_{\text{data}}(\mathbf{x})$

Conditional generation



$\mathbf{x}_t$ ●

$$\nabla \log p_{\gamma}(\mathbf{x}_t | \mathbf{y}) = \nabla \log p(\mathbf{x}_t) + \gamma \nabla \log p(\mathbf{y} | \mathbf{x}_t)$$

Conditional score

Unconditional score

Adversarial gradient

$$\nabla \log p(\mathbf{y} | \mathbf{x}_t) = \nabla \log p(\mathbf{x}_t | \mathbf{y}) - \nabla \log p(\mathbf{x}_t)$$

$p_{\text{data}}(\mathbf{x})$

Conditional generation



$\mathbf{x}_t$ ●

$$\nabla \log p_{\gamma}(\mathbf{x}_t | \textcolor{red}{y}) = \nabla \log p(\mathbf{x}_t) + \gamma$$

Conditional score

Unconditional score

Adversarial gradient

$$\nabla \log p(\textcolor{red}{y} | \mathbf{x}_t) = \nabla \log p(\mathbf{x}_t | \textcolor{red}{y}) - \nabla \log p(\mathbf{x}_t)$$

$p_{\text{data}}(\mathbf{x})$

Conditional generation



$\mathbf{x}_t$ ●

$$\nabla \log p_{\gamma}(\mathbf{x}_t | \mathbf{y}) = \nabla \log p(\mathbf{x}_t) + \gamma(\nabla \log p(\mathbf{x}_t | \mathbf{y}) - \nabla \log p(\mathbf{x}_t))$$

Conditional score Unconditional score Adversarial gradient

$p_{\text{data}}(\mathbf{x})$

Conditional generation



Classifier-free Guidance

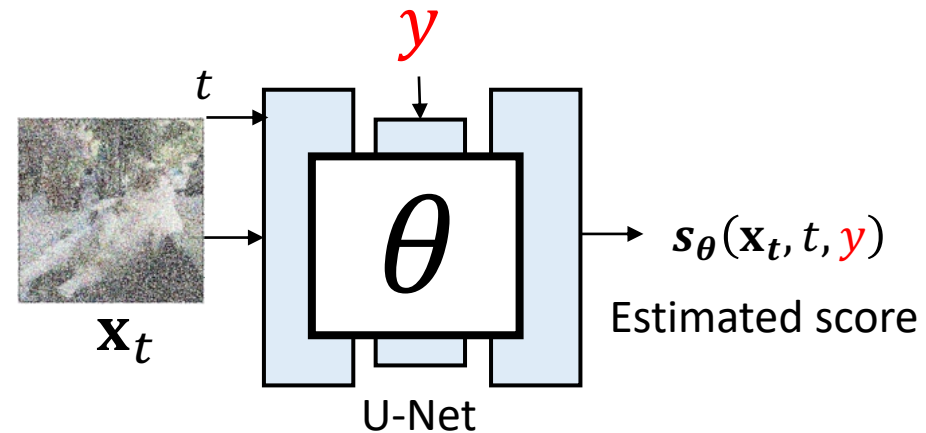
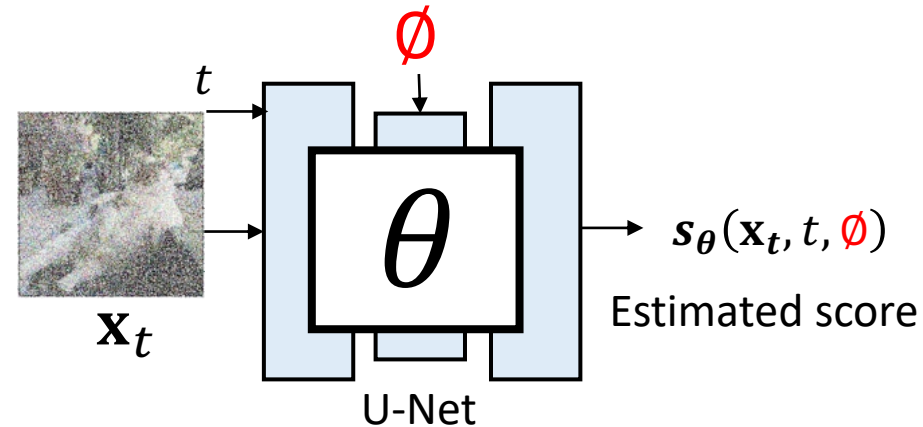
$\mathbf{x}_t$

$$\nabla \log p_\gamma(\mathbf{x}_t | \mathbf{y}) = (1 - \gamma) \nabla \log p(\mathbf{x}_t) + \gamma \nabla \log p(\mathbf{x}_t | \mathbf{y})$$

Conditional score Unconditional score Conditional score



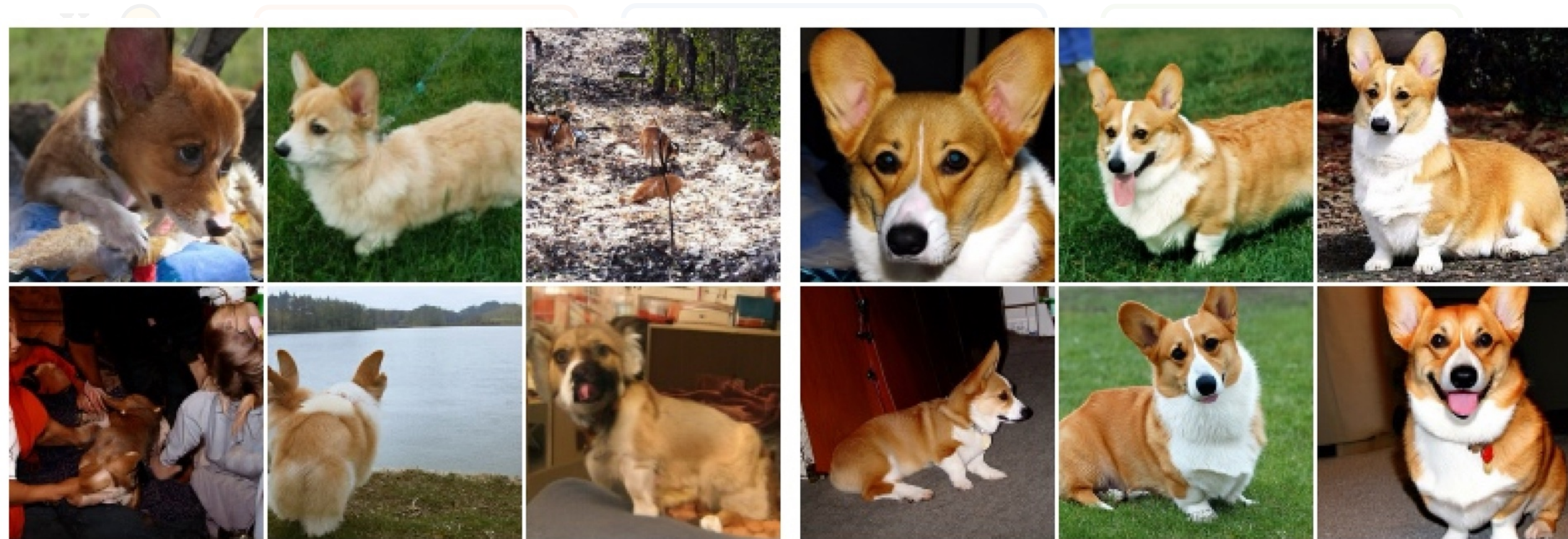
$p_{\text{data}}(\mathbf{x})$



Conditional generation



Classifier-free Guidance



Unguided samples



Guided samples

$s_{\theta}(x_t, t, y)$

Estimated score



Classifier guidance

- We can sample from the class-conditional density $q(x_t|c)$ with the help of a pre-trained classifier $P(c|x_t)$
- Bayes rule:

$$\bullet q(x_t|c) \propto P(c|x_t)q(x_t)$$

$$\bullet \log q(x_t|c) = \log P(c|x_t) + \log q(x_t) + \text{const.}$$

$$\bullet \nabla_{x_t} \log q(x_t|c) = \nabla_{x_t} \log P(c|x_t) + \nabla_{x_t} \log q(x_t)$$

conditional score function obtained from classifier output unconditional score function (pre-trained)

- To sample from class c , steer sample in the modified direction $\nabla_{x_t} [\log q(x_t) + w \log P(c|x_t)]$



Classifier-free guidance

- Instead of training an additional classifier, get an “implicit classifier” by jointly training a conditional and unconditional diffusion model: $P(c|x_t) \propto q(x_t|c)/q(x_t)$
- Both $q(x_t|c)$ and $q(x_t)$ are represented using the same network, trained by dropping out c with some probability (corresponding to the unconditional case)
- The modified score function corresponding to this implicit classifier is
- $$\nabla_{x_t} [\log q(x_t) + w \log P(c|x_t)] = \nabla_{x_t} [\log q(x_t) + w(\log q(x_t|c) - \log q(x_t))]$$

Sample is steered away from the unconditional distribution in the direction of the conditional one

Classifier-free guidance

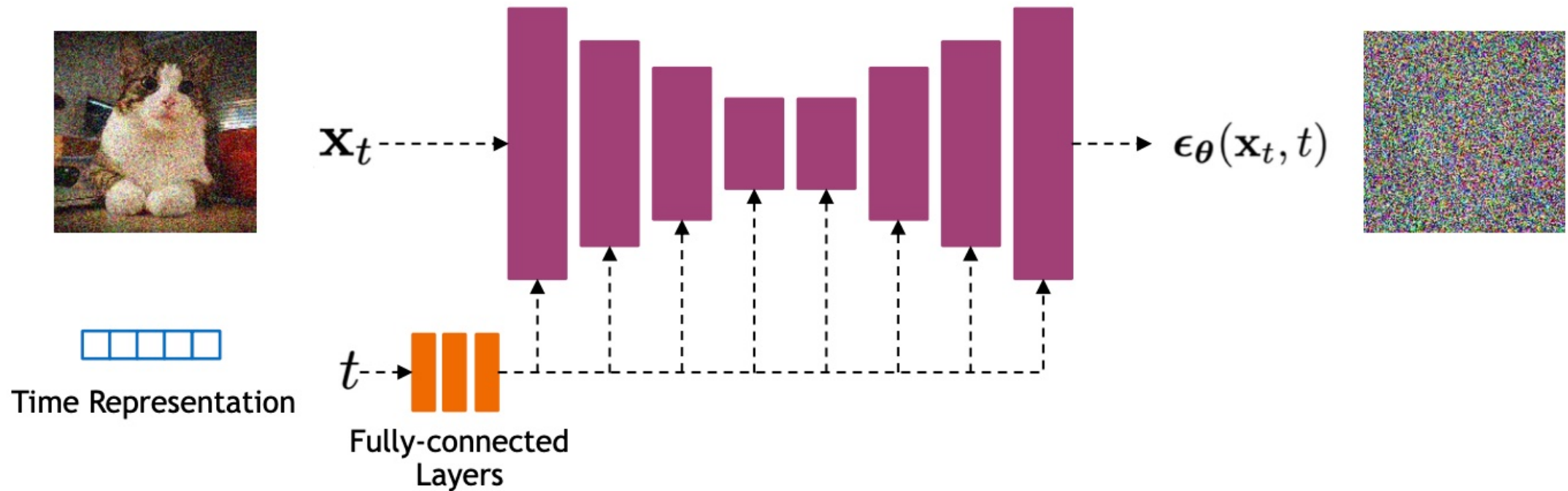


Figure 1: Classifier-free guidance on the malamute class for a 64x64 ImageNet diffusion model. Left to right: increasing amounts of classifier-free guidance, starting from non-guided samples on the left.



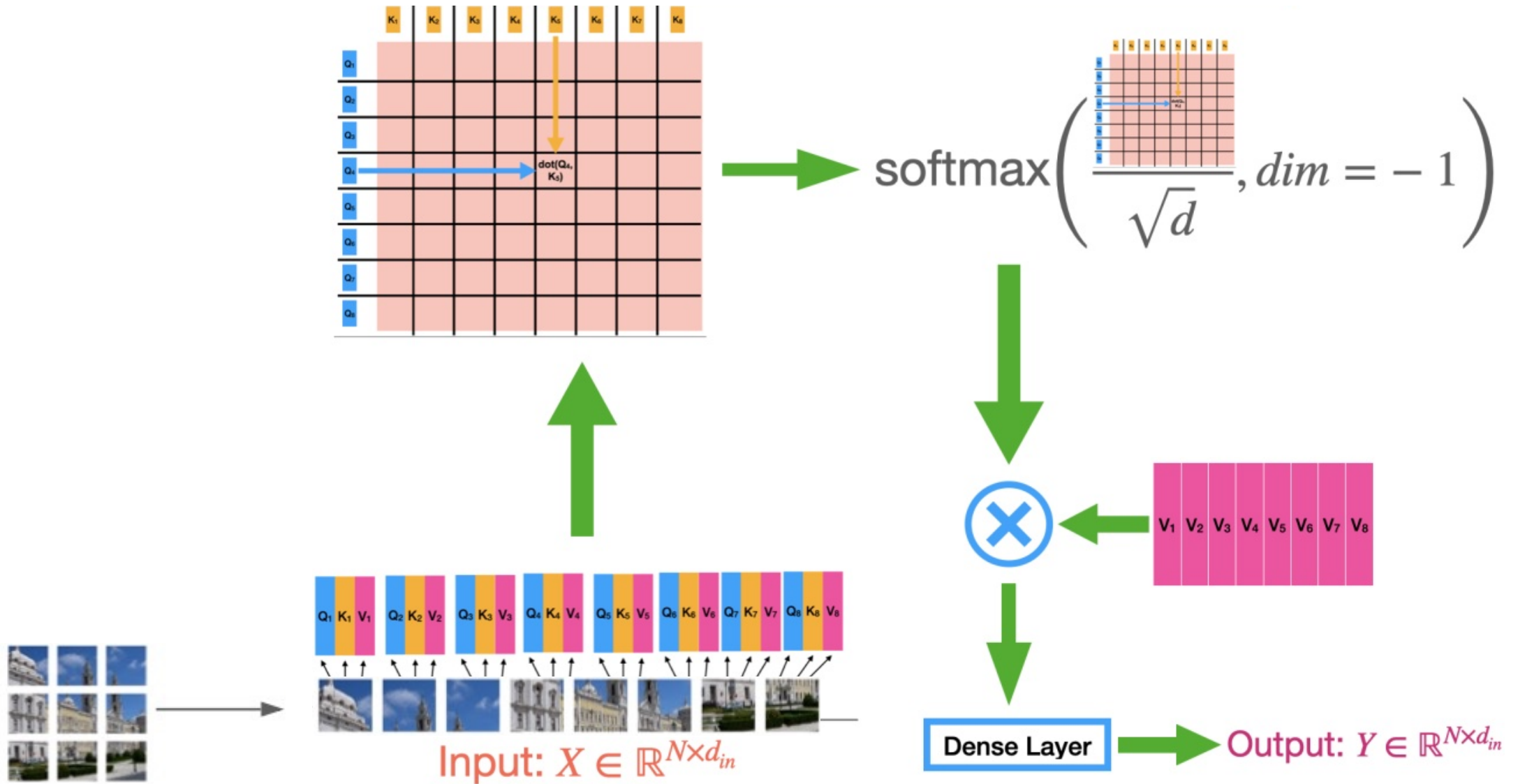
DDPMs: Implementation

- U-Net architectures are typically used to represent $\epsilon_{\theta}(x_t, t)$
 - Bells and whistles: residual blocks, self-attention



- Time is encoded using sinusoidal positional embeddings or random Fourier features, fed into the U-Net using addition or adaptive normalization

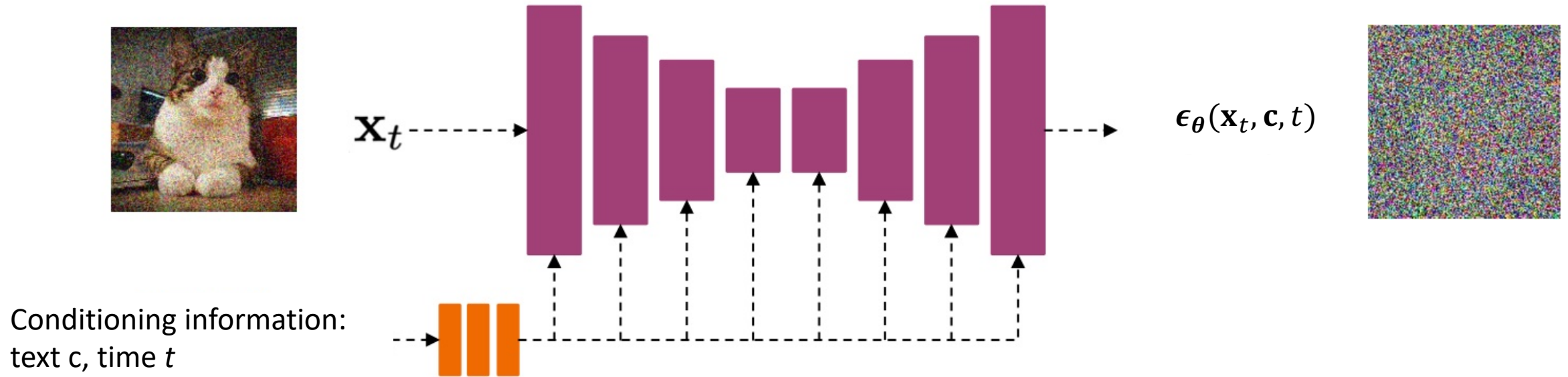
Attention Module





Text-guided diffusion

- Instead of a class label, c can be an encoded text prompt, injected into the U-Net using *cross-attention*



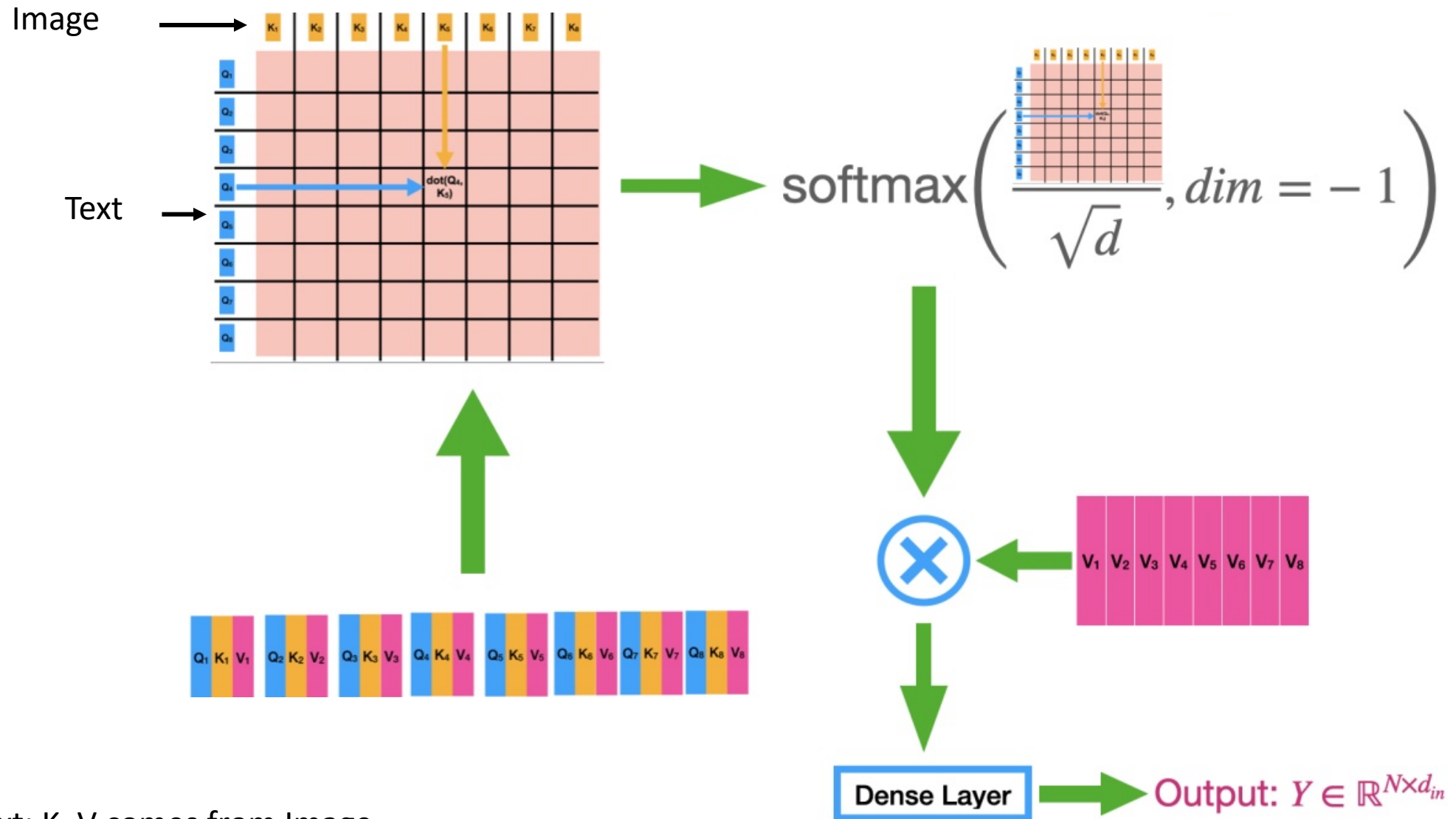


Text-guided diffusion

- Instead of a class label, c can be an encoded text prompt, injected into the U-Net using *cross-attention*
- Classifier-free guidance works the same way as before, by training both conditional and unconditional models using text dropout
- CLIP guidance: steer samples in the direction of $\nabla_{x_t} \text{CLIP}(x_t, c)$
- Note: both classifier and CLIP must be *noise-aware* (trained on noised images)



Cross Attention Module

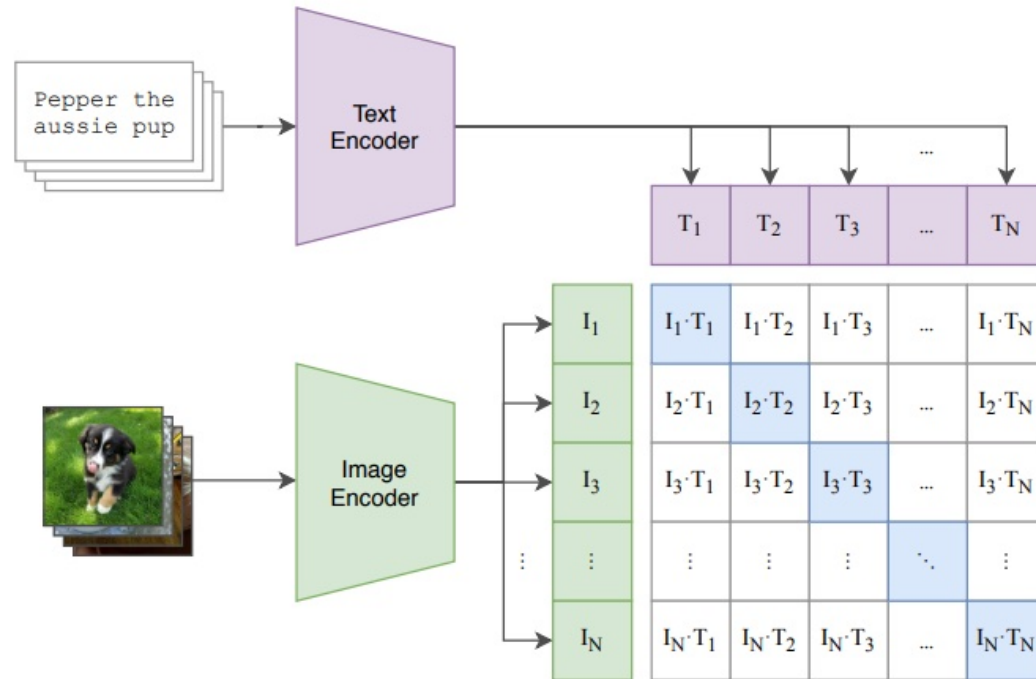


Q comes from Text; K, V comes from Image



CLIP

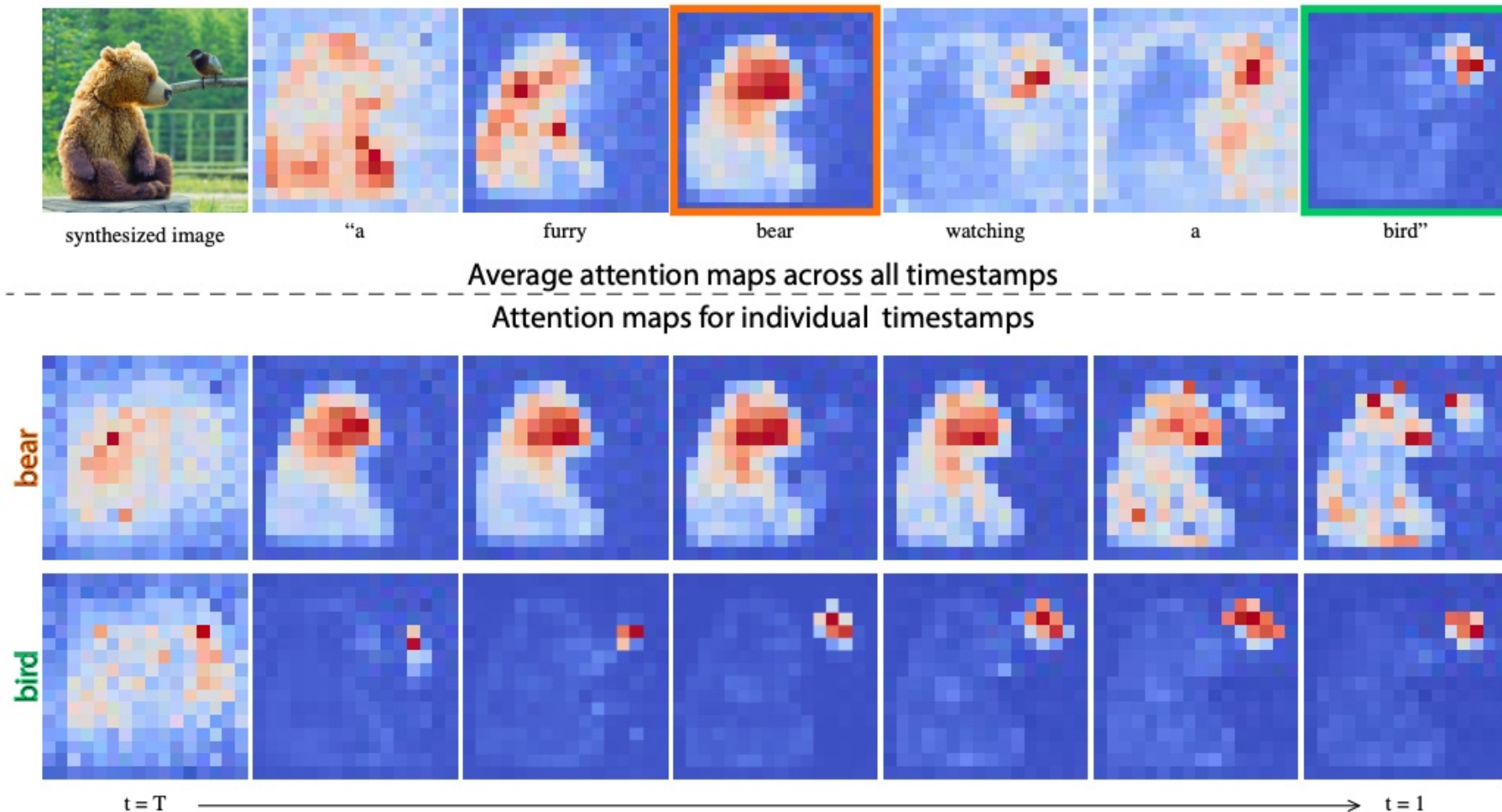
(1) Contrastive pre-training



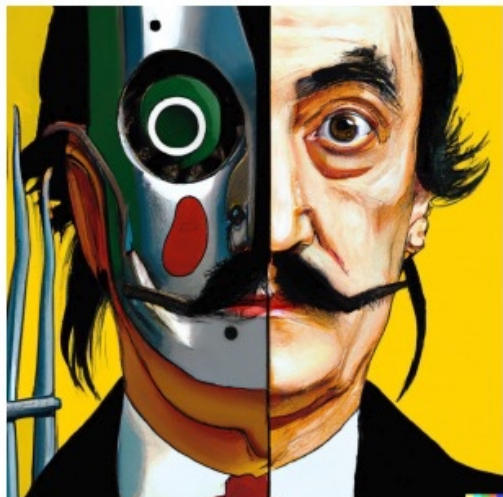
Contrastive objective: in a batch of N image-text pairs, classify each text string to the correct image and vice versa

Text-guided diffusion

- Instead of a class label, c can be an encoded text prompt, injected into the U-Net using *cross-attention*



DALL-E 2



vibrant portrait painting of Salvador Dalí with a robotic half face



a shiba inu wearing a beret and black turtleneck



a close up of a handpalm with leaves growing from it



an espresso machine that makes coffee from human souls, artstation

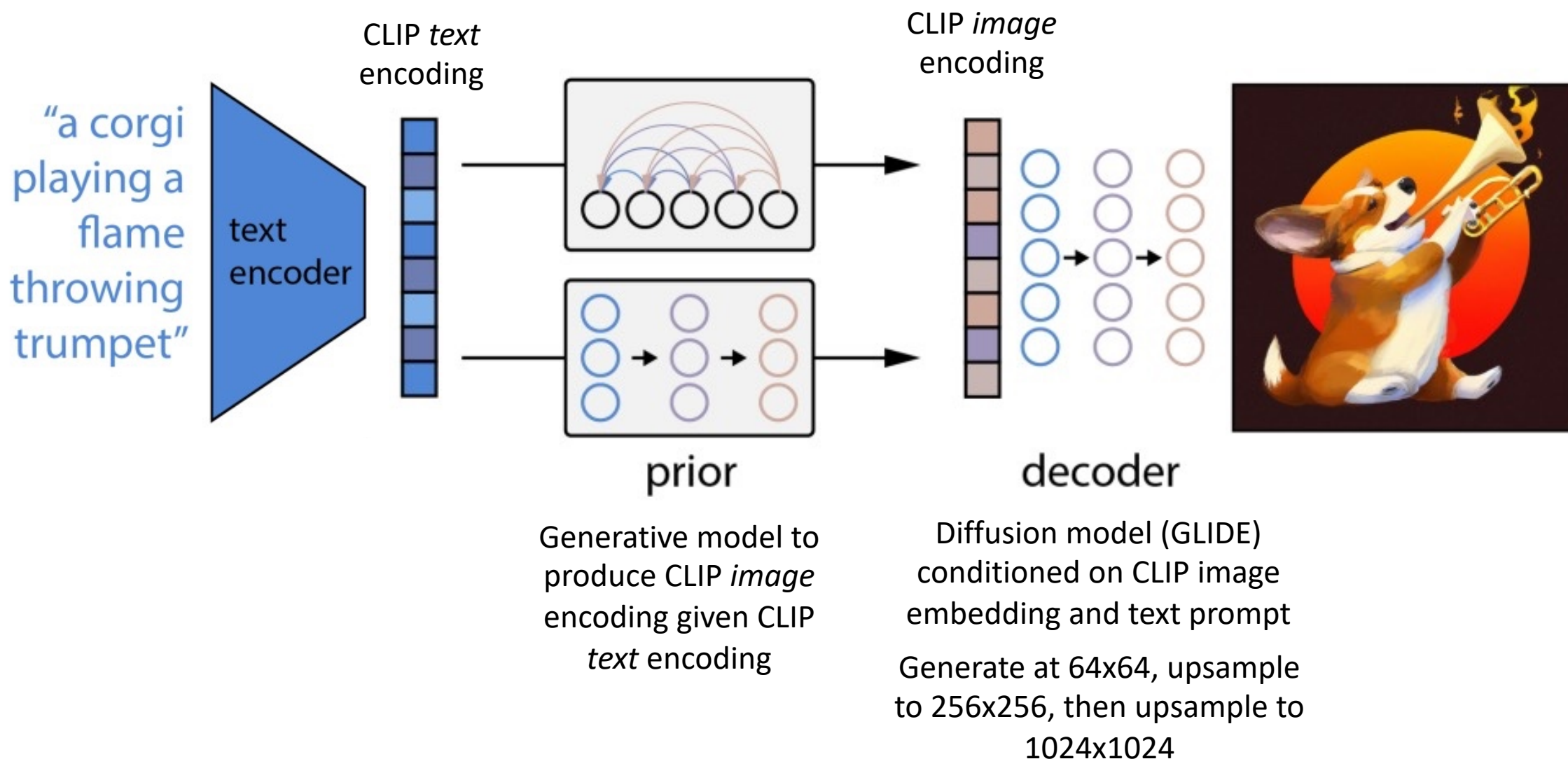


panda mad scientist mixing sparkling chemicals, artstation



a corgi's head depicted as an explosion of a nebula

DALL-E 2



DALL-E 2: Results



Figure 19: Random samples from unCLIP for prompt “A close up of a handpalm with leaves growing from it.”



Figure 18: Random samples from unCLIP for prompt “Vibrant portrait painting of Salvador Dali with a robotic half face”

DALL-E 2: Results



Figure 3: Variations of an input image by encoding with CLIP and then decoding with a diffusion model. The variations preserve both semantic information like presence of a clock in the painting and the overlapping strokes in the logo, as well as stylistic elements like the surrealism in the painting and the color gradients in the logo, while varying the non-essential details.

DALL-E 2: Results



Figure 4: Variations between two images by interpolating their CLIP image embedding and then decoding with a diffusion model. We fix the decoder seed across each row. The intermediate variations naturally blend the content and style from both input images.

DALL-E 2: Limitations



Figure 15: Reconstructions from the decoder for difficult binding problems. We find that the reconstructions mix up objects and attributes. In the first two examples, the model mixes up the color of two objects. In the rightmost example, the model does not reliably reconstruct the relative size of two objects.

Google Imagen (not public)



Sprouts in the shape of text 'Imagen' coming out of a fairytale book.



A photo of a Shiba Inu dog with a backpack riding a bike. It is wearing sunglasses and a beach hat.



A high contrast portrait of a very happy fuzzy panda dressed as a chef in a high end kitchen making dough. There is a painting of flowers on the wall behind him.



Teddy bears swimming at the Olympics 400m Butterfly event.



A cute corgi lives in a house made out of sushi.

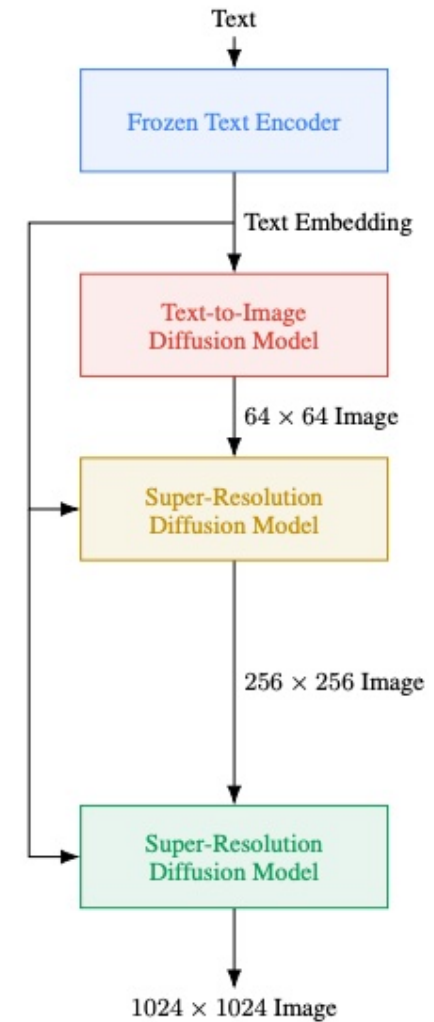


A cute sloth holding a small treasure chest. A bright golden glow is coming from the chest.



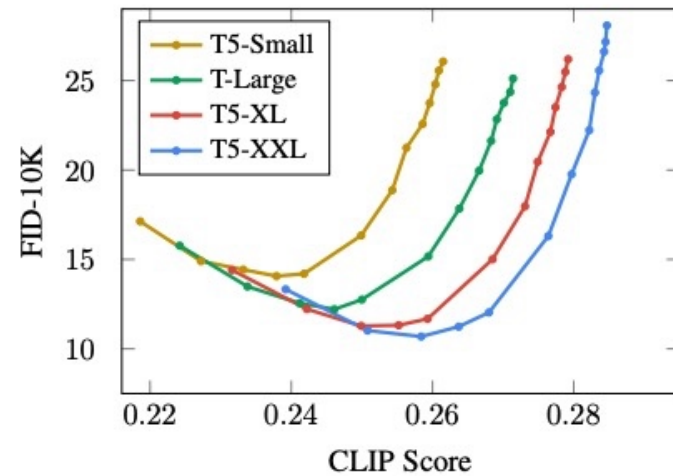
Google Imagen: Details

- Text encoder is a large language model (4.6B parameters) trained on text only
- Diffusion model to generate at 64×64 , upsample to 256×256 , then 1024×1024
 - Architecture: *efficient U-Net* (2B parameters): more parameters at lower resolutions, convolutions *after* downsampling and *before* upsampling
 - Classifier-free guidance with a *dynamic thresholding* technique, enabling good generation quality with high guidance weights
 - Training dataset: 460M image-text pairs (internally collected), 400M pairs from the [LAION dataset](#)

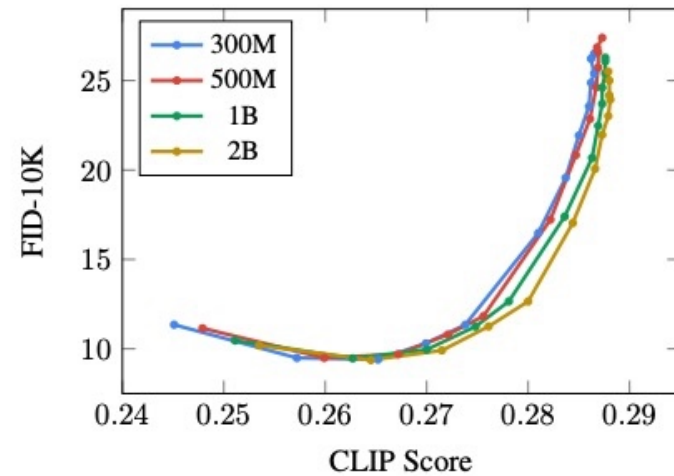


Google Imagen: Evaluation

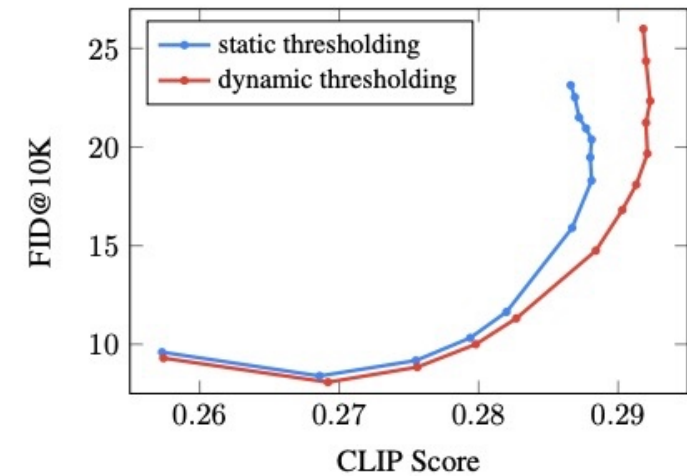
- Impact of model size, implementation choices



(a) Impact of encoder size.



(b) Impact of U-Net size.



(c) Impact of thresholding.

Curves are obtained by varying guidance weight

FID evaluated on COCO dataset by sampling prompts and generating images using the same prompts



Google Imagen: Evaluation

- Human evaluation on DrawBench (set of 200 prompts)

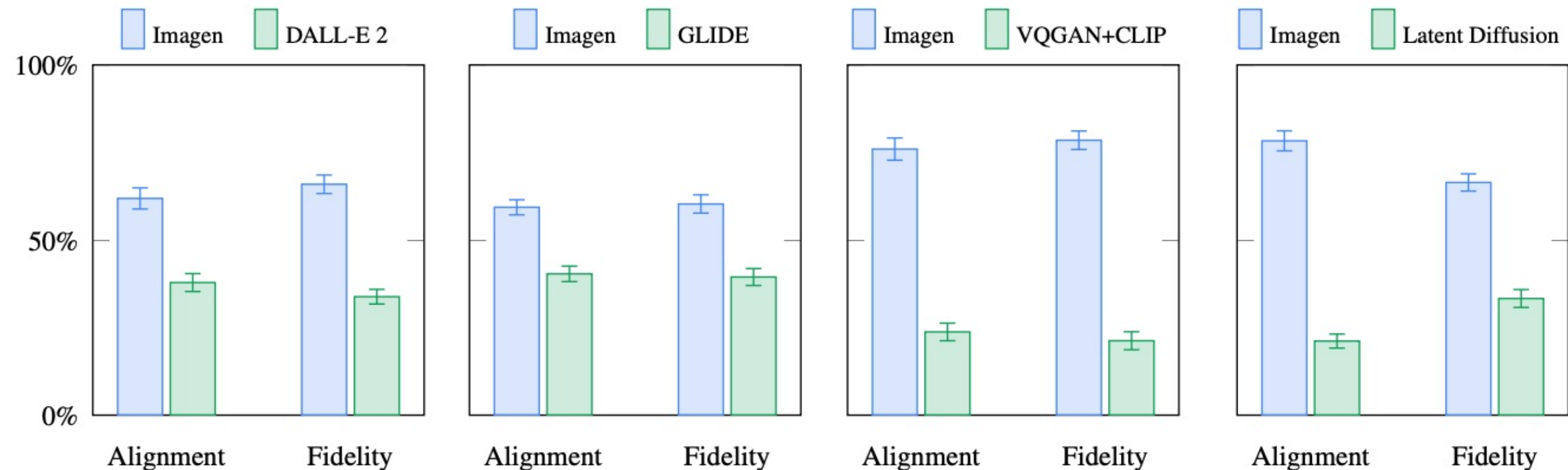
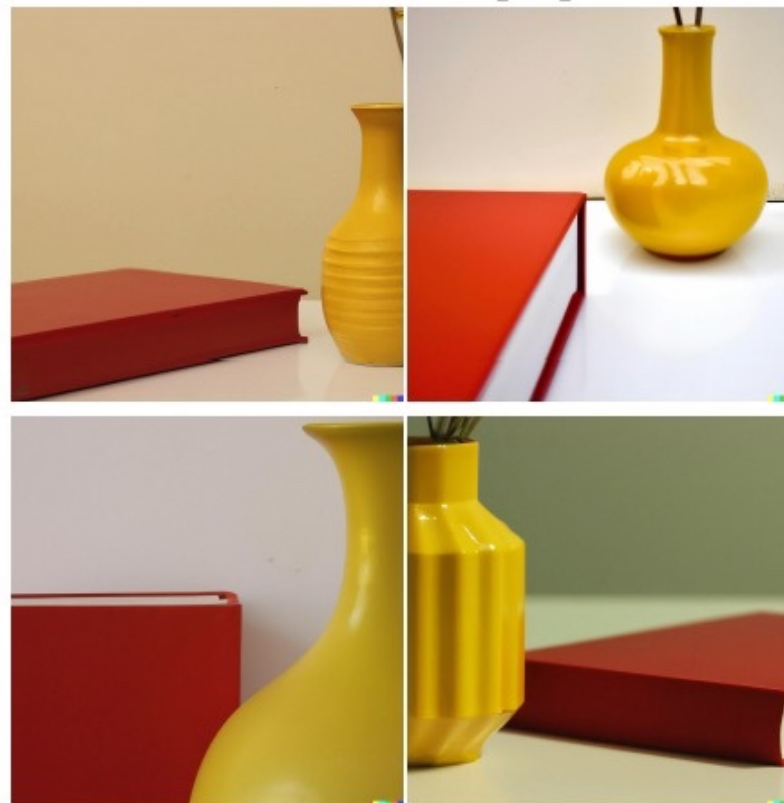


Imagen vs. DALL-E 2

Imagen (Ours)



DALL-E 2 [54]



“A yellow book and a red vase”



Imagen vs. DALL-E 2

Imagen (Ours)



DALL-E 2 [54]



“A black apple and a green backpack”

Imagen is better than DALL-E 2 in assigning the colors to the objects

Imagen vs. DALL-E 2

Imagen (Ours)



DALL-E 2 [54]



“A storefront with Text to Image written on it”

Imagen vs. DALL-E 2

Imagen (Ours)



DALL-E 2 [54]



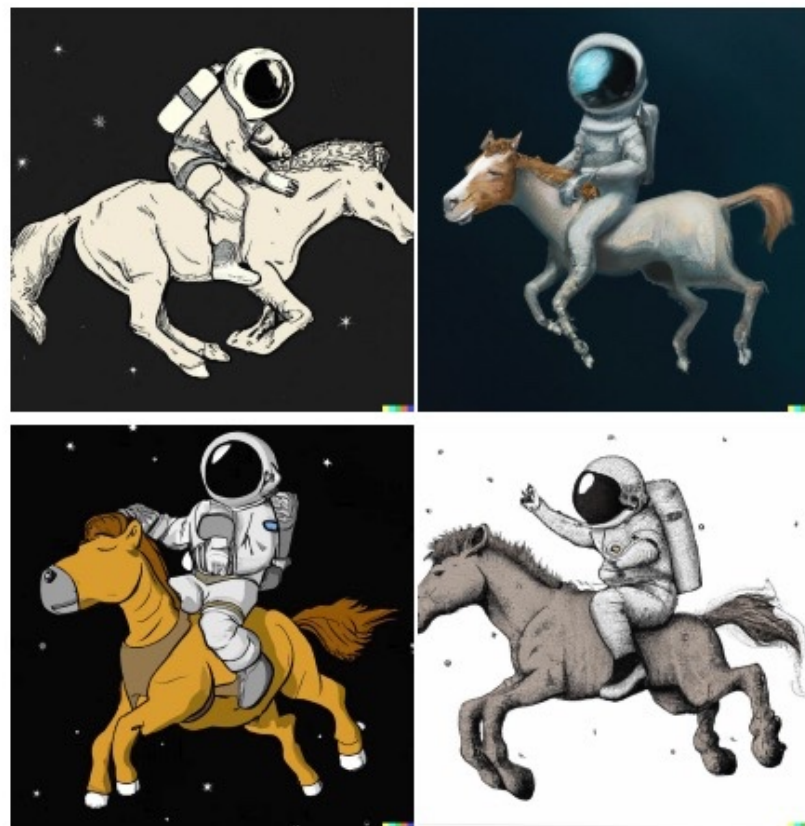
“A panda making latte art”

Imagen vs. DALL-E 2

Imagen (Ours)



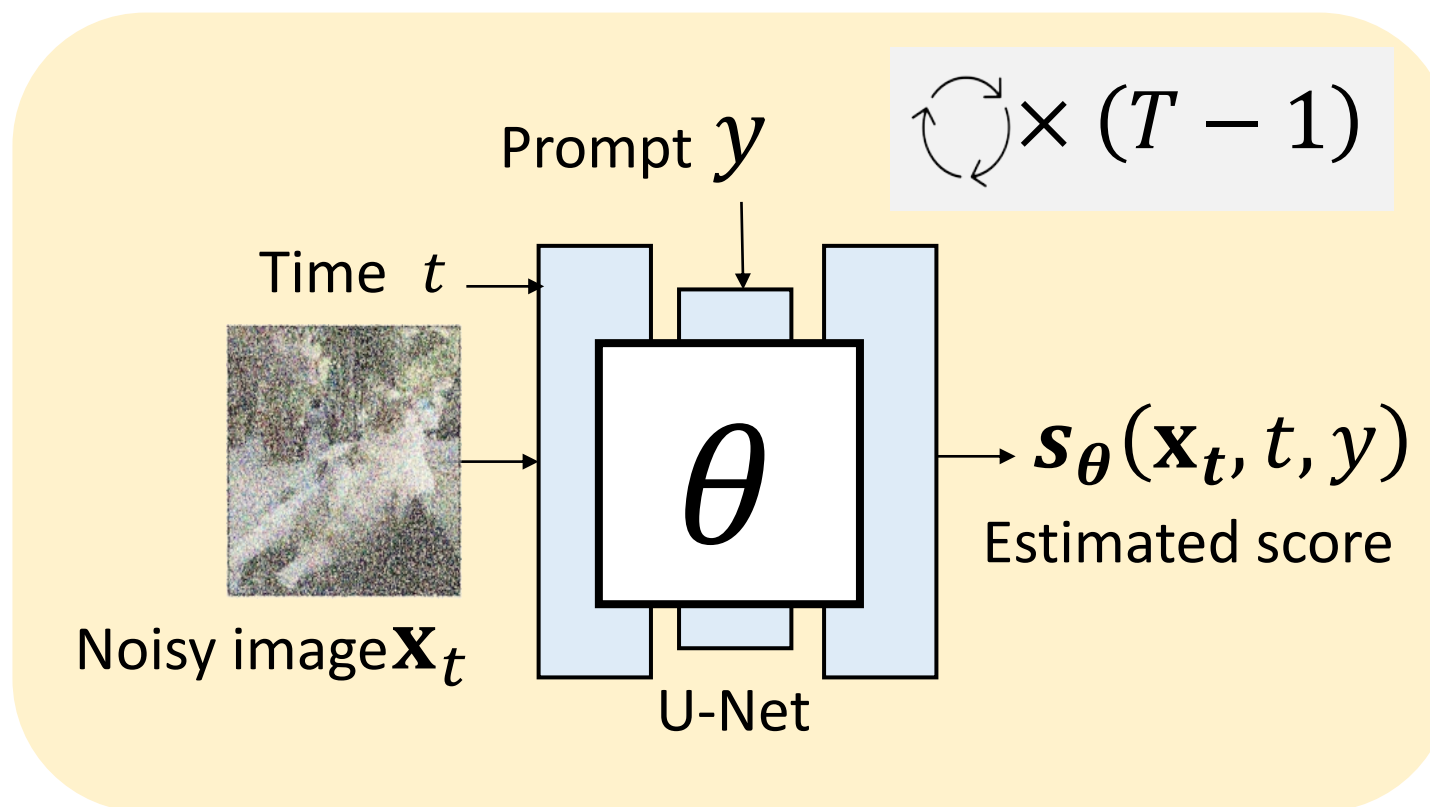
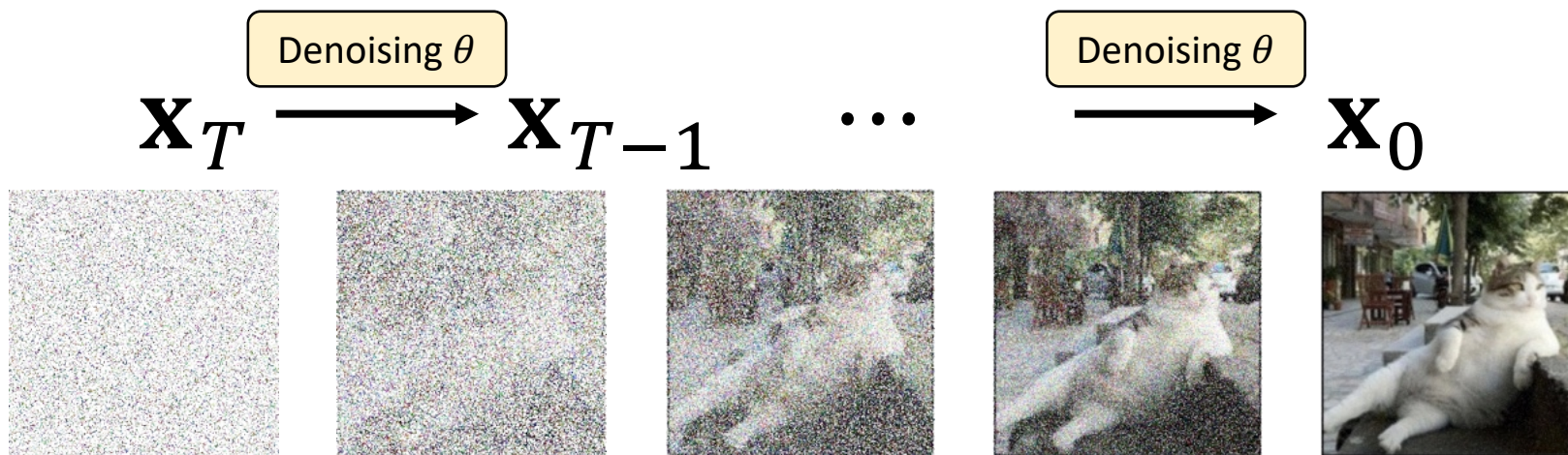
DALL-E 2 [54]



“A horse riding an astronaut”



Challenge: Resolution

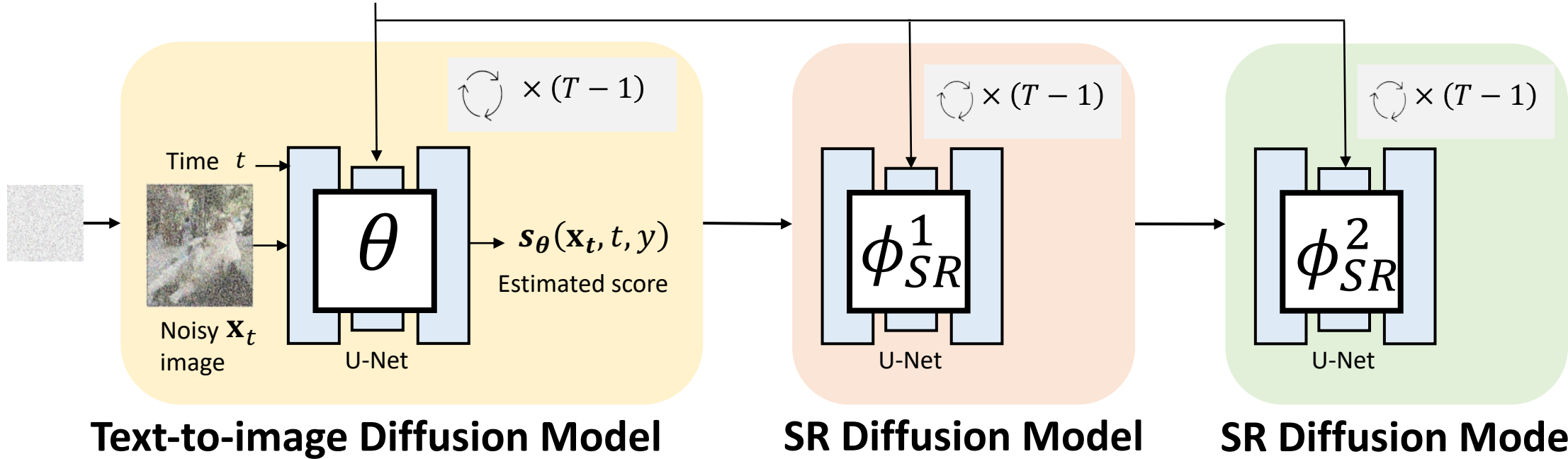




Cascade Diffusion Models



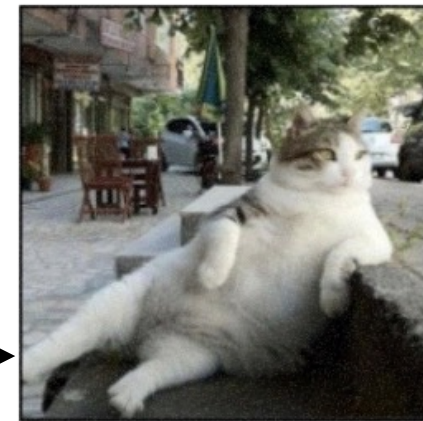
Prompt y



64×64



256×256

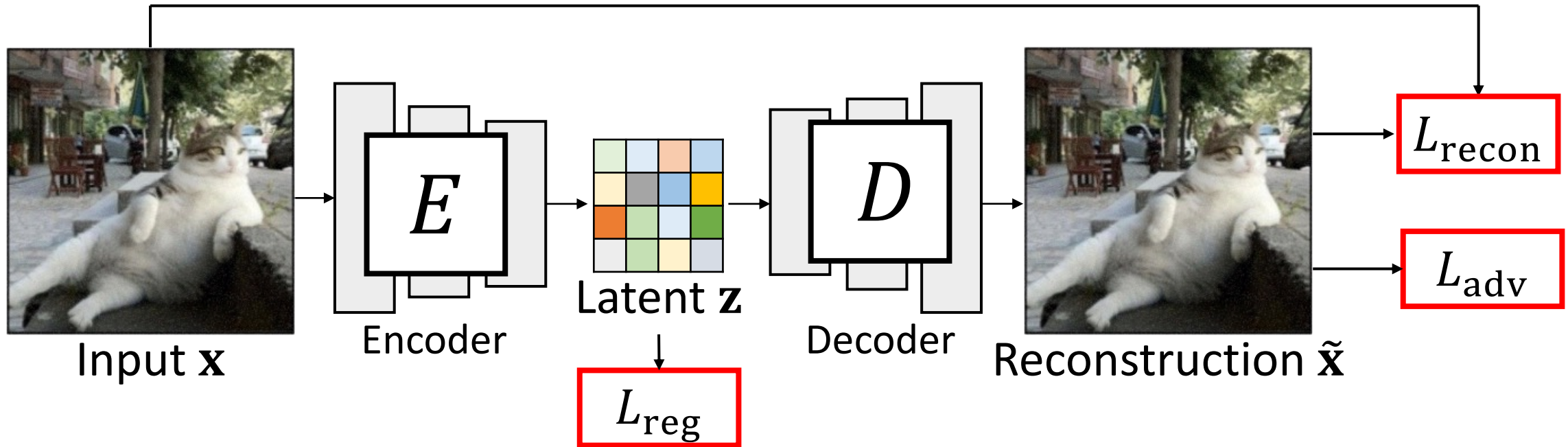


1024×1024

Slide from Jia-Bin Huang

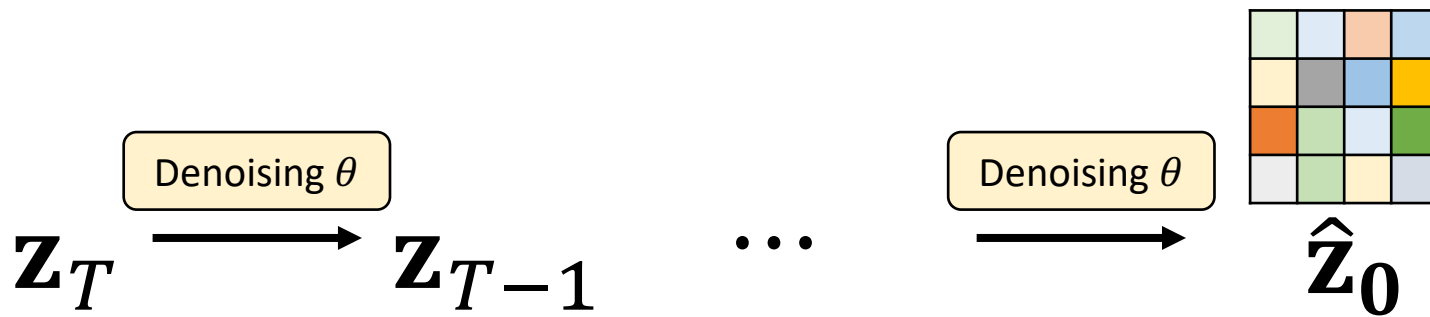
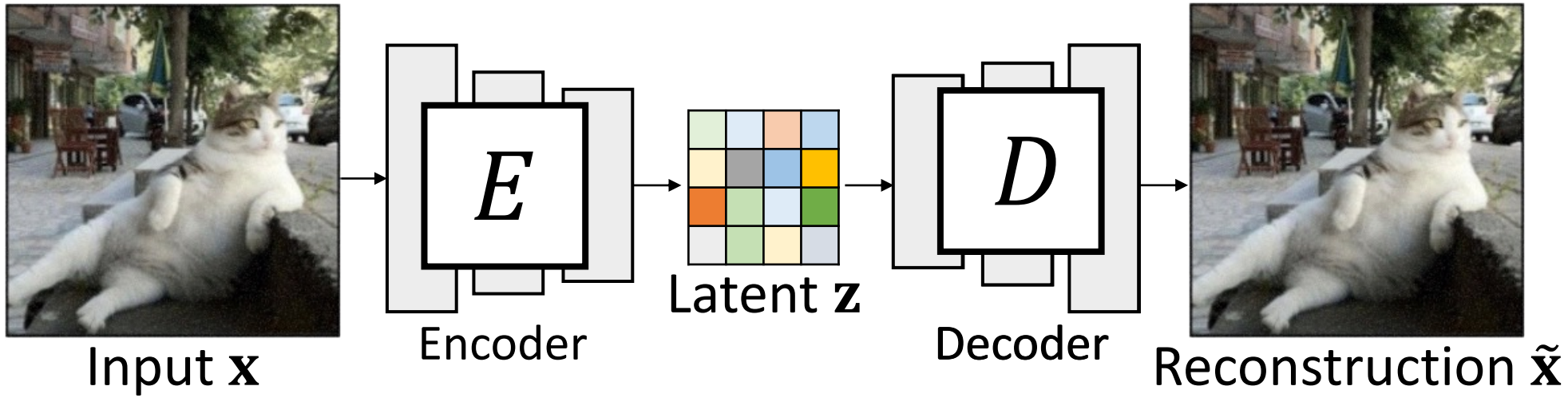


Latent Diffusion Models



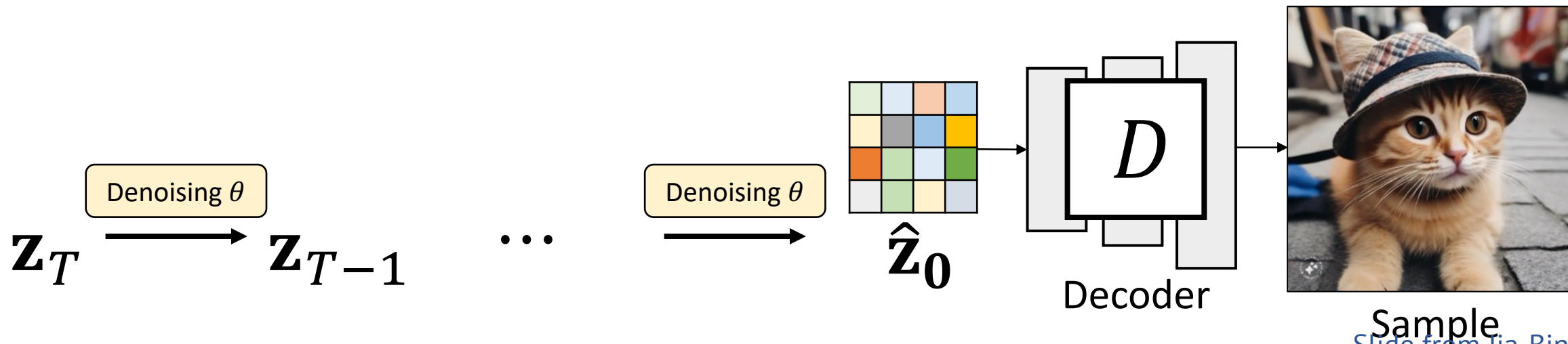
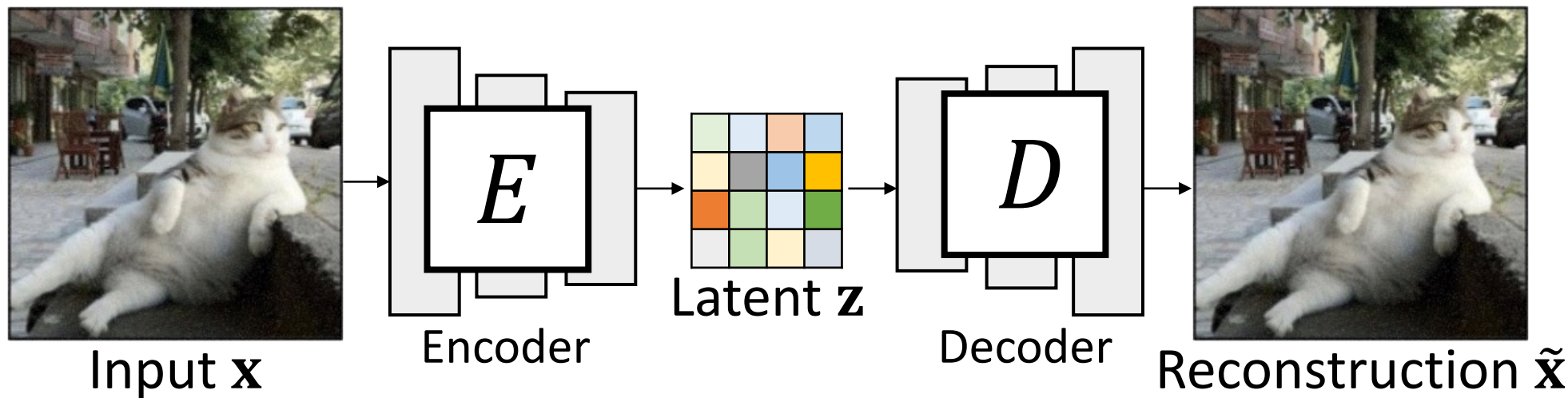


Latent Diffusion Models





Latent Diffusion Models



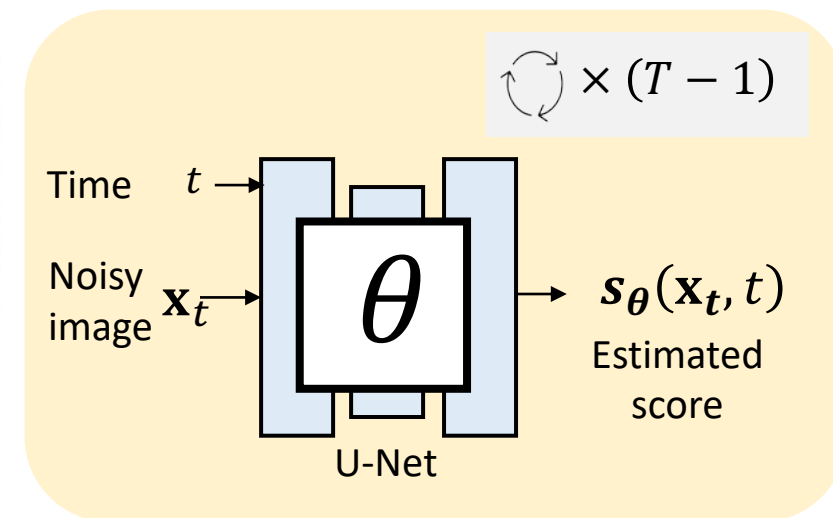
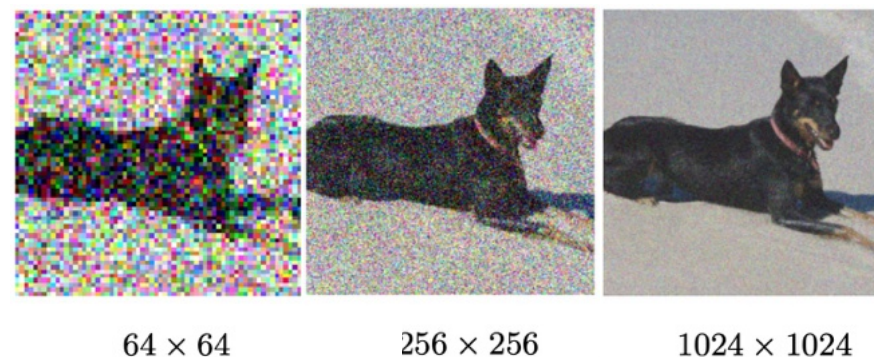


End-to-end Diffusion Models



Adjusted noise schedules

[Chen et al. 2023] [Hoogetboom et al. 2023]



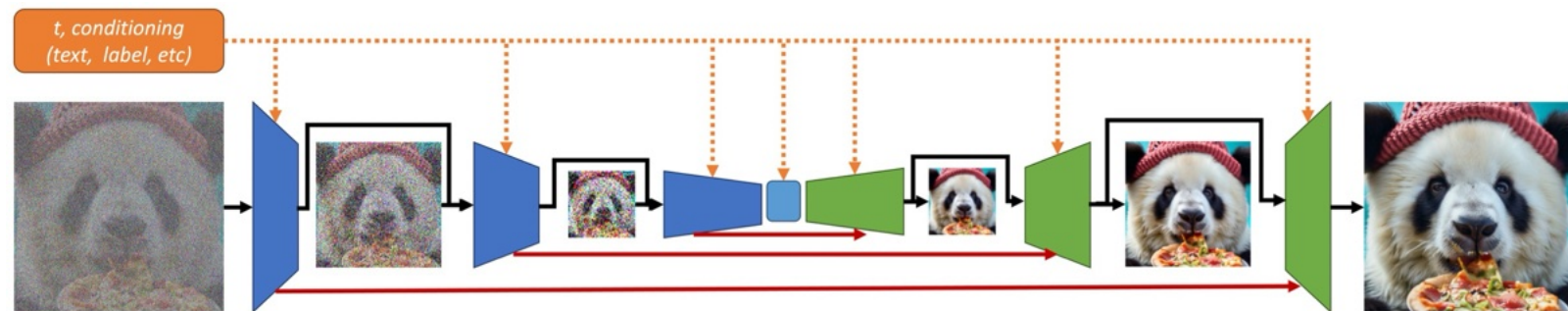
Multi-scale loss

simple diffusion [Hoogetboom et al. 2023]

$$L_\theta(\mathbf{x}) \xrightarrow{\text{Single-scale}} \sum_s \frac{1}{s} L_\theta^{s \times s}(\mathbf{x}) \quad \text{Multi-scale}$$

Progressive training

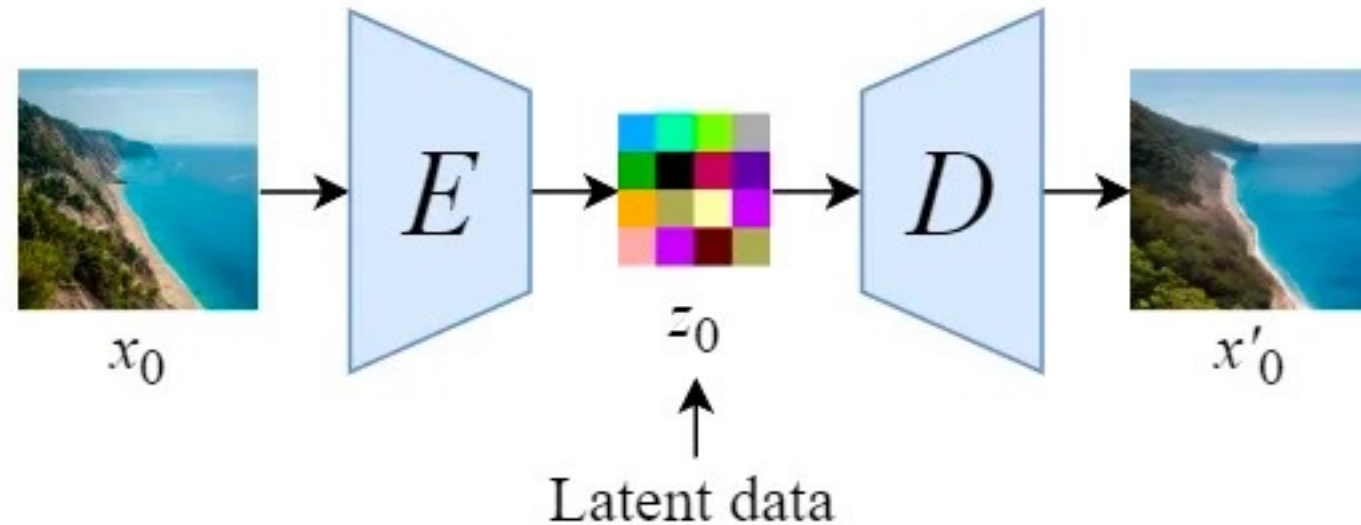
Matryoshka Diffusion Models [Gu et al. 2023]





Latent diffusion model (basis of Stable Diffusion)

- Key idea: train a separate *encoder* and *decoder* to convert images to and from a lower-dimensional latent space, run conditional diffusion model in latent space



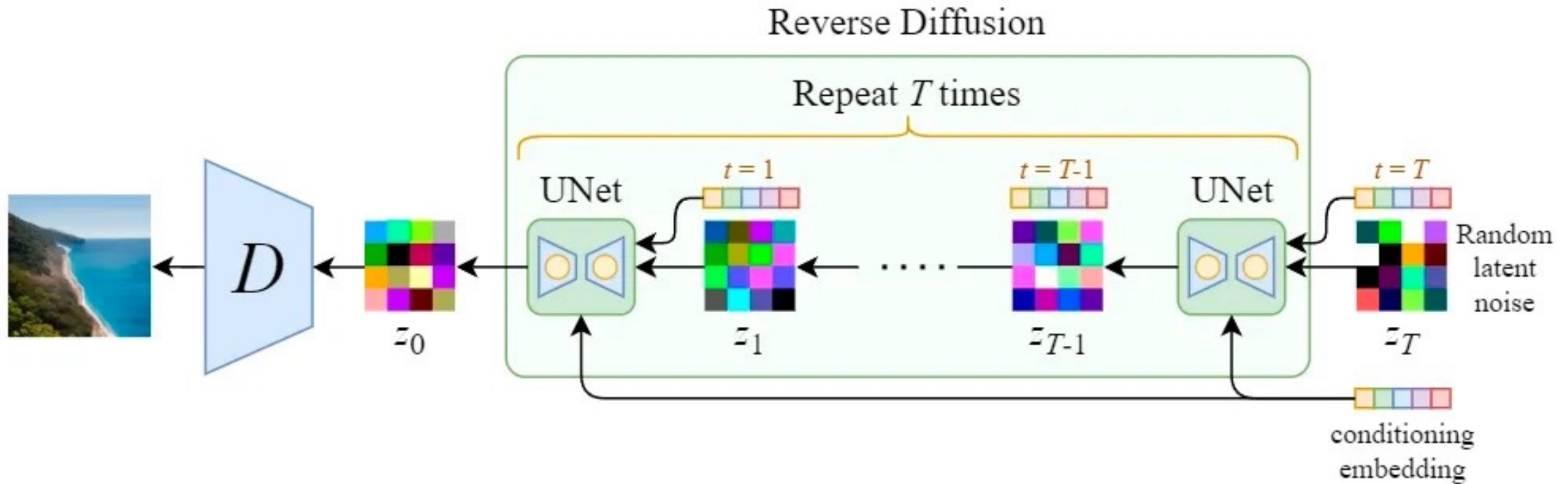
R. Rombach et al. [High-Resolution Image Synthesis with Latent Diffusion Models](#). CVPR 2022

<https://medium.com/@steinsfu/stable-diffusion-clearly-explained-ed008044e07e>



Latent diffusion model (basis of Stable Diffusion)

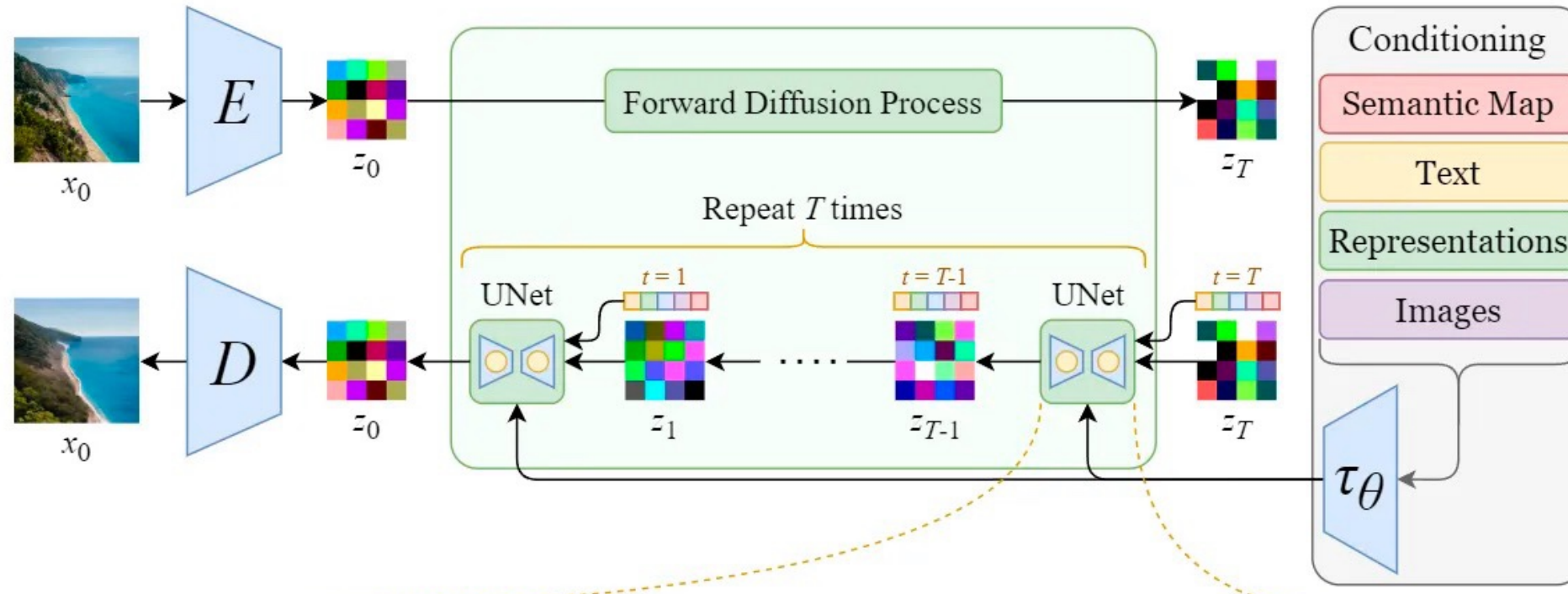
- Key idea: train a separate *encoder* and *decoder* to convert images to and from a lower-dimensional latent space, run conditional



Latent diffusion model (basis of Stable Diffusion)

- Key idea: train a separate *encoder* and *decoder* to convert images to and from a lower-dimensional latent space, run conditional diffusion model in latent space

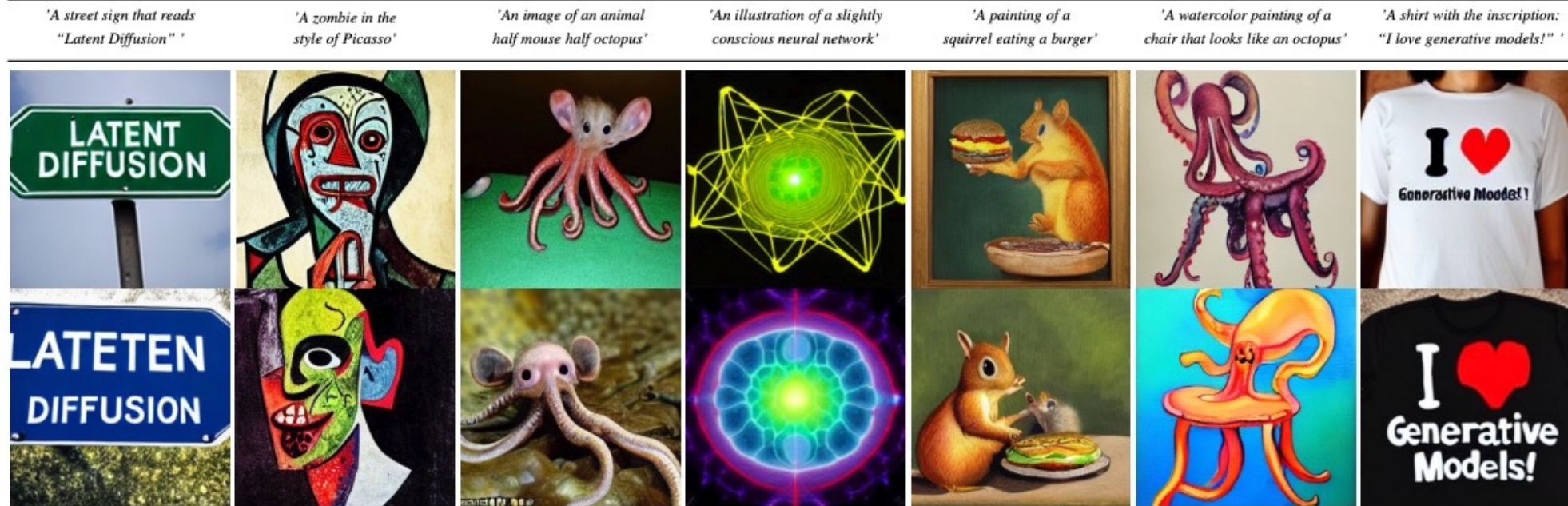
Close-up of U-Net: Conditioning information incorporated using cross-attention



Latent diffusion model (basis of Stable Diffusion)



Text-to-Image Synthesis on LAION. 1.45B Model.





Challenge: Inference Speed

Denoising Diffusion Implicit Models (DDIMs)

- DDIM **roughly sketches** the final sample, then **refine** it with the reverse process
- **Key idea:**
 - Given $\mathbf{x}_t$, generate the **rough sketch** $\mathbf{x}_0$ and **refine** $p_\theta(\mathbf{x}_{t-1}|\mathbf{x}_t, \mathbf{x}_0)^1$
 - Unlike original diffusion model, it is not a Markovian structure

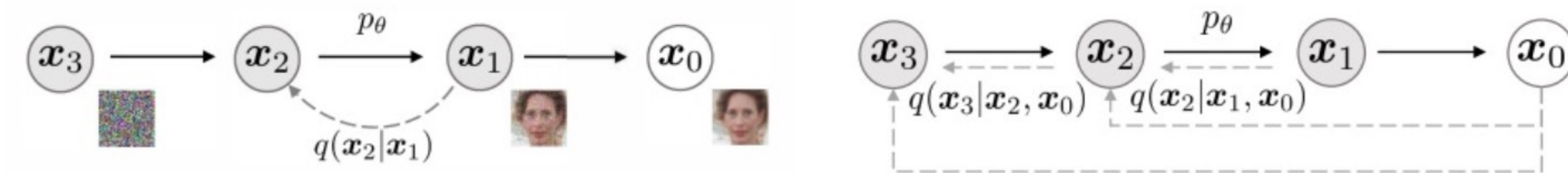


Figure 1: Graphical models for diffusion (left) and non-Markovian (right) inference models.

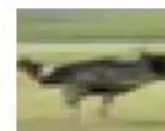
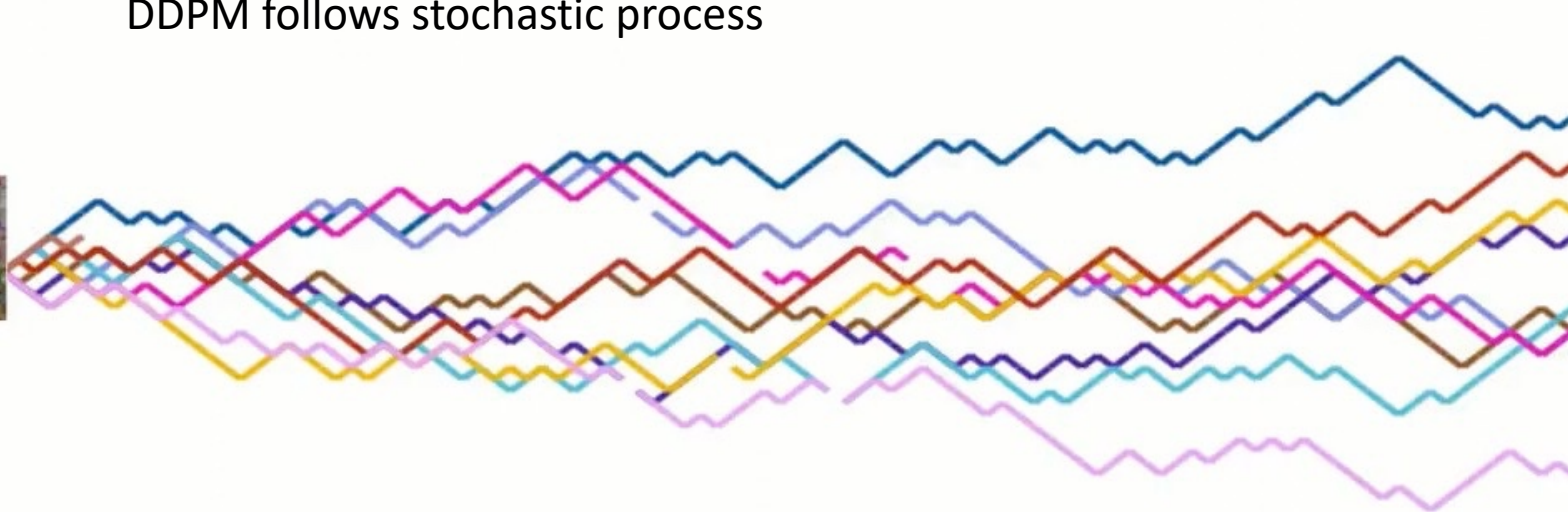
DDIM follows a deterministic process

DDPM follows stochastic process

DDPM



x_T



DDIM follows deterministic process

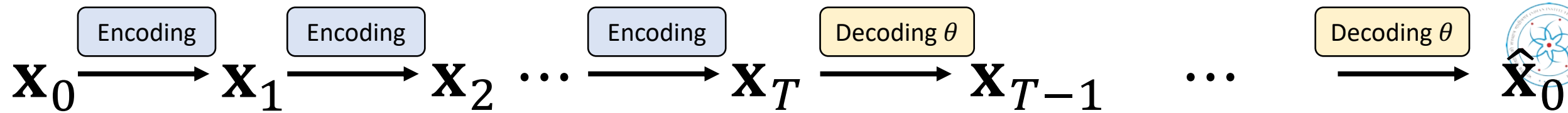
DDIM



x_T



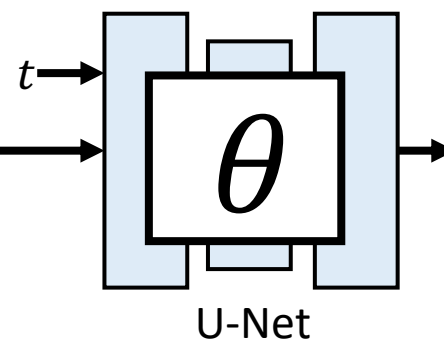
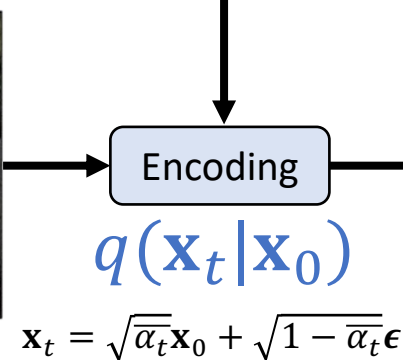
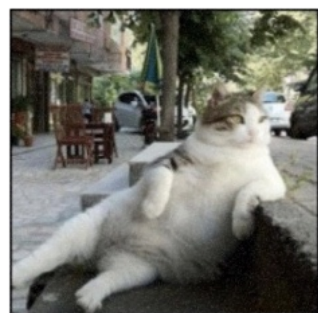
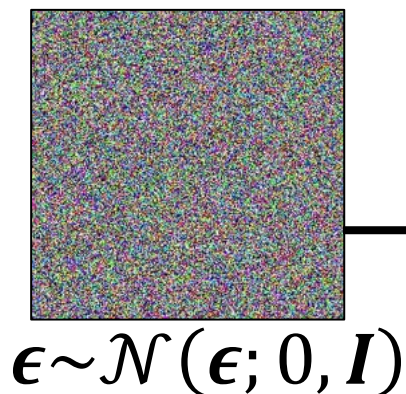
The same original noise x_T to same image x_0

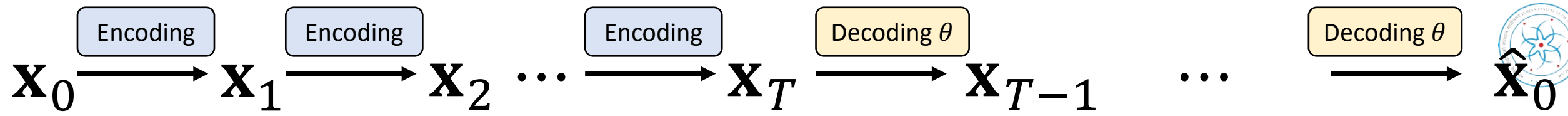


$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} [w(t) [|| \hat{\epsilon}_{\theta}(\mathbf{x}_t, t) - \epsilon ||_2^2]]$$

$$\mu_q(\mathbf{x}_t, \mathbf{x}_0) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{(1 - \bar{\alpha}_t)\alpha_t}} \epsilon$$

$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{(1 - \bar{\alpha}_t)\alpha_t}} \hat{\epsilon}_{\theta}(\mathbf{x}_t, t)$$

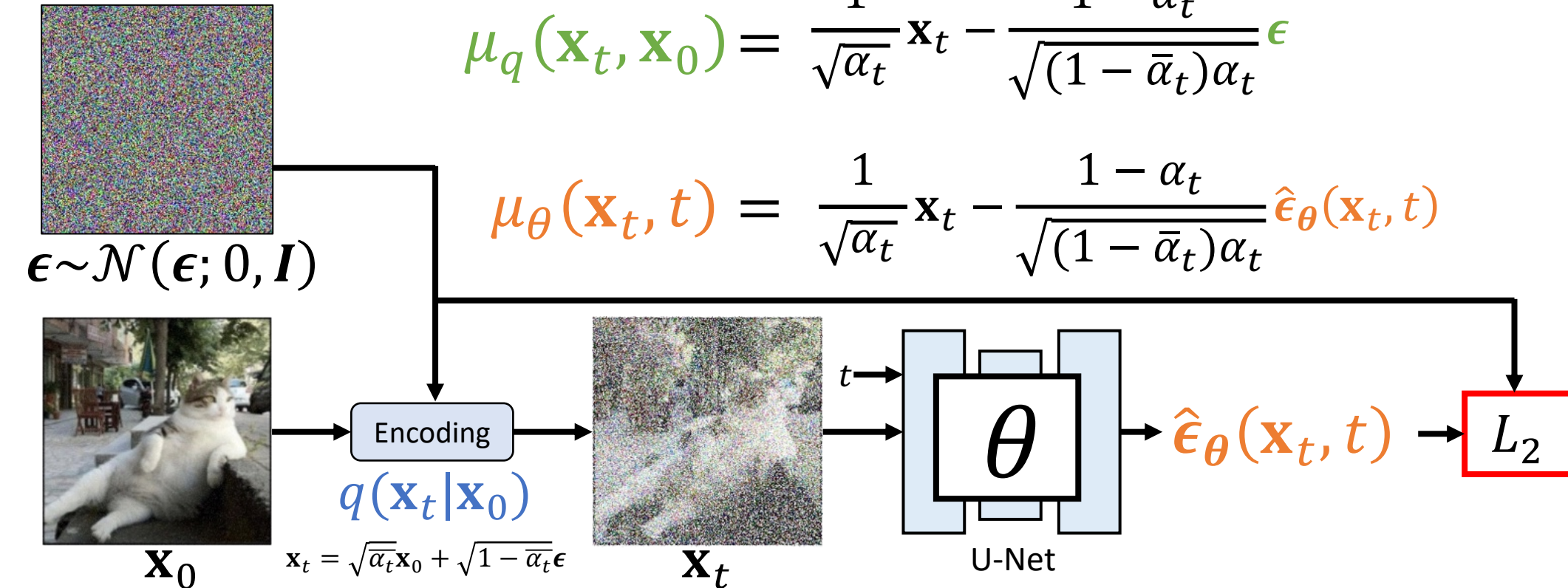


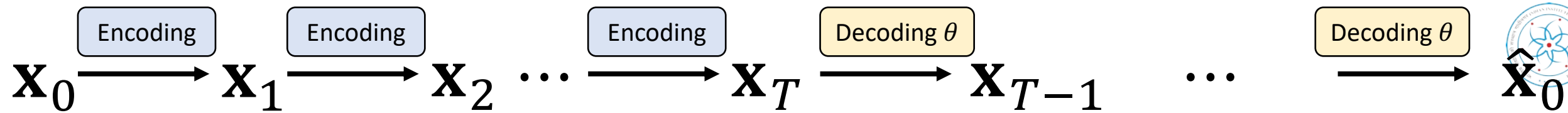


$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} [w(t) [|| \hat{\epsilon}_{\theta}(\mathbf{x}_t, t) - \epsilon ||_2^2]]$$

$$\mu_q(\mathbf{x}_t, \mathbf{x}_0) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{(1 - \bar{\alpha}_t)\alpha_t}} \epsilon$$

$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{(1 - \bar{\alpha}_t)\alpha_t}} \hat{\epsilon}_{\theta}(\mathbf{x}_t, t)$$

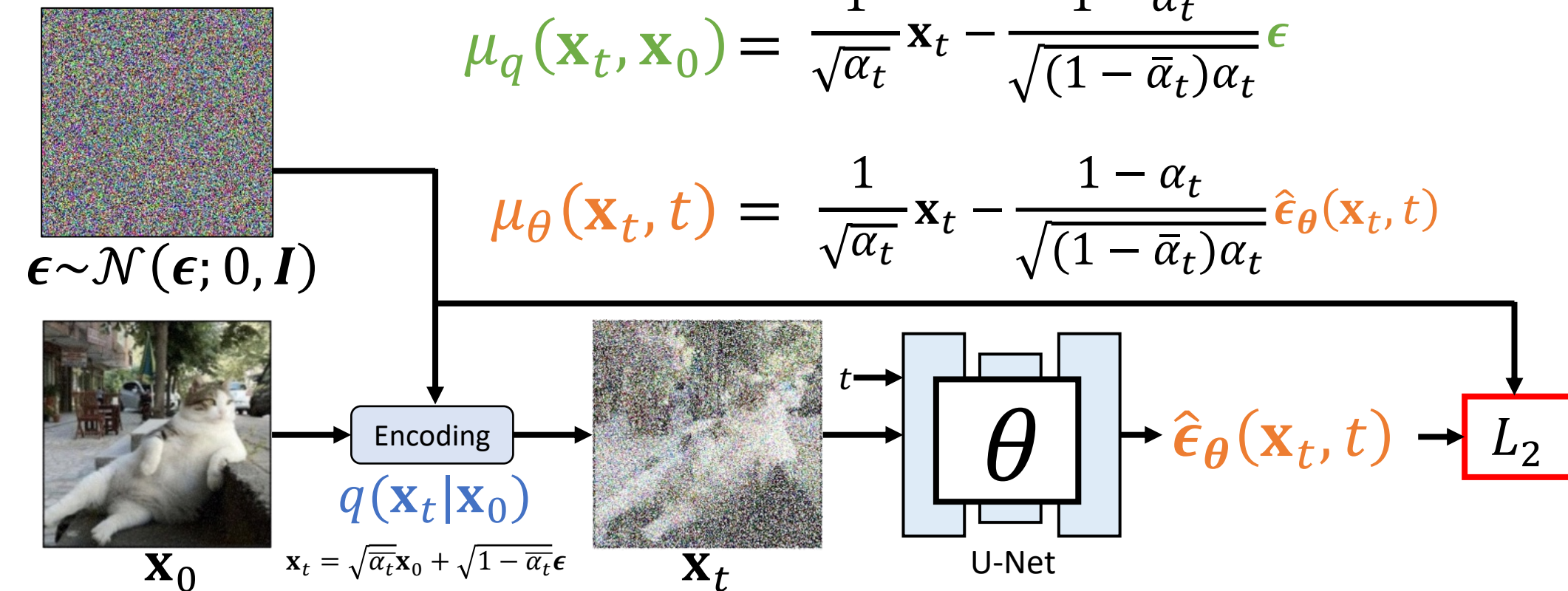


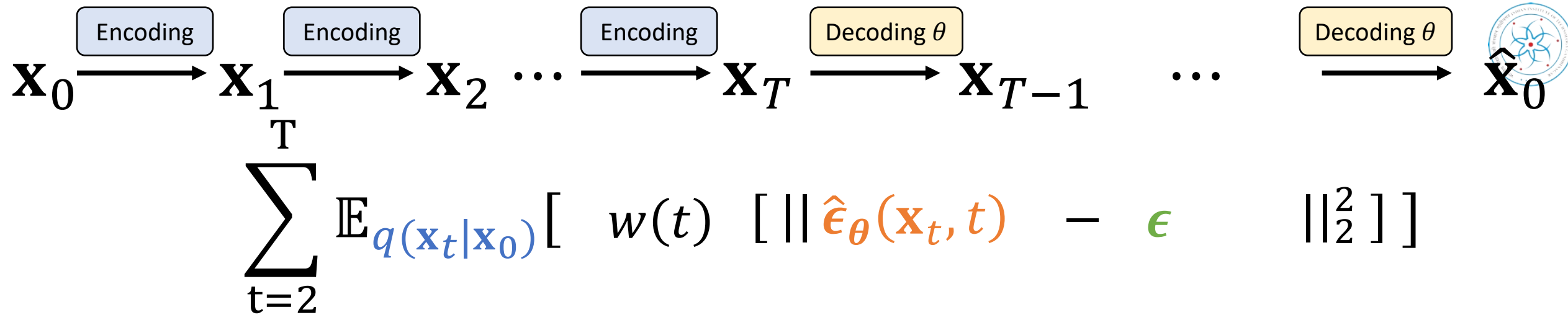


$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} [w(t) [|| \hat{\epsilon}_{\theta}(\mathbf{x}_t, t) - \epsilon ||_2^2]]$$

$$\mu_q(\mathbf{x}_t, \mathbf{x}_0) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{(1 - \bar{\alpha}_t)\alpha_t}} \epsilon$$

$$\mu_{\theta}(\mathbf{x}_t, t) = \frac{1}{\sqrt{\alpha_t}} \mathbf{x}_t - \frac{1 - \alpha_t}{\sqrt{(1 - \bar{\alpha}_t)\alpha_t}} \hat{\epsilon}_{\theta}(\mathbf{x}_t, t)$$



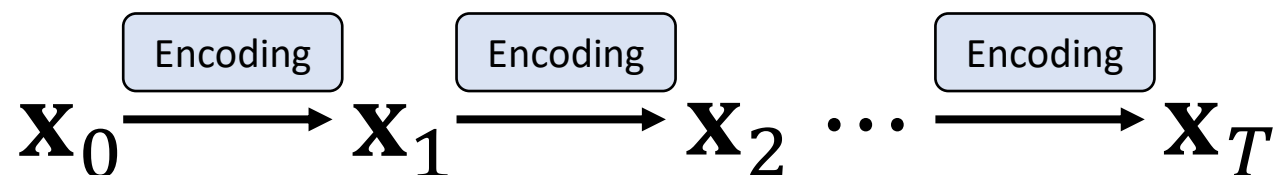


- ① $\mathbf{x}_t = \sqrt{\alpha_t} \mathbf{x}_0 + \sqrt{1 - \alpha_t} \epsilon$
- ② $\mu_q(\mathbf{x}_t, \mathbf{x}_0) = a \mathbf{x}_t + b \epsilon$
- ③ $\mu_{\theta}(\mathbf{x}_t, t) = a \mathbf{x}_t + b \hat{\epsilon}_{\theta}(\mathbf{x}_t, t)$



$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} \left[w(t) \left[\left\| \hat{\boldsymbol{\epsilon}}_{\boldsymbol{\theta}}(\mathbf{x}_t, t) - \boldsymbol{\epsilon} \right\|_2^2 \right] \right]$$

$$\textcircled{1} \quad \mathbf{x}_t = \sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t} \boldsymbol{\epsilon}$$



$$\textcircled{2} \quad \mu_q(\mathbf{x}_t, \mathbf{x}_0) = a\mathbf{x}_t + b\boldsymbol{\epsilon}$$

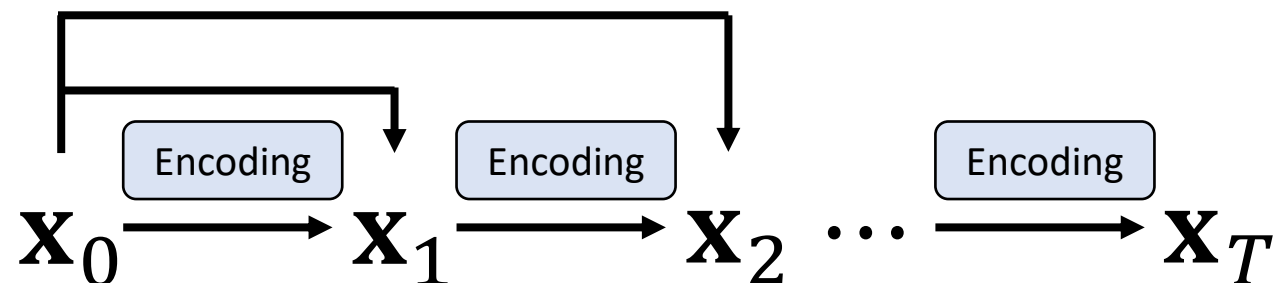
$$q(\mathbf{x}_t | \mathbf{x}_{t-1})$$

$$\textcircled{3} \quad \mu_{\boldsymbol{\theta}}(\mathbf{x}_t, t) = a\mathbf{x}_t + b\hat{\boldsymbol{\epsilon}}_{\boldsymbol{\theta}}(\mathbf{x}_t, t) \quad \text{No need to be a Markovian process!}$$



$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} \left[w(t) \left[\left\| \hat{\epsilon}_{\theta}(\mathbf{x}_t, t) - \epsilon \right\|_2^2 \right] \right]$$

$$\textcircled{1} \quad \mathbf{x}_t = \sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t} \epsilon$$



$$\textcircled{2} \quad \mu_q(\mathbf{x}_t, \mathbf{x}_0) = a\mathbf{x}_t + b\epsilon$$

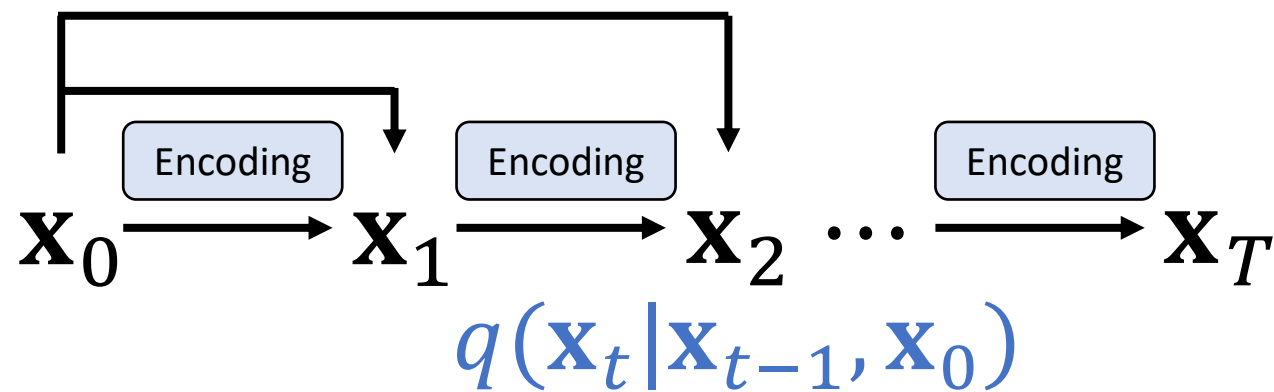
$$q(\mathbf{x}_t | \mathbf{x}_{t-1}, \mathbf{x}_0)$$

$$\textcircled{3} \quad \mu_{\theta}(\mathbf{x}_t, t) = a\mathbf{x}_t + b\hat{\epsilon}_{\theta}(\mathbf{x}_t, t)$$

Find a and b such that $\mathbf{x}_t = \sqrt{\bar{\alpha}_t} \mathbf{x}_0 + \sqrt{1 - \bar{\alpha}_t} \epsilon$!

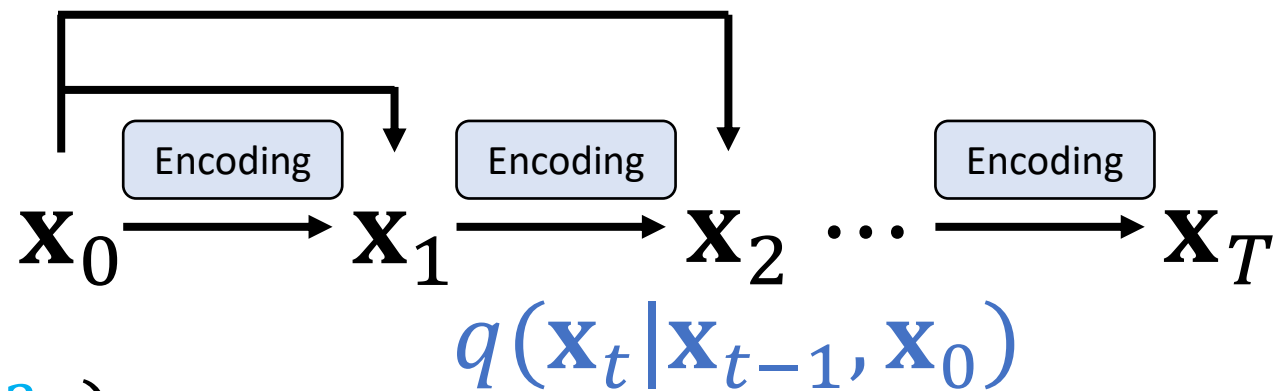


$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} \left[w(t) \left[\left\| \hat{\boldsymbol{\epsilon}}_{\boldsymbol{\theta}}(\mathbf{x}_t, t) - \boldsymbol{\epsilon} \right\|_2^2 \right] \right]$$





$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} \left[w(t) \left[\left\| \hat{\boldsymbol{\epsilon}}_{\boldsymbol{\theta}}(\mathbf{x}_t, t) - \boldsymbol{\epsilon} \right\|_2^2 \right] \right]$$

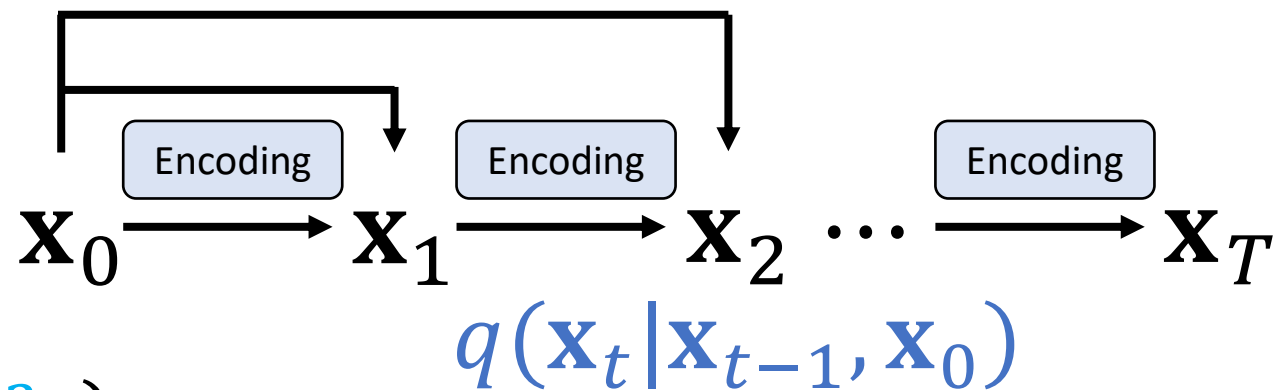


$$q(\mathbf{x}_{t-1} | \mathbf{x}_t, \mathbf{x}_0) = \mathcal{N}(\mu_q(\mathbf{x}_t, \mathbf{x}_0), \sigma_t^2 \mathbf{I})$$

$$p(\mathbf{x}_{t-1} | \mathbf{x}_t) = \mathcal{N}(\mu_{\boldsymbol{\theta}}(\mathbf{x}_t, \mathbf{x}_0), \sigma_t^2 \mathbf{I})$$



$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} \left[w(t) \left[\left\| \hat{\boldsymbol{\epsilon}}_{\theta}(\mathbf{x}_t, t) - \boldsymbol{\epsilon} \right\|_2^2 \right] \right]$$



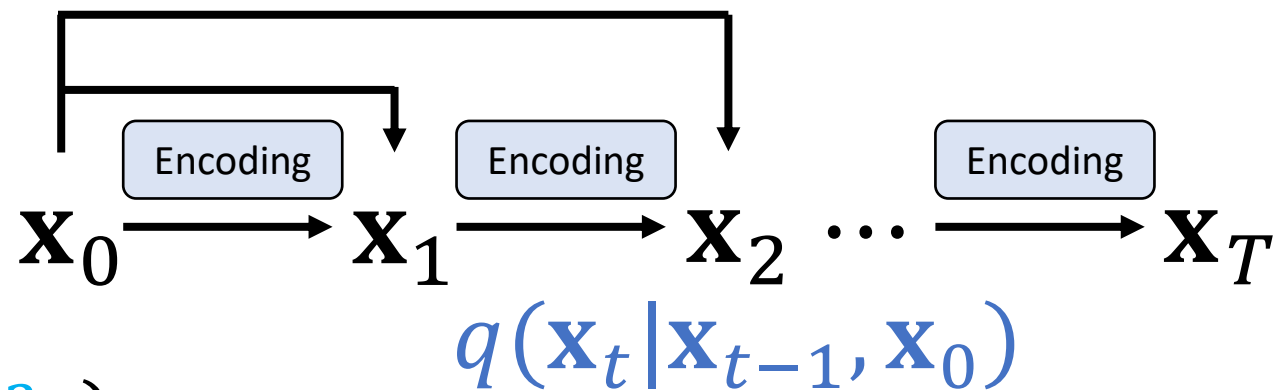
$$q(\mathbf{x}_{t-1} | \mathbf{x}_t, \mathbf{x}_0) = \mathcal{N}(\mu_q(\mathbf{x}_t, \mathbf{x}_0), \sigma_t^2 I)$$

$$p(\mathbf{x}_{t-1} | \mathbf{x}_t) = \mathcal{N}(\mu_{\theta}(\mathbf{x}_t, \mathbf{x}_0), \sigma_t^2 I)$$

$$\mu_q(\mathbf{x}_t, \mathbf{x}_0) = \sqrt{\alpha_t} \mathbf{x}_0 + \sqrt{1 - \alpha_t} \boldsymbol{\epsilon}$$



$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} \left[w(t) \left[\left\| \hat{\boldsymbol{\epsilon}}_{\theta}(\mathbf{x}_t, t) - \boldsymbol{\epsilon} \right\|_2^2 \right] \right]$$



$$q(\mathbf{x}_{t-1} | \mathbf{x}_t, \mathbf{x}_0) = \mathcal{N}(\mu_q(\mathbf{x}_t, \mathbf{x}_0), \sigma_t^2 I)$$

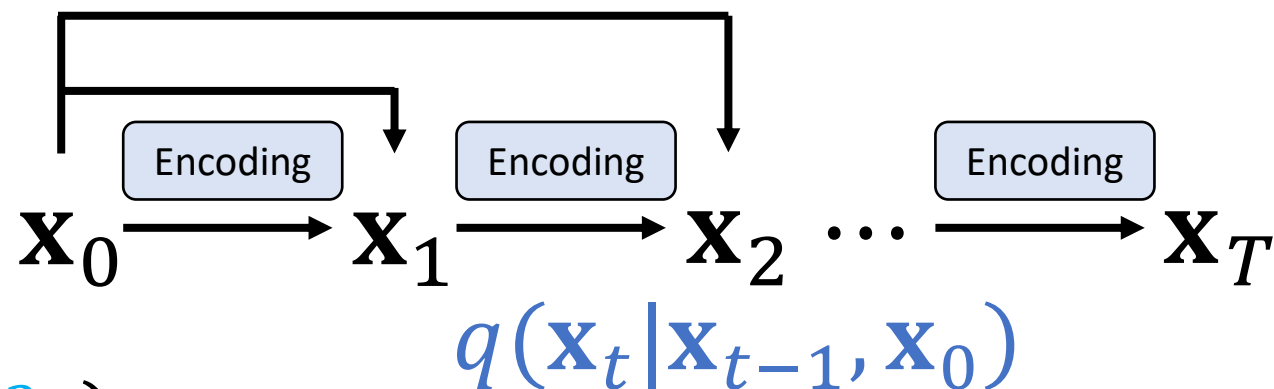
$$p(\mathbf{x}_{t-1} | \mathbf{x}_t) = \mathcal{N}(\mu_{\theta}(\mathbf{x}_t, \mathbf{x}_0), \sigma_t^2 I)$$

$$\mu_q(\mathbf{x}_t, \mathbf{x}_0) = \sqrt{\alpha_{t-1}} \mathbf{x}_0 + \sqrt{1 - \alpha_{t-1} - \sigma_t^2} \boldsymbol{\epsilon}$$

$$\mu_{\theta}(\mathbf{x}_t, \mathbf{x}_0) = \sqrt{\alpha_{t-1}} \hat{\mathbf{x}}_0 + \sqrt{1 - \alpha_{t-1} - \sigma_t^2} \hat{\boldsymbol{\epsilon}}$$



$$\sum_{t=2}^T \mathbb{E}_{q(\mathbf{x}_t|\mathbf{x}_0)} \left[w(t) \left[\left\| \hat{\epsilon}_{\theta}(\mathbf{x}_t, t) - \epsilon \right\|_2^2 \right] \right]$$



$$q(\mathbf{x}_{t-1} | \mathbf{x}_t, \mathbf{x}_0) = \mathcal{N}(\mu_q(\mathbf{x}_t, \mathbf{x}_0), \sigma_t^2 I)$$

$$p(\mathbf{x}_{t-1} | \mathbf{x}_t) = \mathcal{N}(\mu_{\theta}(\mathbf{x}_t, \mathbf{x}_0), \sigma_t^2 I)$$

DDIM sampler: Set $\sigma_t^2 = 0$

$$\mu_q(\mathbf{x}_t, \mathbf{x}_0) = \sqrt{\alpha_{t-1}} \mathbf{x}_0 + \sqrt{1 - \alpha_{t-1}} \epsilon$$

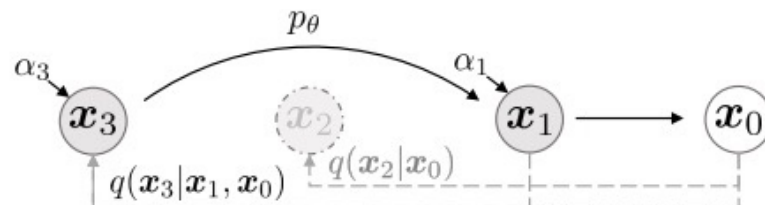
$$\mu_{\theta}(\mathbf{x}_t, \mathbf{x}_0) = \sqrt{\alpha_{t-1}} \hat{\mathbf{x}}_0 + \sqrt{1 - \alpha_{t-1}} \hat{\epsilon}$$

 Deterministic generative process!

	CIFAR10 (32×32)					CelebA (64×64)				
	10	20	50	100	1000	10	20	50	100	1000
DDIM	13.36	6.84	4.67	4.16	4.04	17.33	13.73	9.17	6.53	3.51
DDPM	367.43	133.37	32.72	9.99	3.17	299.71	183.83	71.71	45.20	3.26

DDIM reduces the sampling steps significantly

- Creates the outline of the sample after only 10 steps (DDPM needs hundreds)



sample timesteps

10

100



sample timesteps

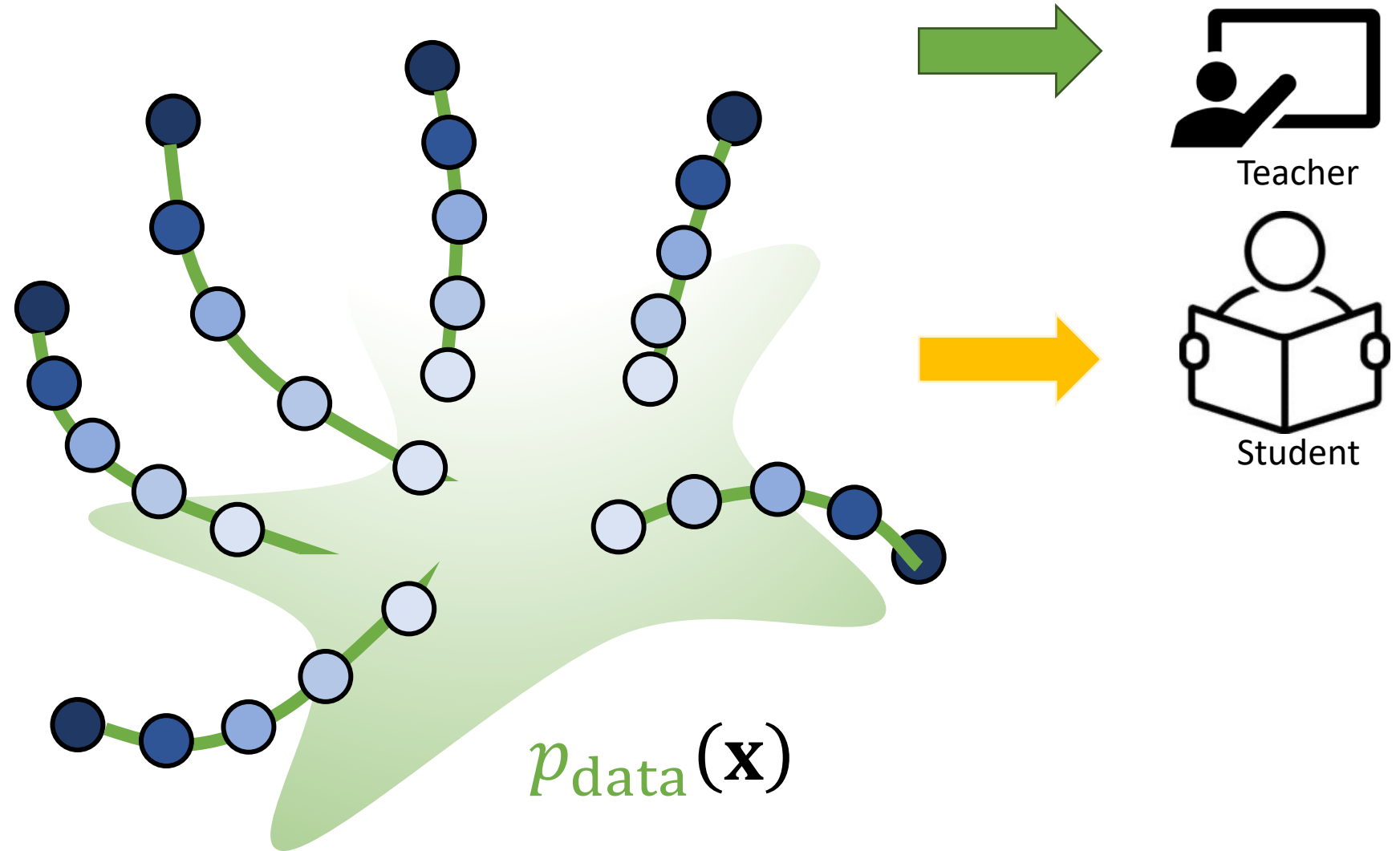
10

100



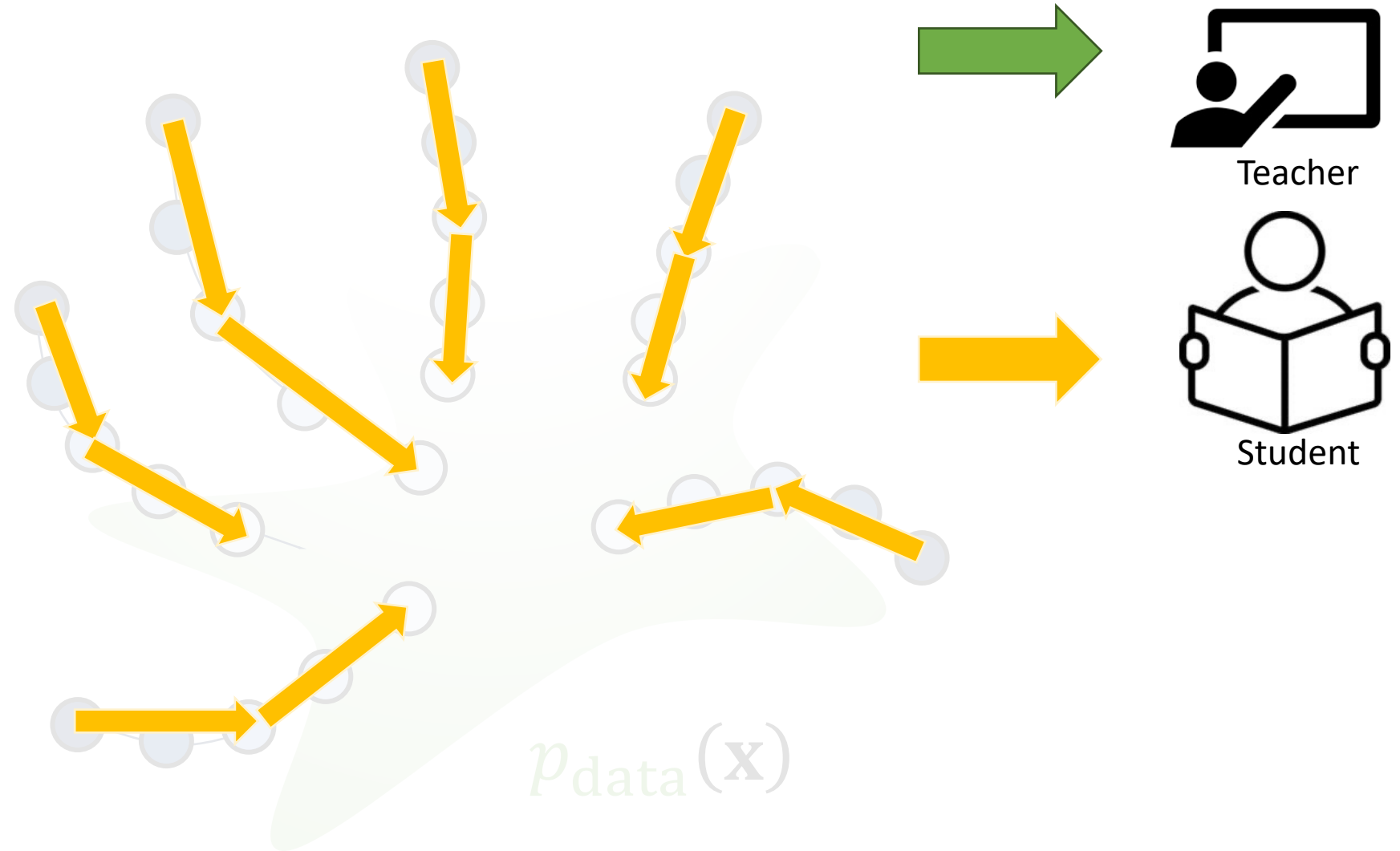


Progressive Distillation



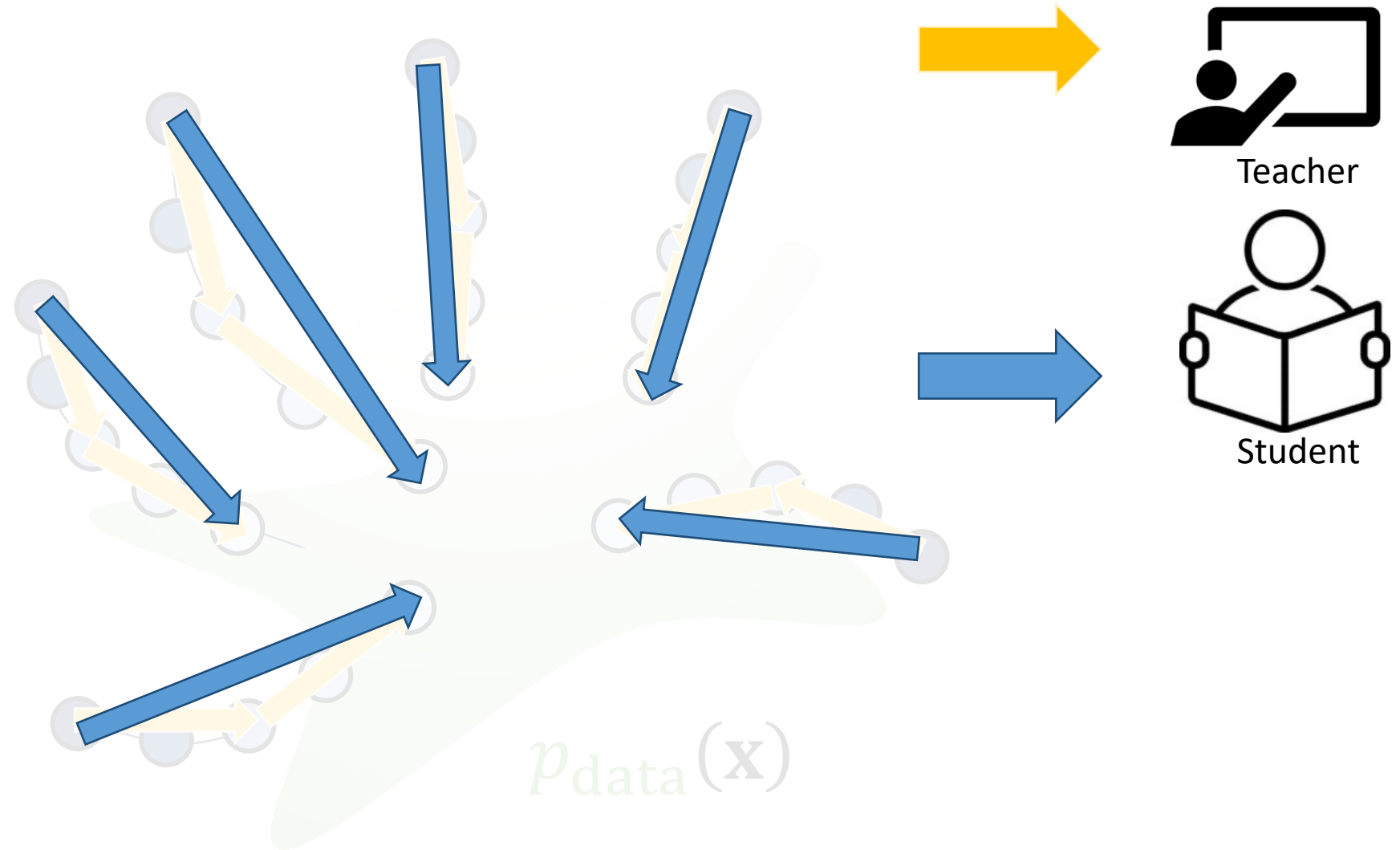


Progressive Distillation



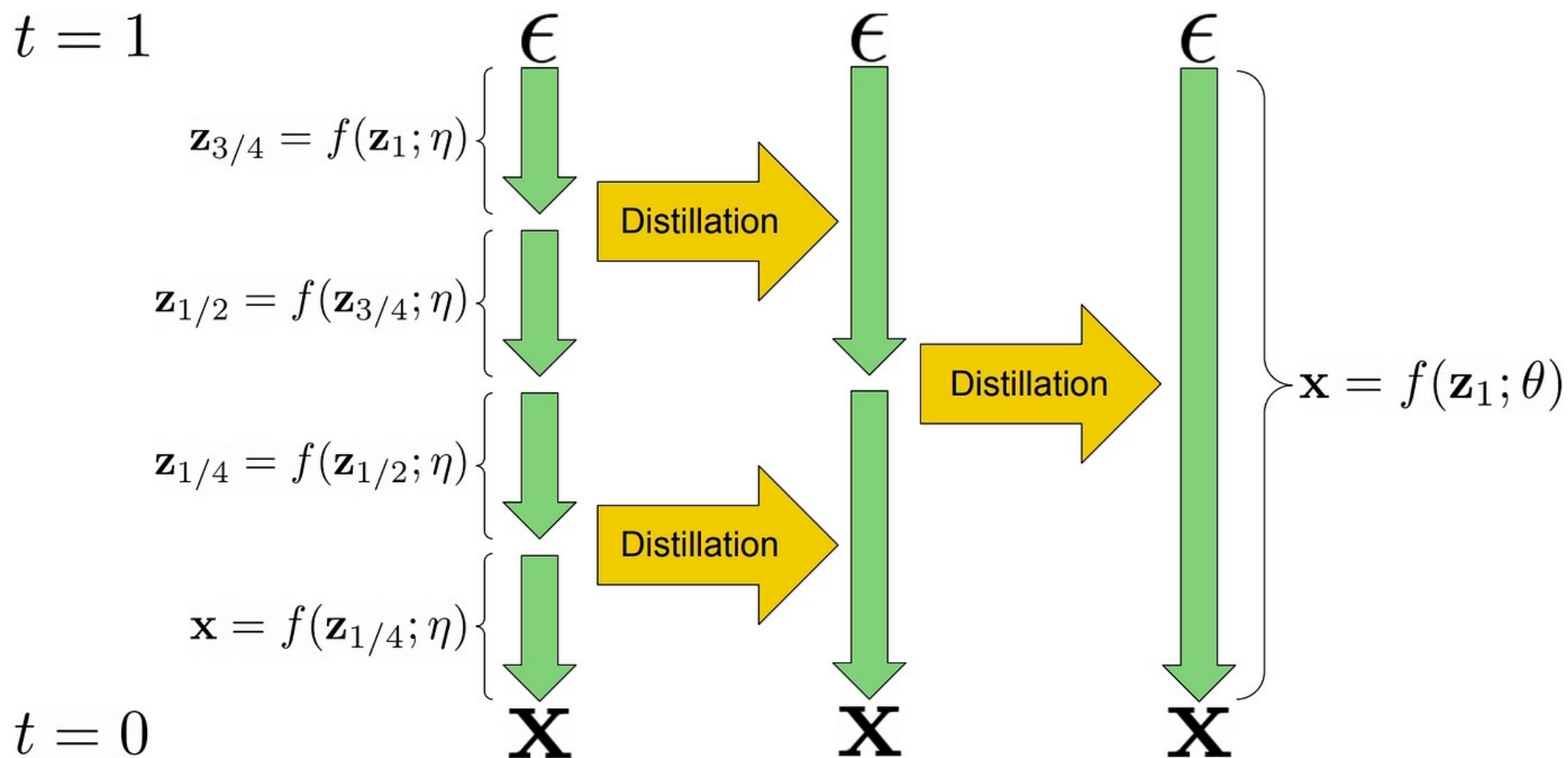


Progressive Distillation





Progressive Distillation



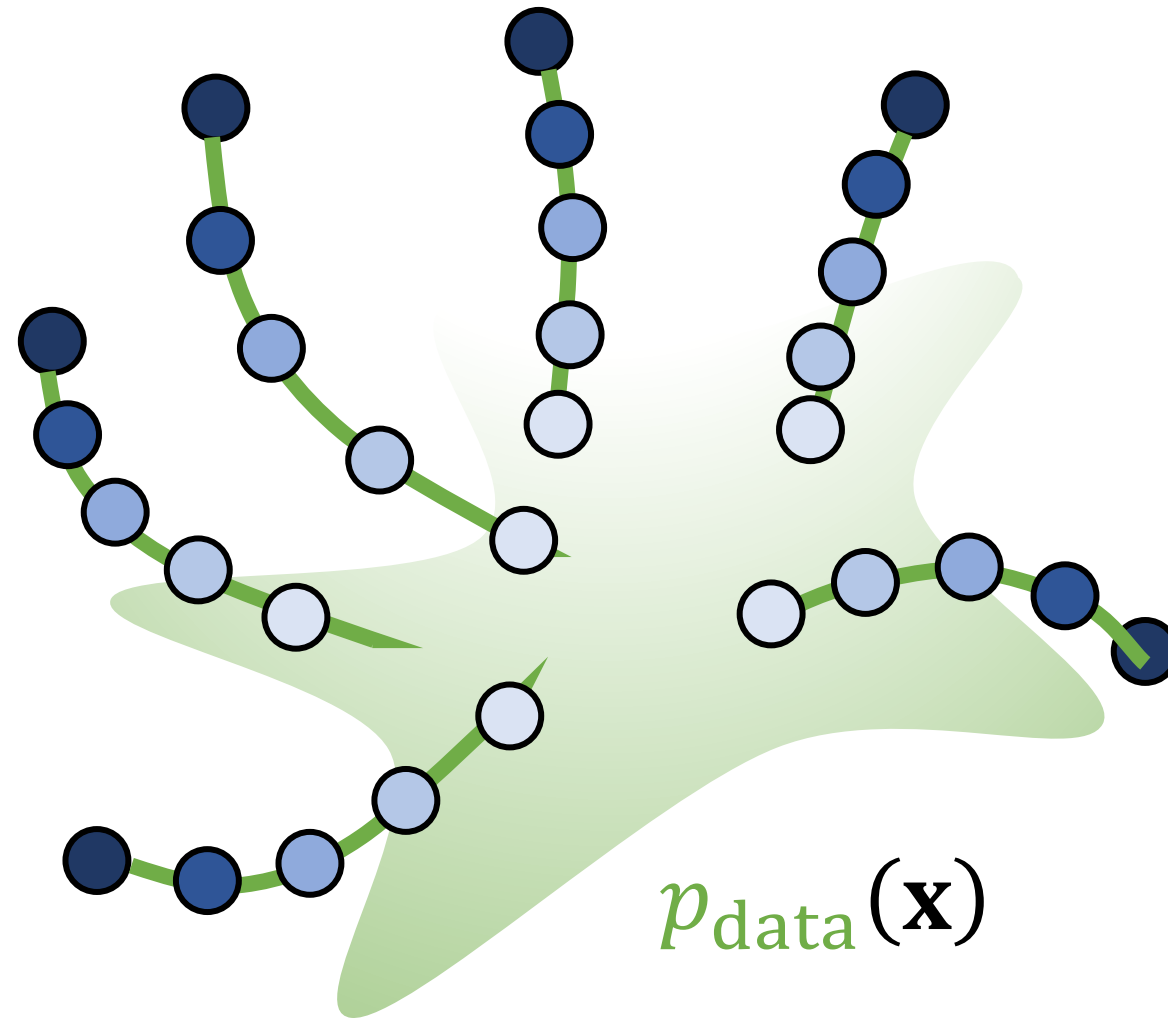
Progressive Distillation: Results



Figure 10: Random samples from our distilled LSUN bedrooms models, for fixed random seed and for varying number of sampling steps.



Guided Distillation

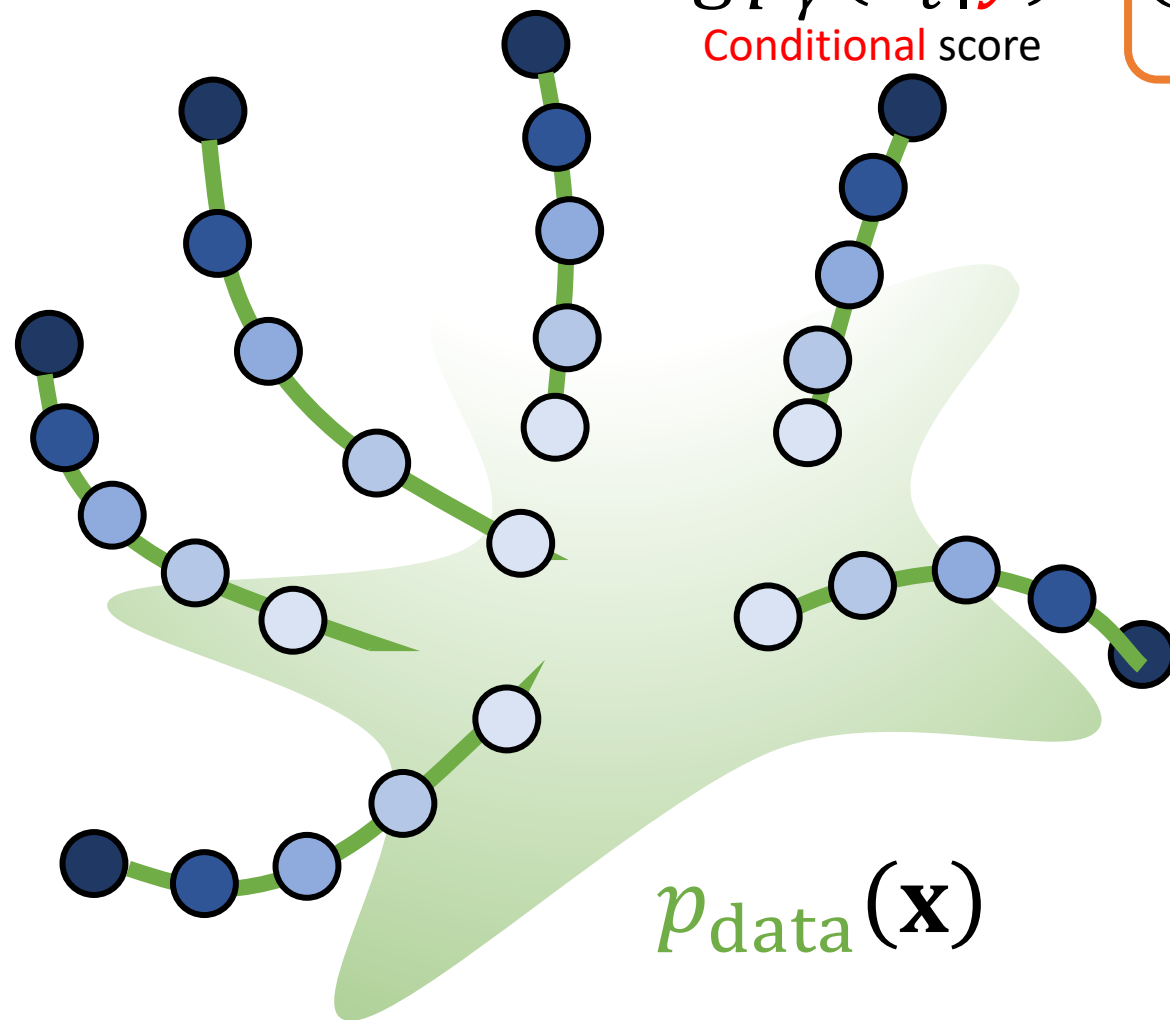
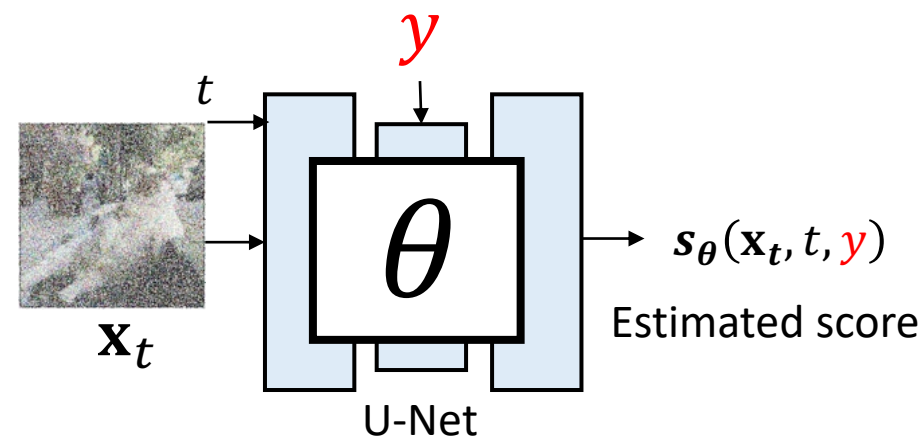
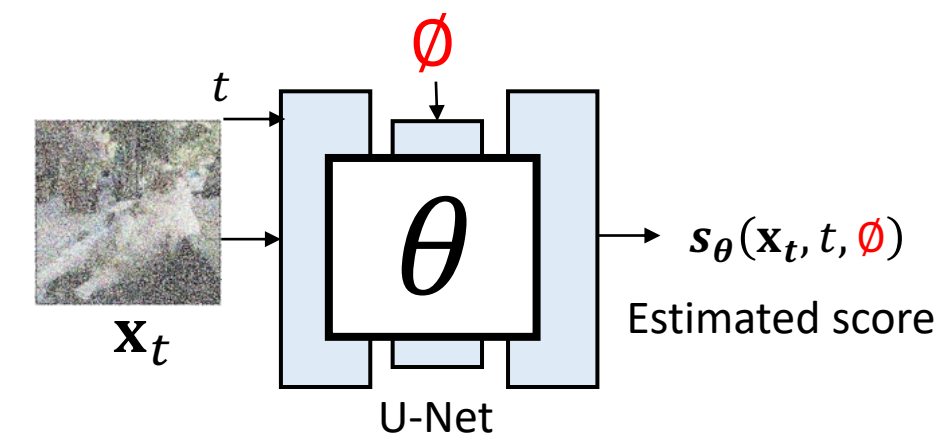




Guided Distillation

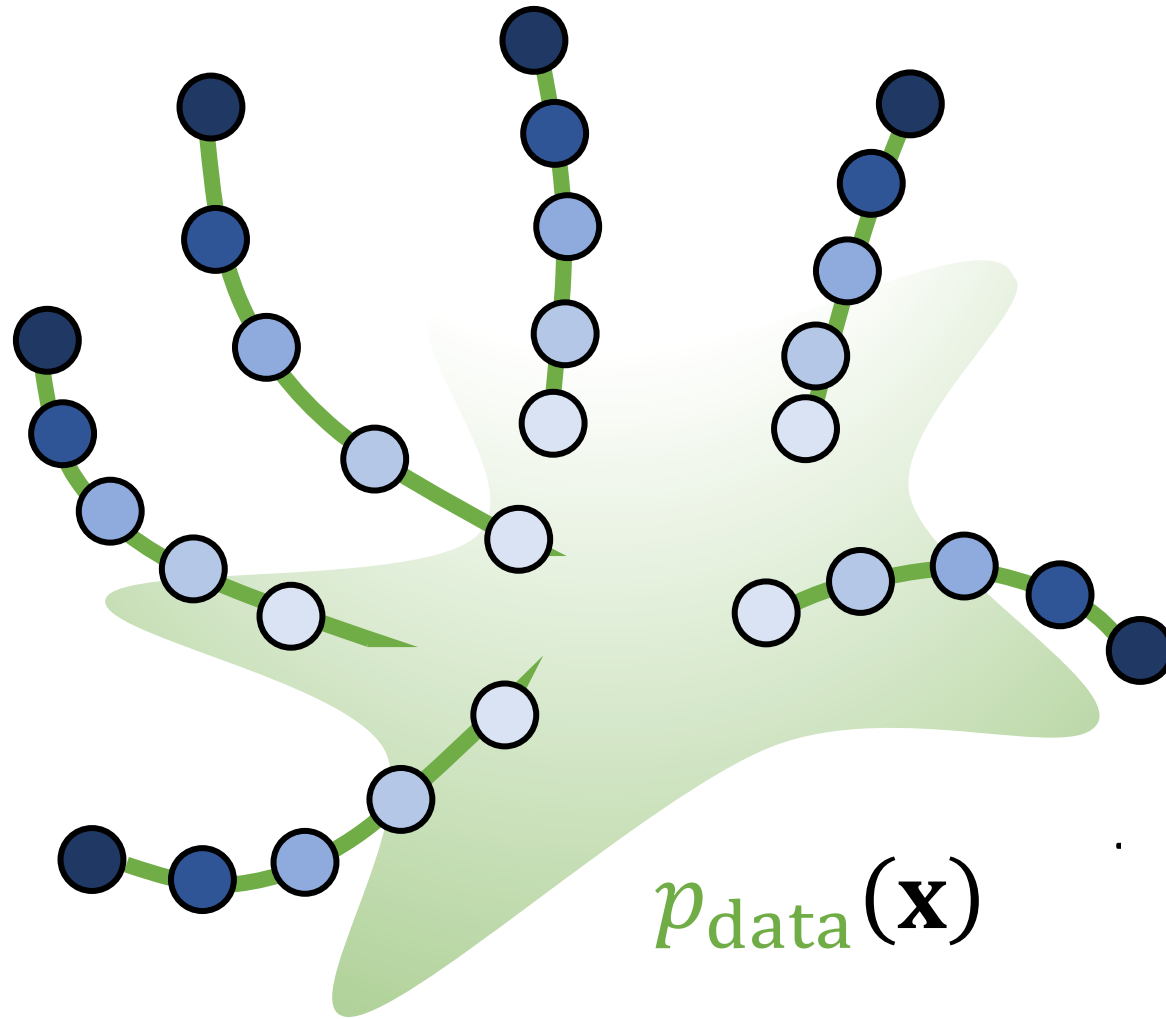
$$\nabla \log p_{\gamma}(\mathbf{x}_t | \mathbf{y}) = \underbrace{(1 - \gamma) \nabla \log p(\mathbf{x}_t)}_{\text{Unconditional score}} + \underbrace{\gamma \nabla \log p(\mathbf{x}_t | \mathbf{y})}_{\text{Conditional score}}$$

Conditional score





Guided Distillation



Classifier-free guidance
distillation



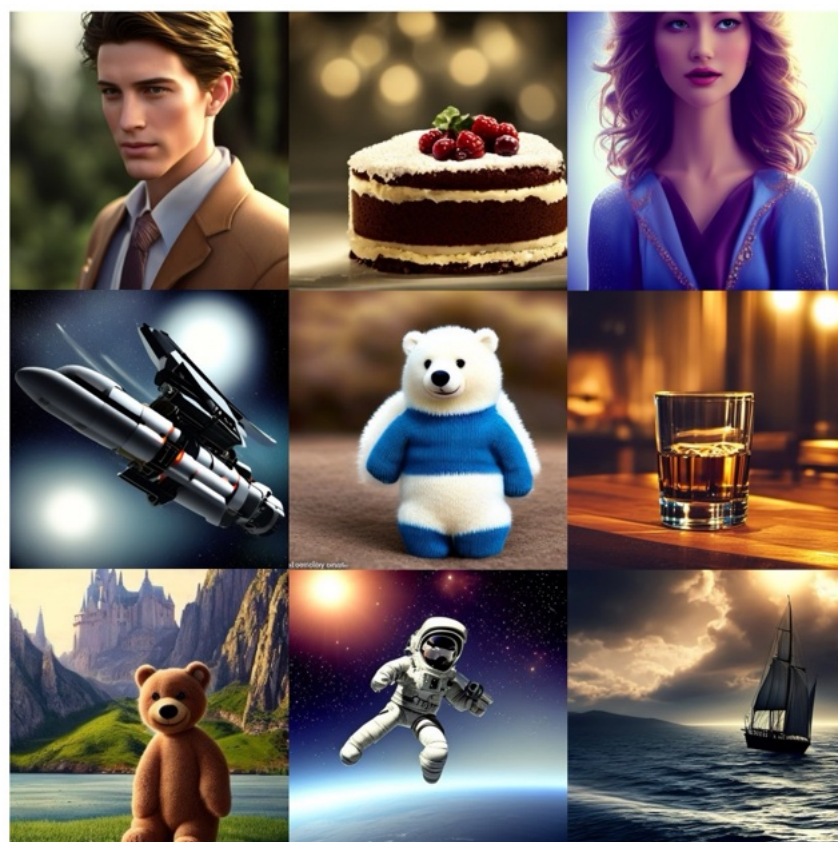
$p_{\text{data}}(\mathbf{x})$



Guided Distillation



(a) 2 denoising steps



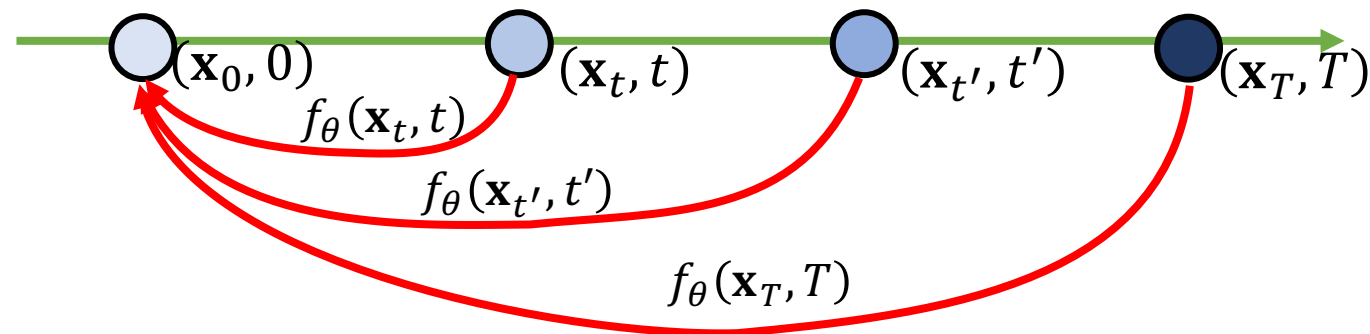
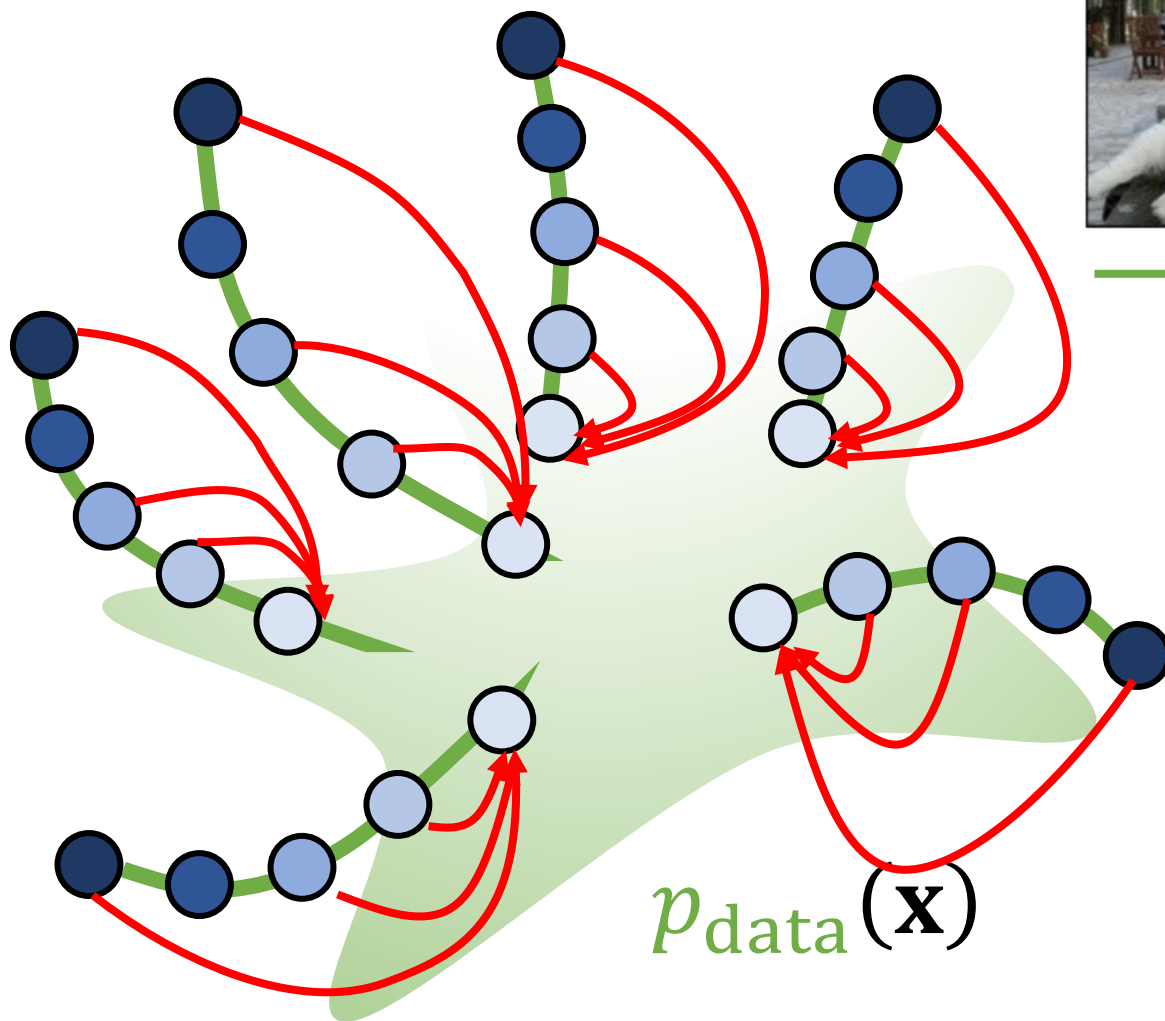
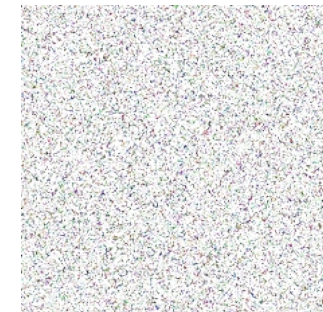
(b) 4 denoising steps



(c) 8 denoising steps



Consistency Models



$$\min_{\theta} d\left(f_{EMA}(\mathbf{x}_t, t), f_{\theta}(\mathbf{x}_{t'}, t')\right)$$

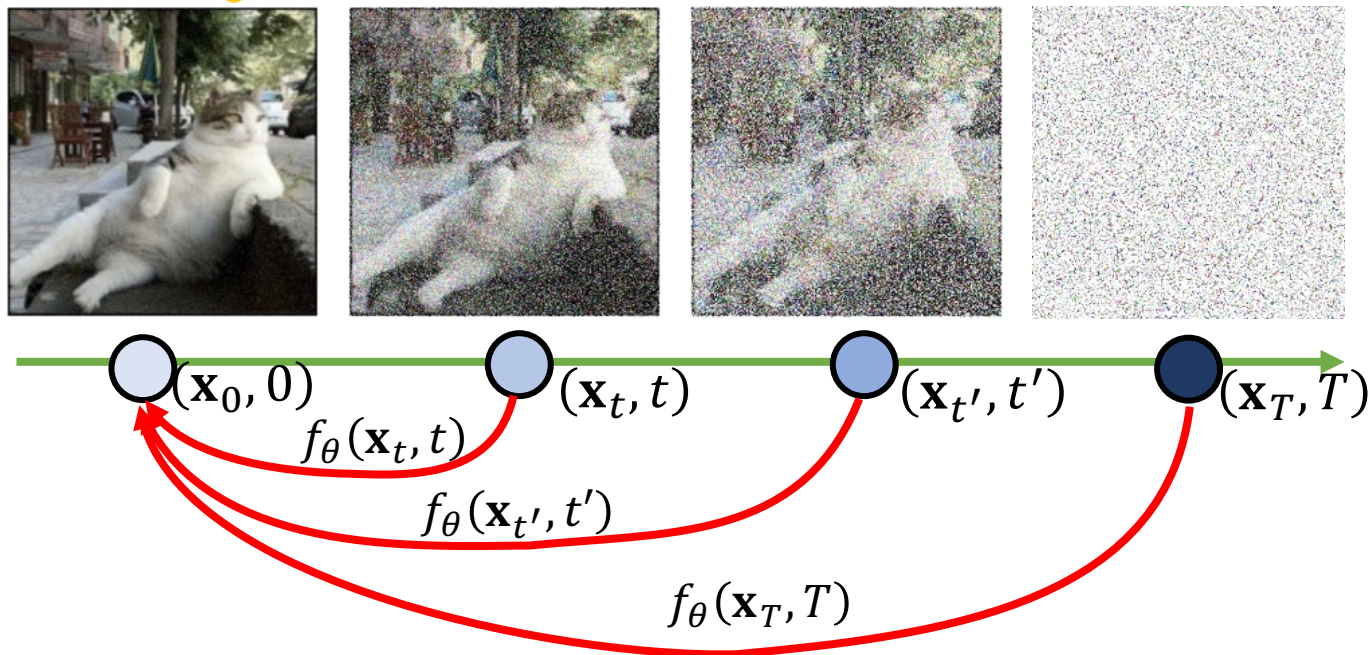
target network
(teacher)

online network
(student)

$p_{\text{data}}(\mathbf{X})$



Consistency Models



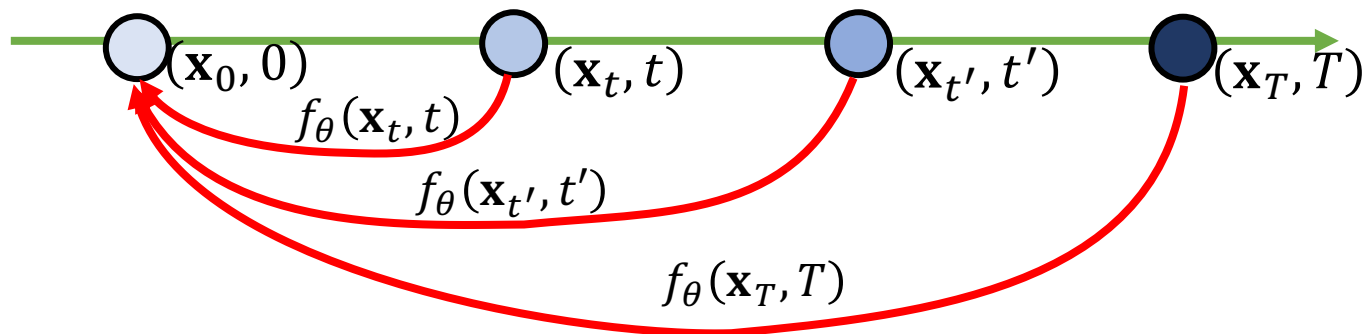
$$\min_{\theta} d\left(f_{EMA}(\mathbf{x}_t, t), f_{\theta}(\mathbf{x}_{t'}, t')\right)$$

target network
(teacher)

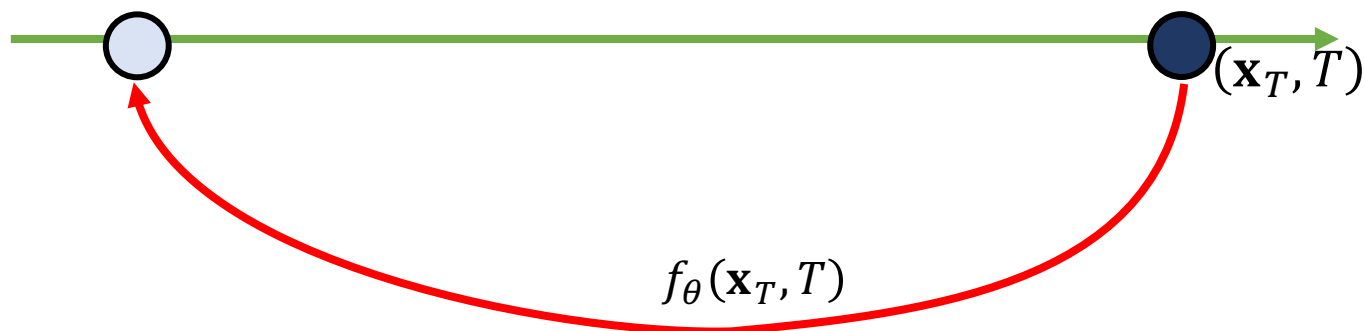
online network
(student)



Consistency Models

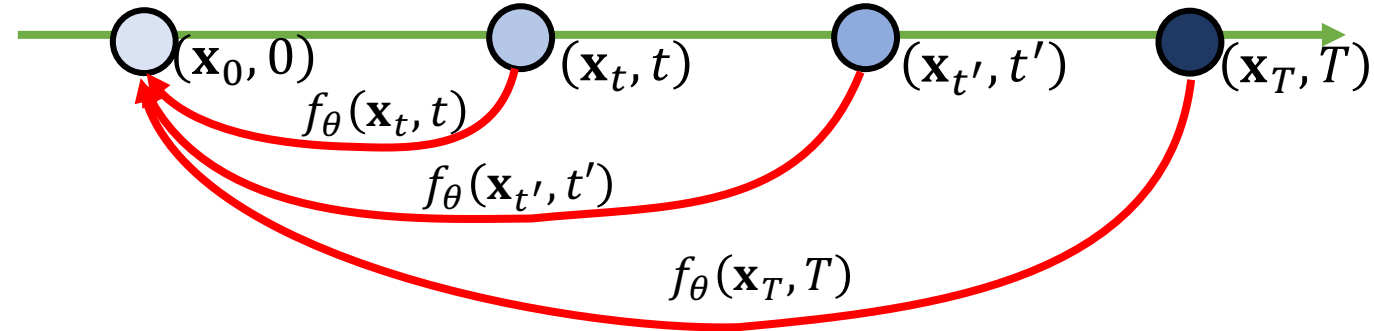


Single-step generation:

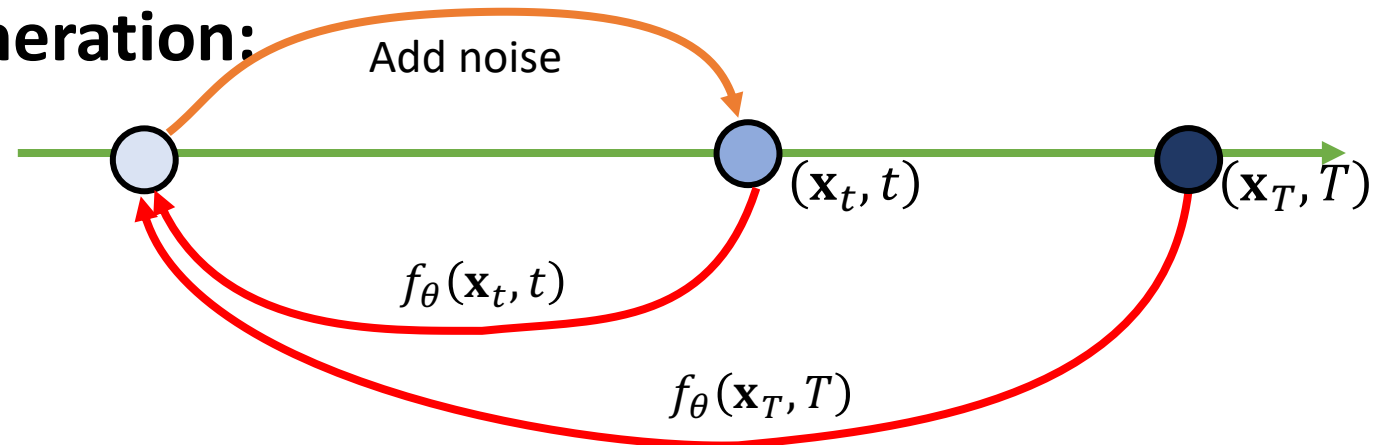




Consistency Models



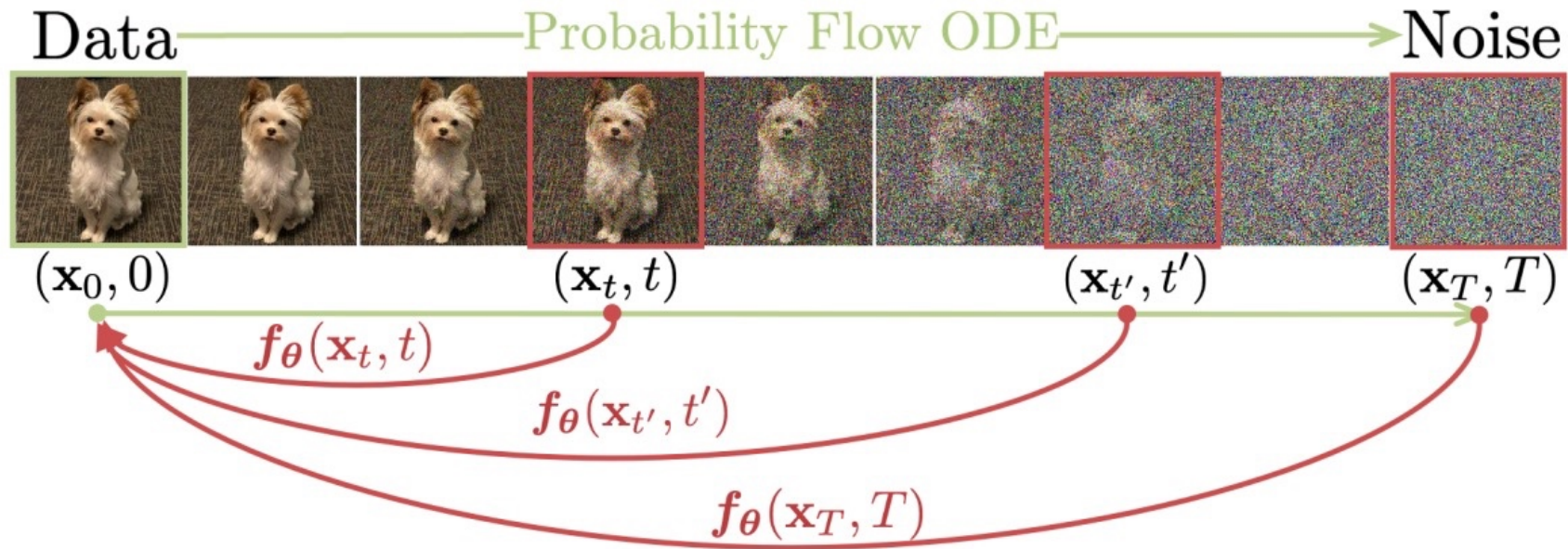
Multi-step generation:





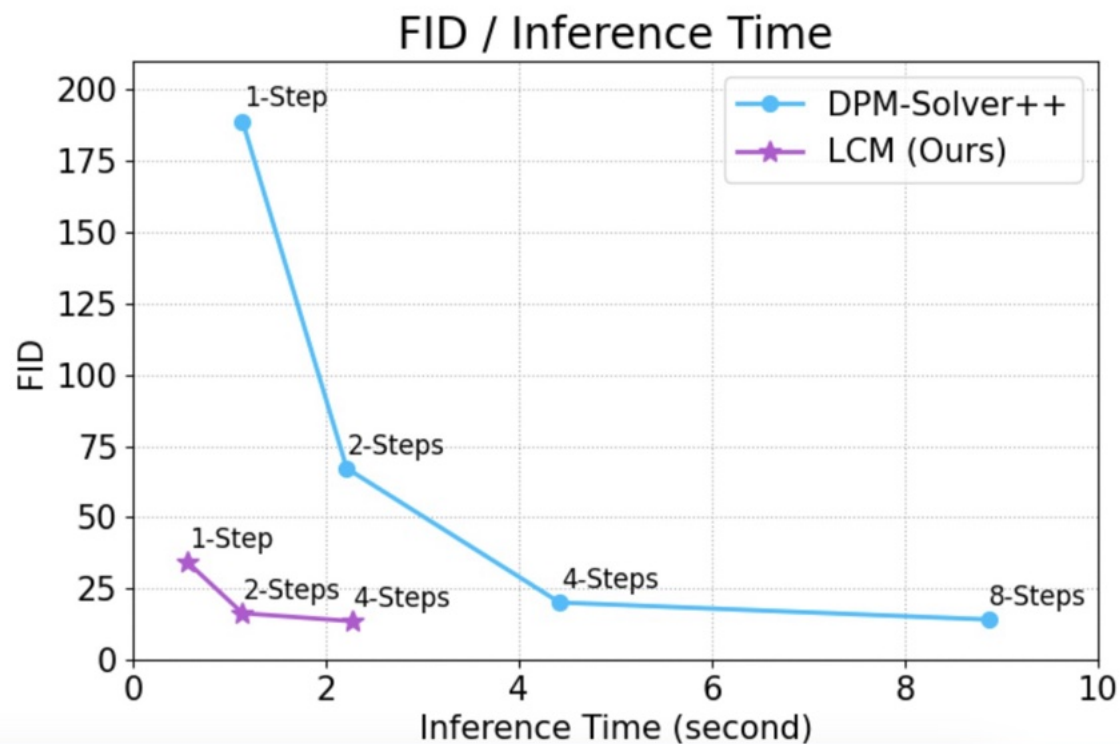
Latent Consistency Models

Consistency Models



Latent Consistency Models: combine the above idea with Latent Diffusion Models

Latent Consistency Models: Results



4-Steps Inference



2-Steps Inference

1-Step Inference



Latent Consistency Models





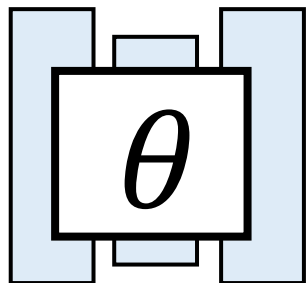
Latent Consistency Models + LoRA





Low-rank Adaptation: LoRA

[Hu et al. 2021]



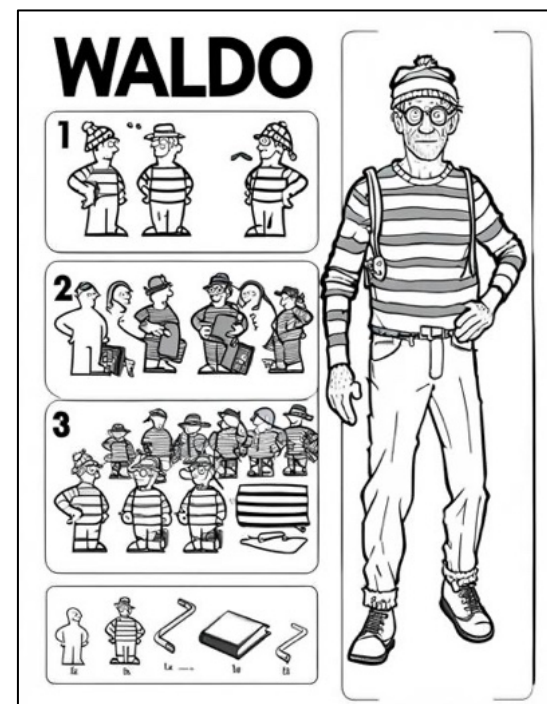
U-Net
Pretrained
diffusion model



PixelArt



Lego



IKEA instructions



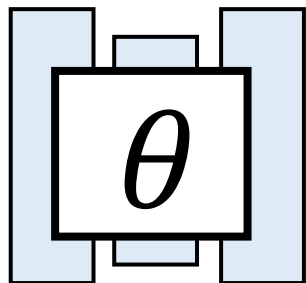
Anime



Low-rank Adaptation: LoRA



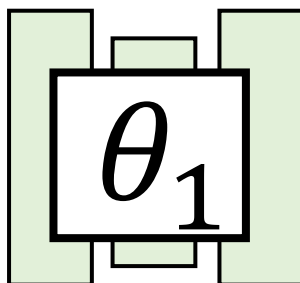
[Hu et al. 2021]



U-Net
**Pretrained
diffusion model**

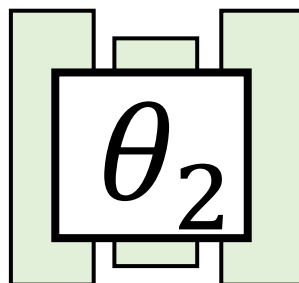
Computationally expensive

High storage requirement



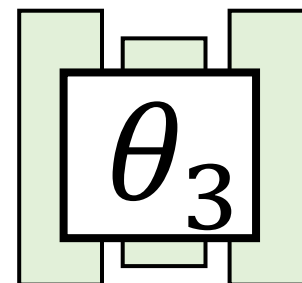
U-Net

PixelArt



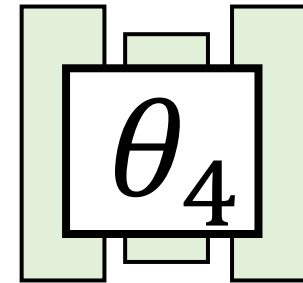
U-Net

Lego



U-Net

IKEA instructions



U-Net

Anime

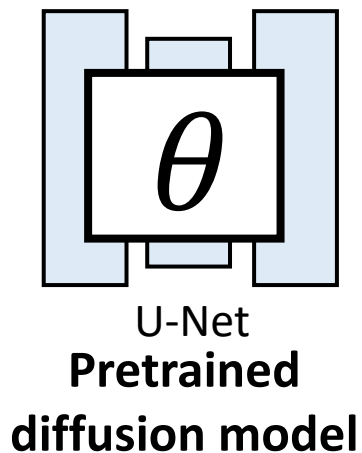


Low-rank Adaptation: LoRA



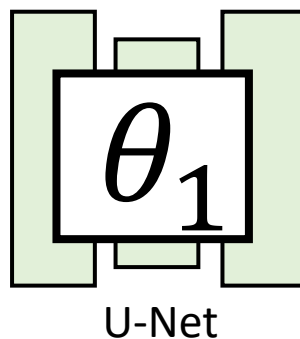
[Hu et al. 2021]

Finetuning cross-attention layers

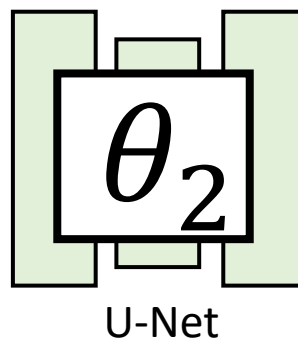


$$\begin{matrix} & k \\ & \text{---} \\ d & \begin{matrix} \text{---} \\ W_0 \\ \text{---} \end{matrix} \\ & \text{---} \end{matrix} + \begin{matrix} & k \\ & \text{---} \\ d & \begin{matrix} \text{---} \\ \Delta W \\ \text{---} \end{matrix} \\ & \text{---} \end{matrix}$$

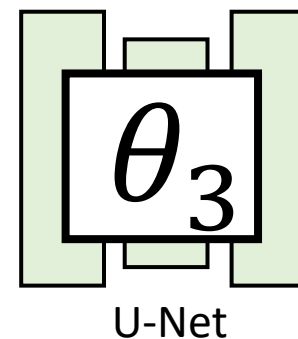
The diagram illustrates the LoRA adaptation process. It shows two matrices, W_0 and ΔW , both of size $d \times k$. The matrix W_0 is represented by a blue square with a blue face emoji at the bottom left, indicating it is the pretrained weight. The matrix ΔW is represented by a green square with a fire emoji at the bottom left, indicating it is the low-rank adaptation weight. The two matrices are added together to form the adapted weight.



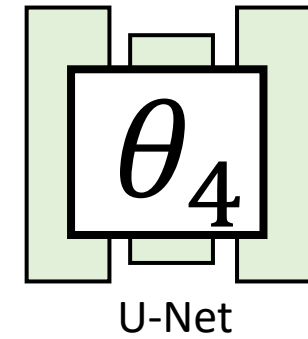
PixelArt



Lego



IKEA instructions



Anime

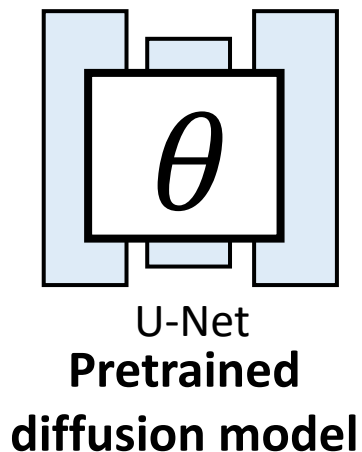


Low-rank Adaptation: LoRA



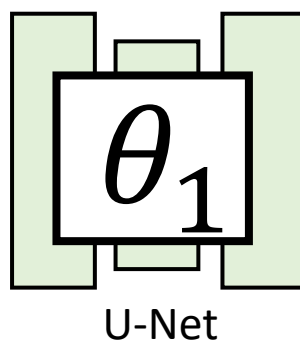
[Hu et al. 2021]

Finetuning cross-attention layers

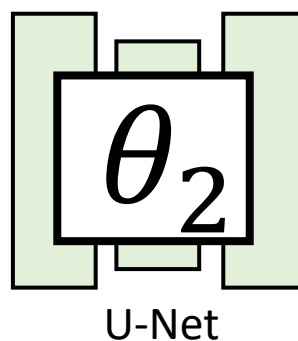


$$\begin{matrix} & k \\ & \text{---} \\ d & \begin{matrix} \text{---} \\ W_0 \\ \text{---} \end{matrix} \\ & \text{---} \end{matrix} + \begin{matrix} r \\ \text{---} \\ d & \begin{matrix} \text{---} \\ B \\ \text{---} \end{matrix} \\ & \text{---} \end{matrix} \begin{matrix} k \\ \text{---} \\ r & \begin{matrix} \text{---} \\ A \\ \text{---} \end{matrix} \\ & \text{---} \end{matrix}$$

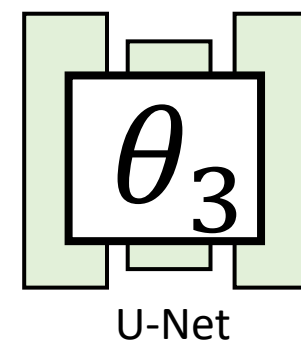
The diagram illustrates the LoRA adaptation process. It shows a large blue square matrix W_0 of size $d \times k$ with a blue face emoji at the bottom left. This is added to a product of two smaller matrices: a vertical green rectangle B of size $d \times r$ with a fire emoji at the bottom, and a horizontal green rectangle A of size $r \times k$ with a fire emoji at the right. The dimensions d , k , and r are labeled near their respective matrices.



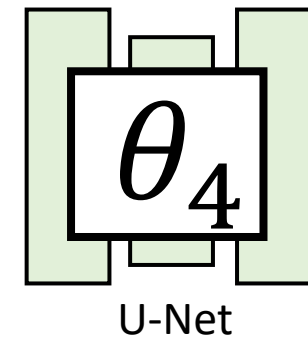
PixelArt



Lego



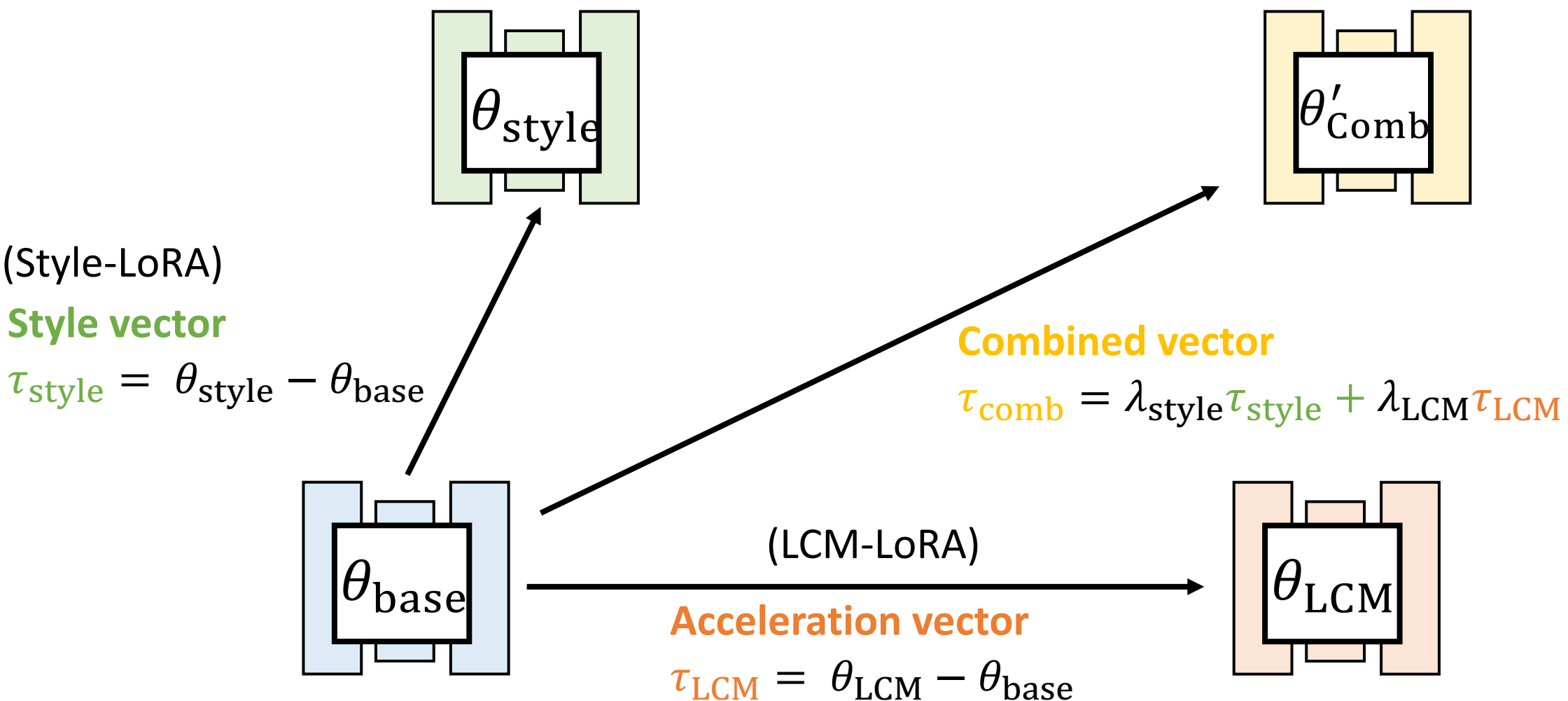
IKEA instructions



Anime



Latent Consistency Models + LoRA





Latent Consistency Models + LoRA



**LCM-LoRA-
SD-V1.5**



**LCM-LoRA-
SDXL**



**LCM-LoRA-
SSD-1B**

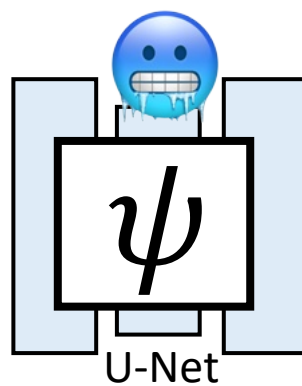
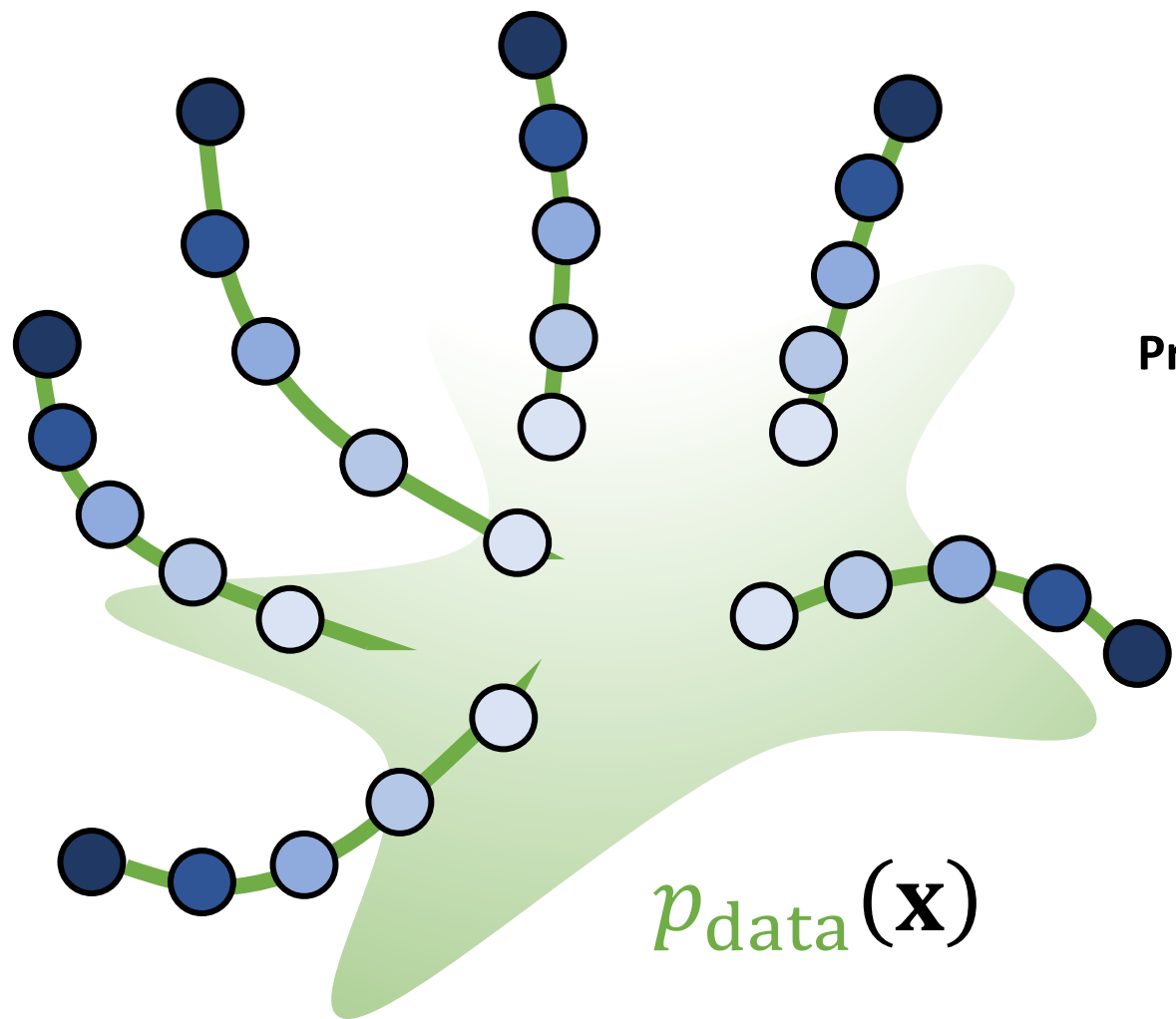


Slide from Jia-Bin Huang

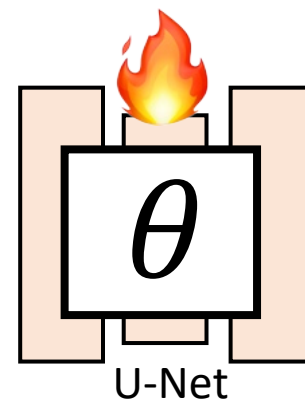
LCM-LoRA [Luo et al. 2023]



Adversarial Diffusion Distillation



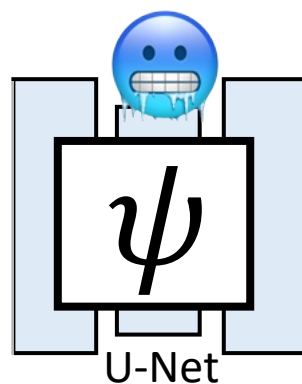
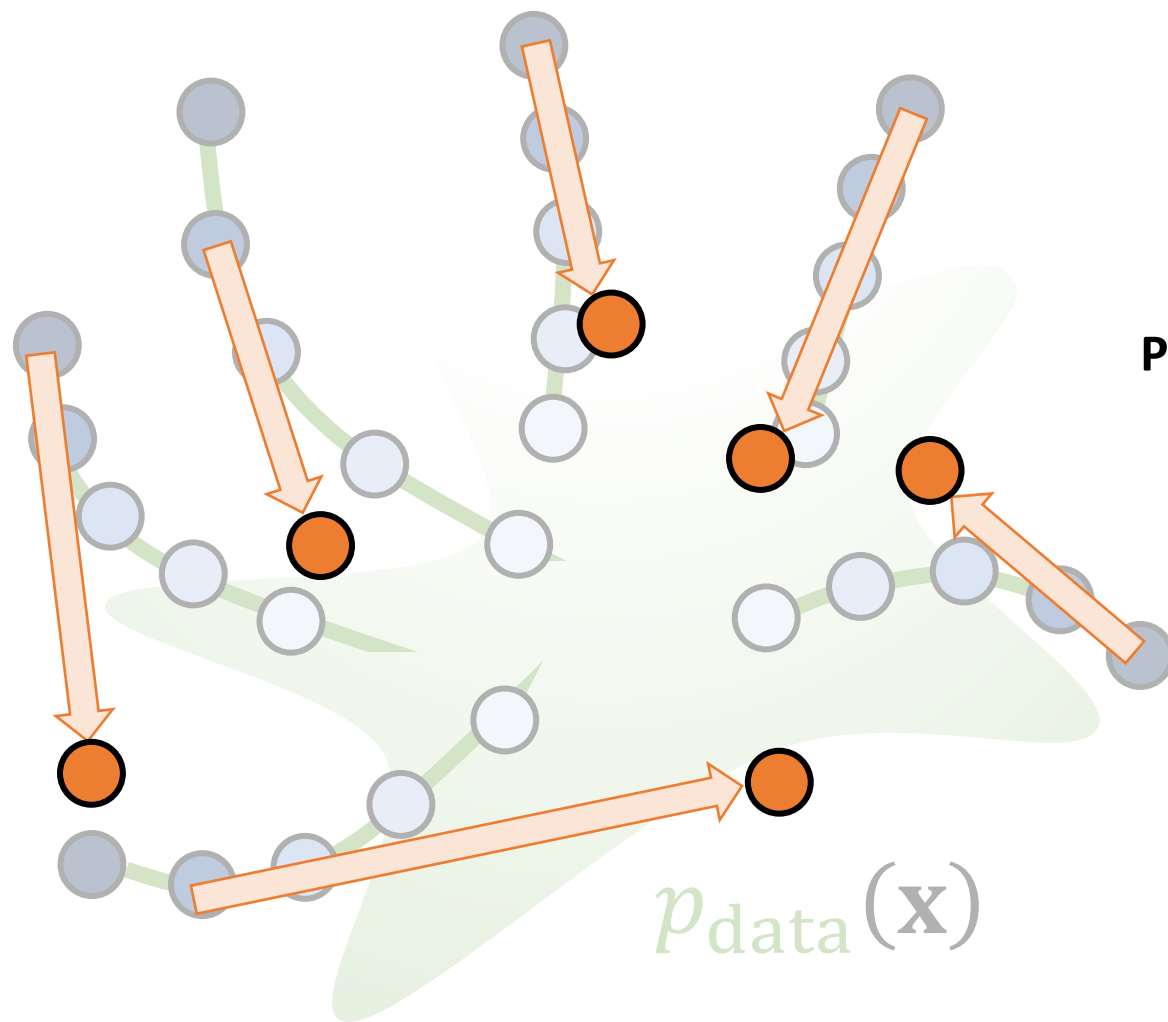
Pretrained model



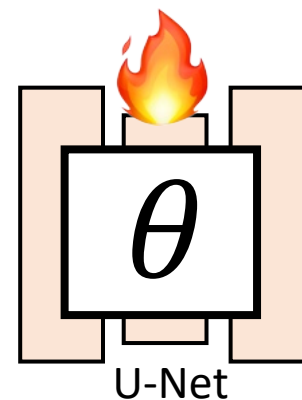
Student model



Adversarial Diffusion Distillation



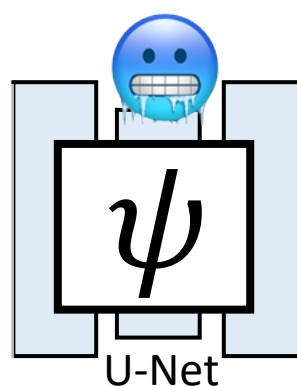
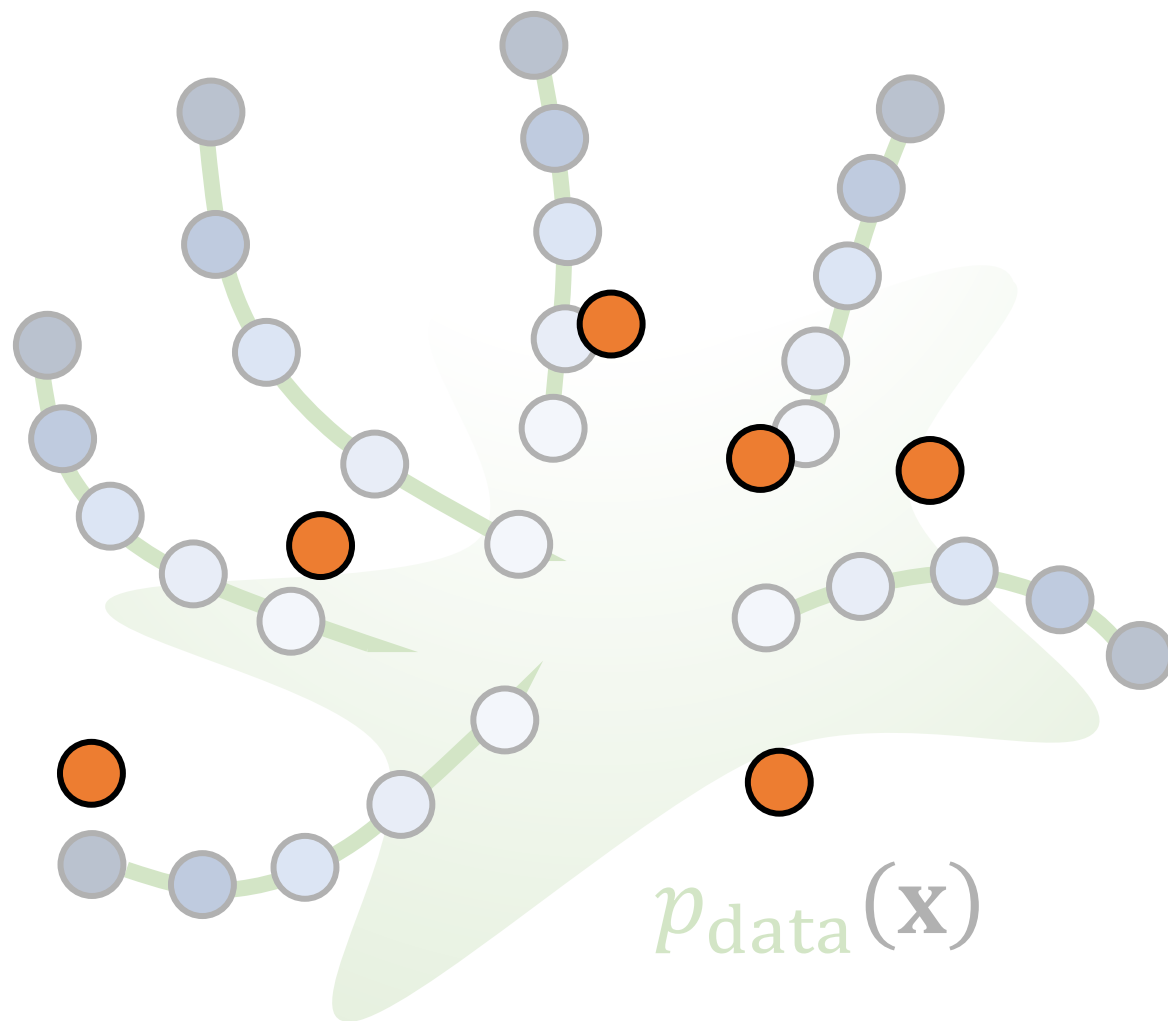
Pretrained model



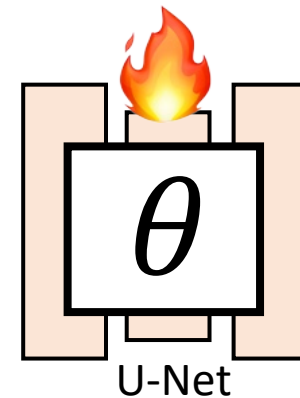
Student model



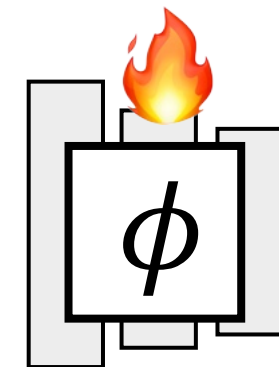
Adversarial Diffusion Distillation



Teacher model



Student model



Discriminator

Problem:

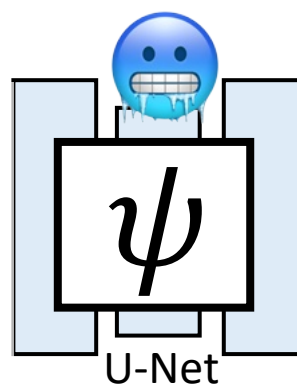
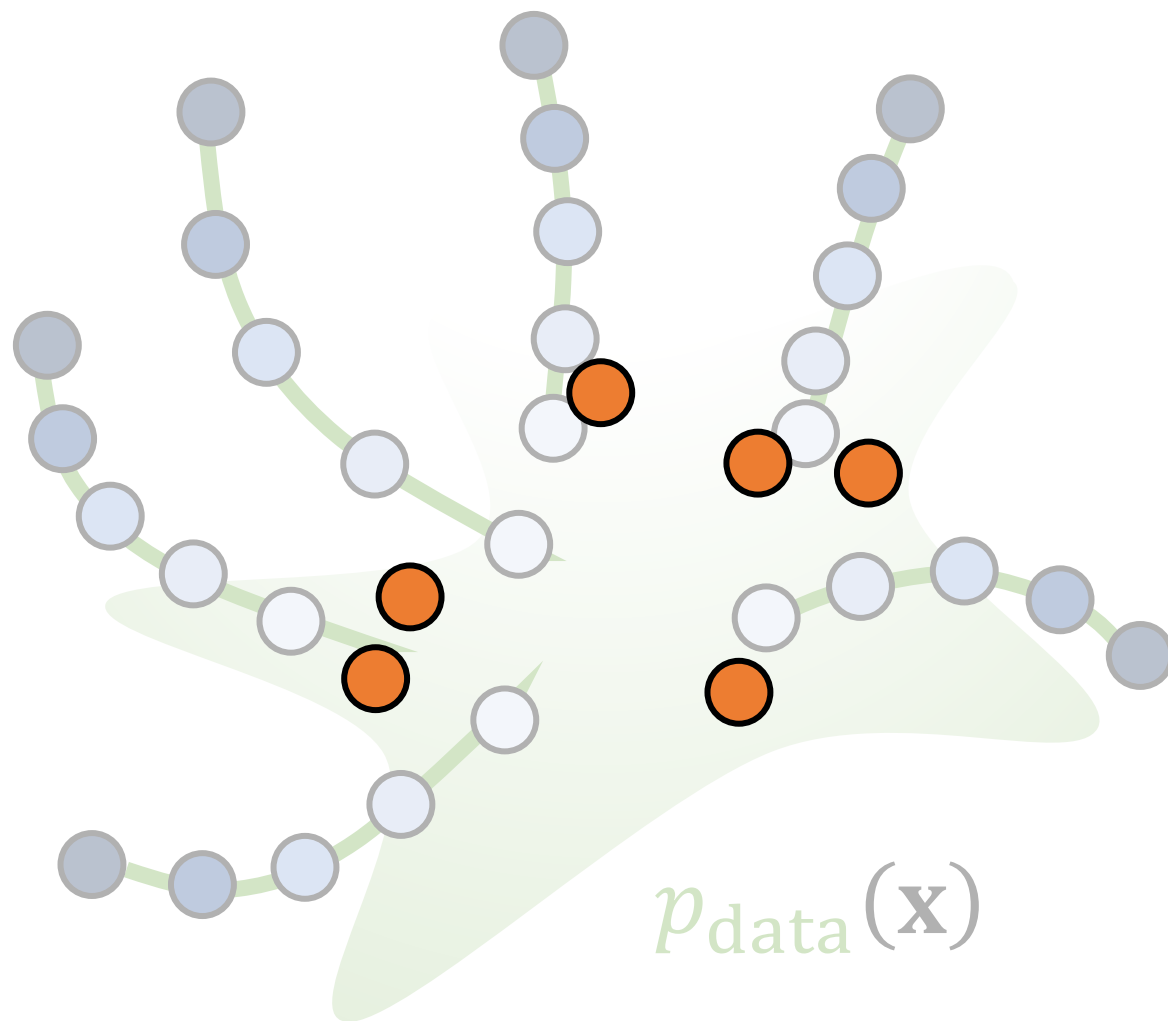
● Denoised image predicted by the teacher:
blurry

Idea:

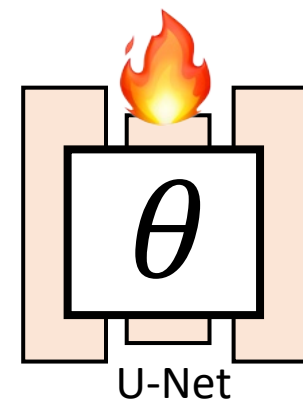
Use both adversarial loss and
score distillation loss



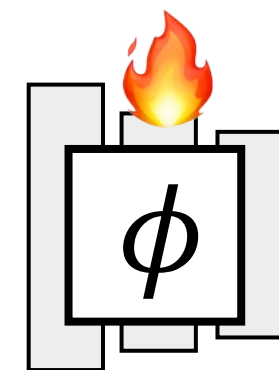
Adversarial Diffusion Distillation



Teacher model



Student model



Discriminator

Problem:

● Denoised image predicted by the teacher:
blurry

Idea:

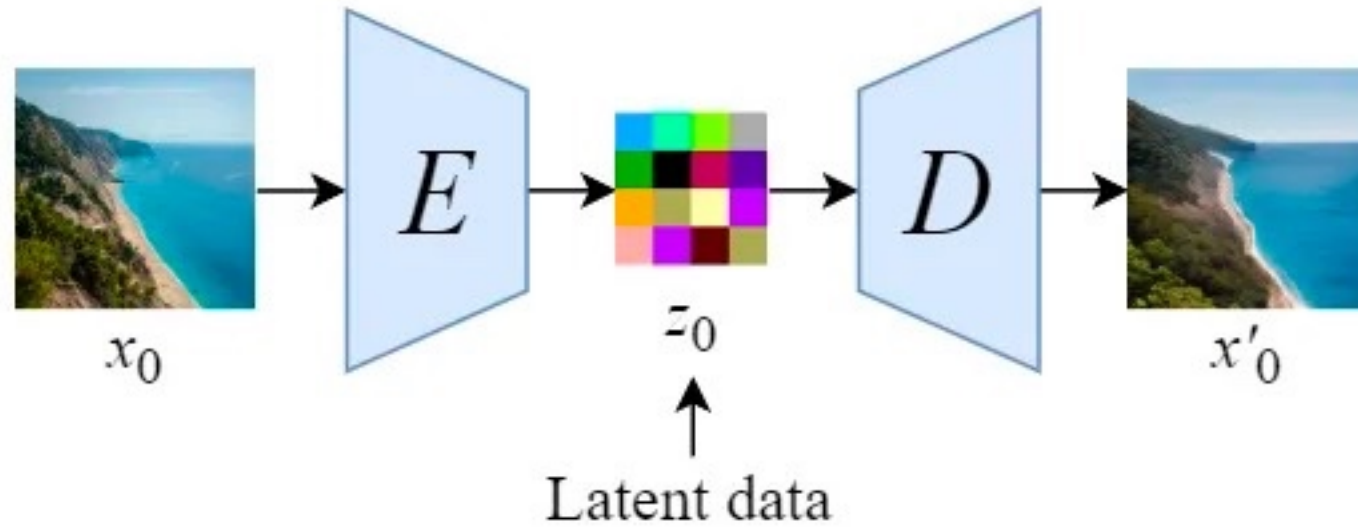
Use both adversarial loss and
score distillation loss





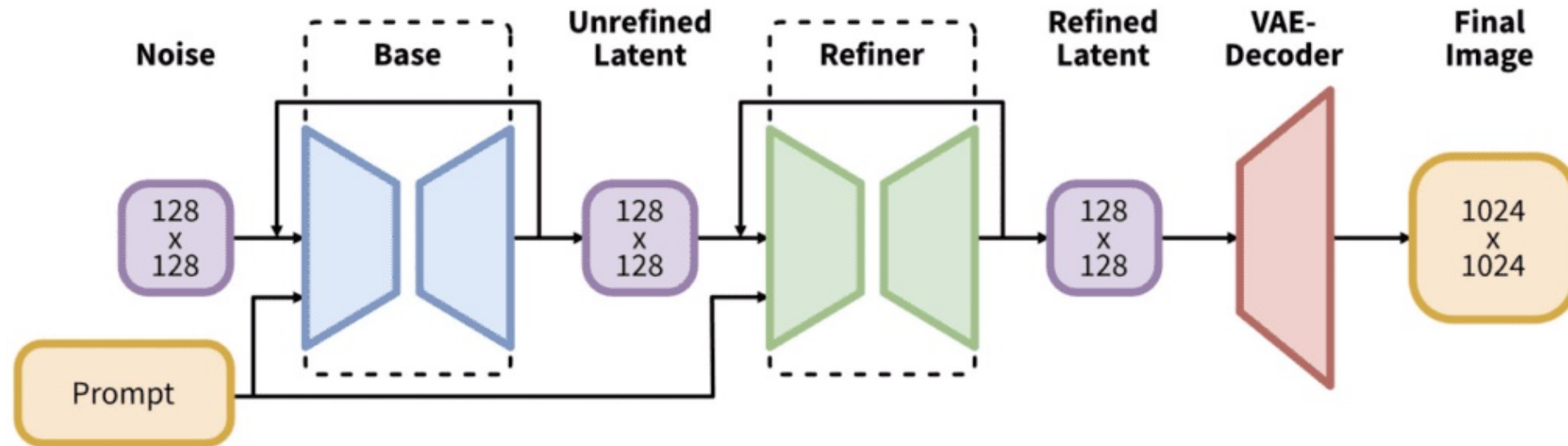
Recent Improvements

Recall Stable Diffusion (SD v1.4, SD v1.5, SD v2.1)





Improved SDXL pipeline

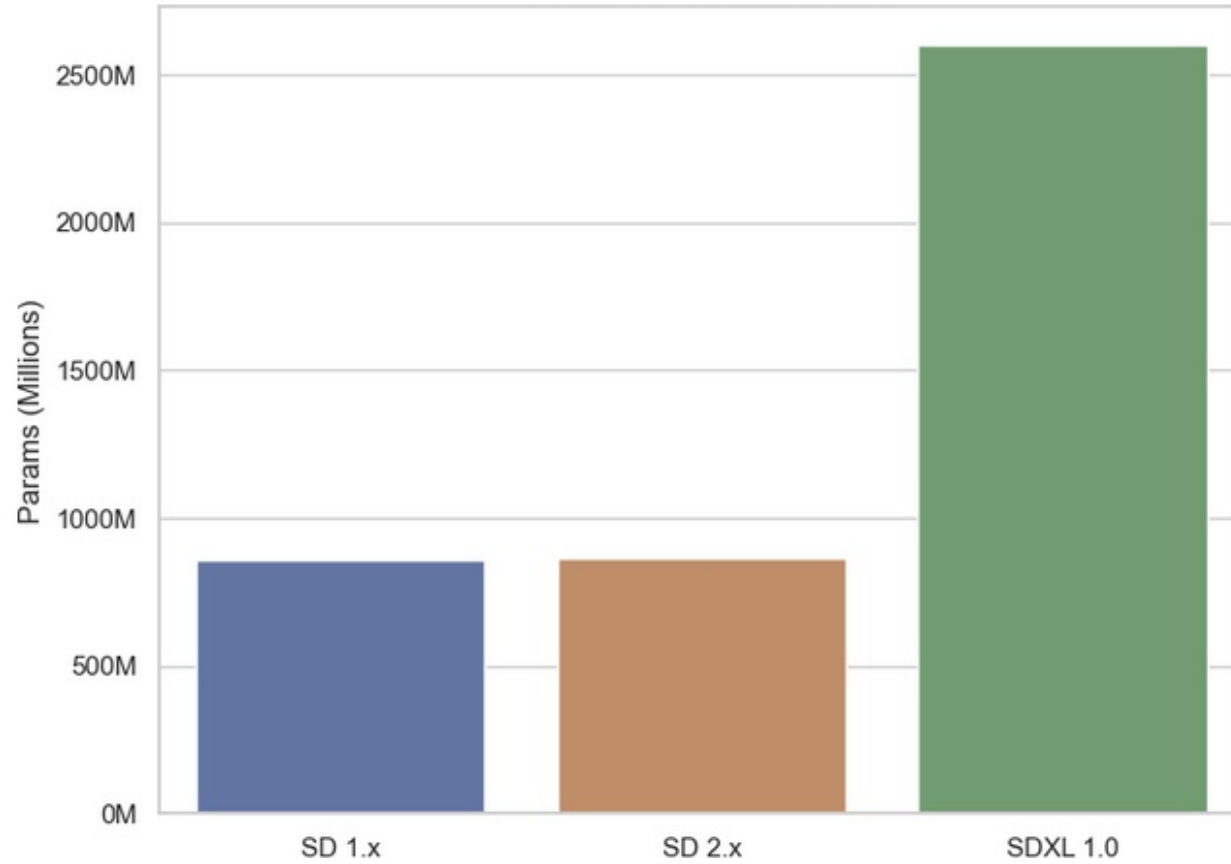


- Separate refiner model
- Two text-encoders
- Bigger U-net with more attention blocks and higher number of parameters

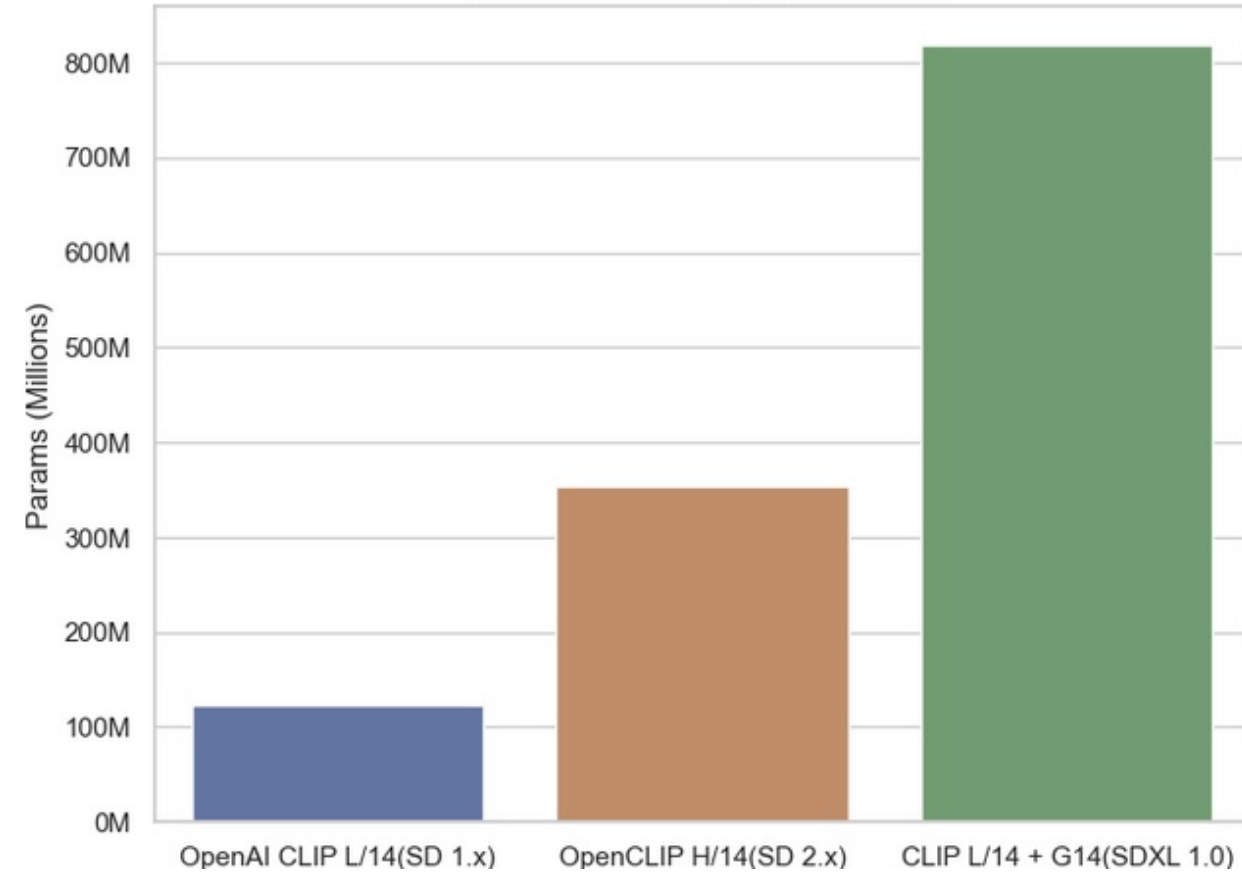


SDXL

Number of UNeT Parameters



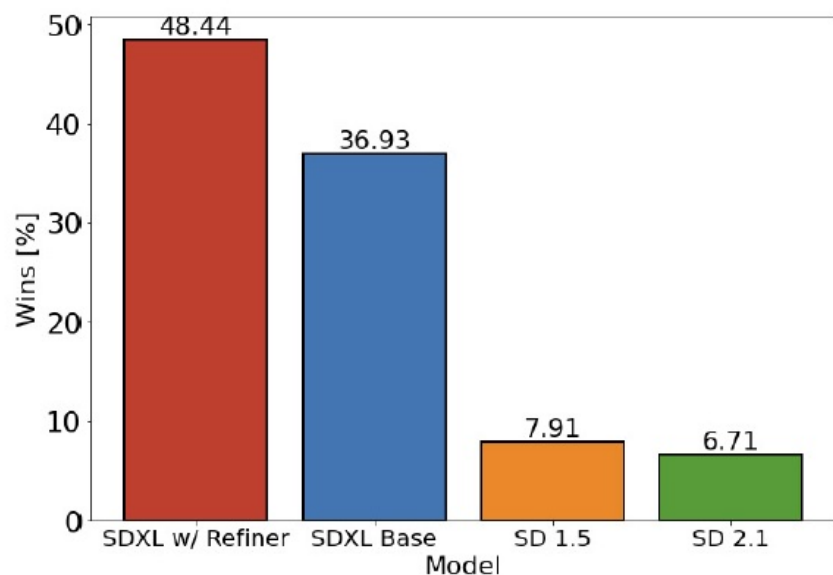
Number of Text Encoder Parameters



<https://towardsdatascience.com/the-arrival-of-sdxl-1-0-4e739d5cc6c7>



SDXL: Improvements in generation quality



Comparing user preferences
between SDXL and
previous models.

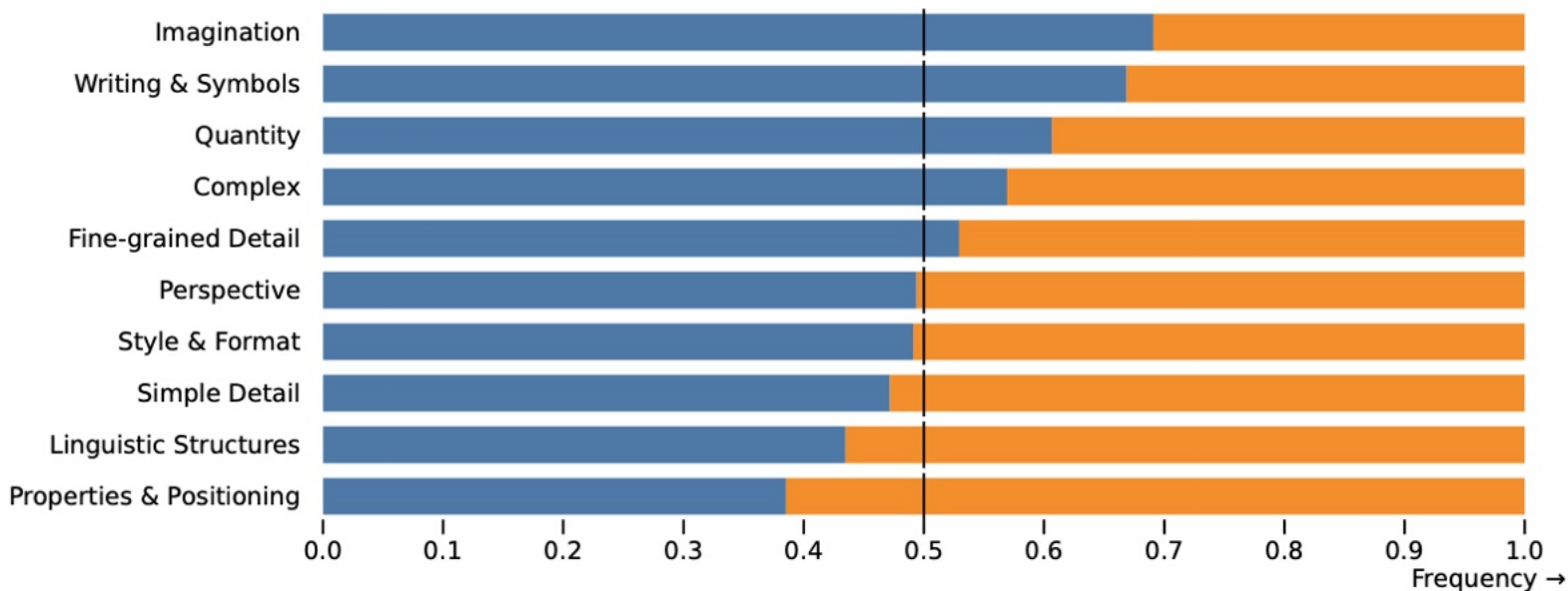


Figure 11: Preference comparisons of *SDXL* (with refinement model) to *Midjourney V5.1* on complex prompts. *SDXL* either outperforms or is statistically equal to *Midjourney V5.1* in 7 out of 10 categories.

SDXL: Results



Figure 4: Comparison of the output of *SDXL* with previous versions of *Stable Diffusion*. For each prompt, we show 3 random samples of the respective model for 50 steps of the DDIM sampler [46] and cfg-scale 8.0 [13]. Additional samples in Fig. 14.

SDXL: Results



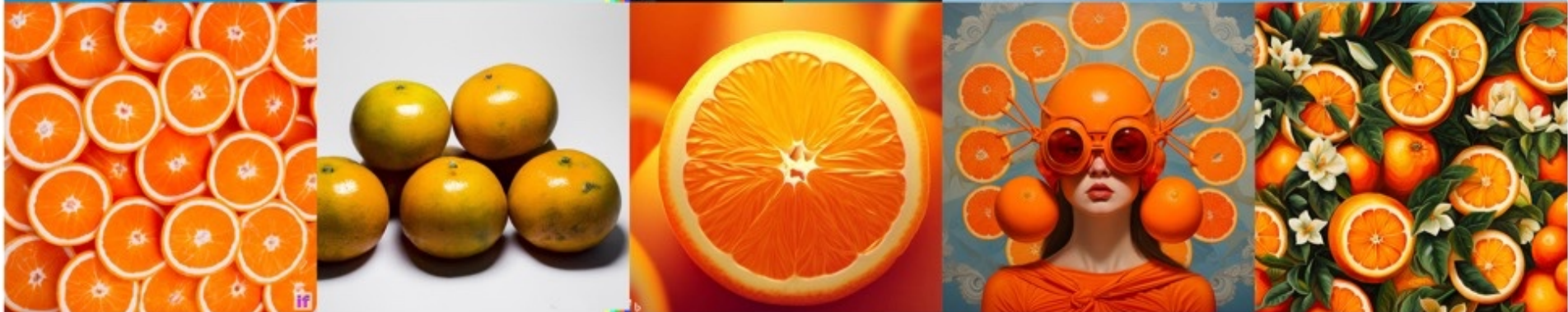
cat patting a crystal ball
with the number 7 written
on it in black marker



photograph of
a red ball on
a blue cube



orange



DEEPLOYD IF

DALLE-2

BING IMAGE CREATOR

MIDJOURNEY v5.2

SDXL v0.9

SD3



Prompt: A beautiful painting of flowing colors and styles forming the words "The SD3 research paper is here!",
the background is speckled with drops and splashes of paint

<https://stability.ai/news/stable-diffusion-3-research-paper>

SD3: Results



Prompt: Translucent pig, inside is a smaller pig.



Prompt: A massive alien space ship that is shaped like a pretzel.



Prompt: A kangaroo holding a beer, wearing ski goggles and passionately singing silly songs.



Prompt: An entire universe inside a bottle sitting on the shelf at walmart on sale.



Prompt: A cheeseburger with juicy beef patties and melted cheese sits on top of a toilet that looks like a



Prompt: This dreamlike digital art captures a vibrant, kaleidoscopic bird in a lush rainforest



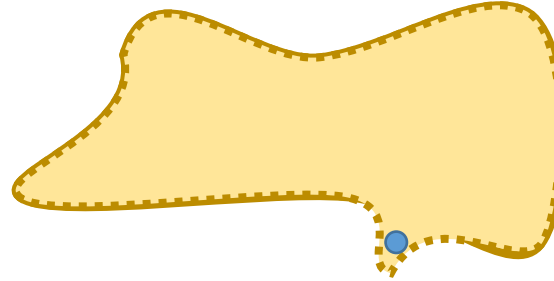
Prompt: A car made out of vegetables.



Prompt: Heat death of the universe line art

Local Customization of Diffusion Model

Diffusion Model Image Space



Input images



in the Acropolis



swimming



sleeping



in a doghouse

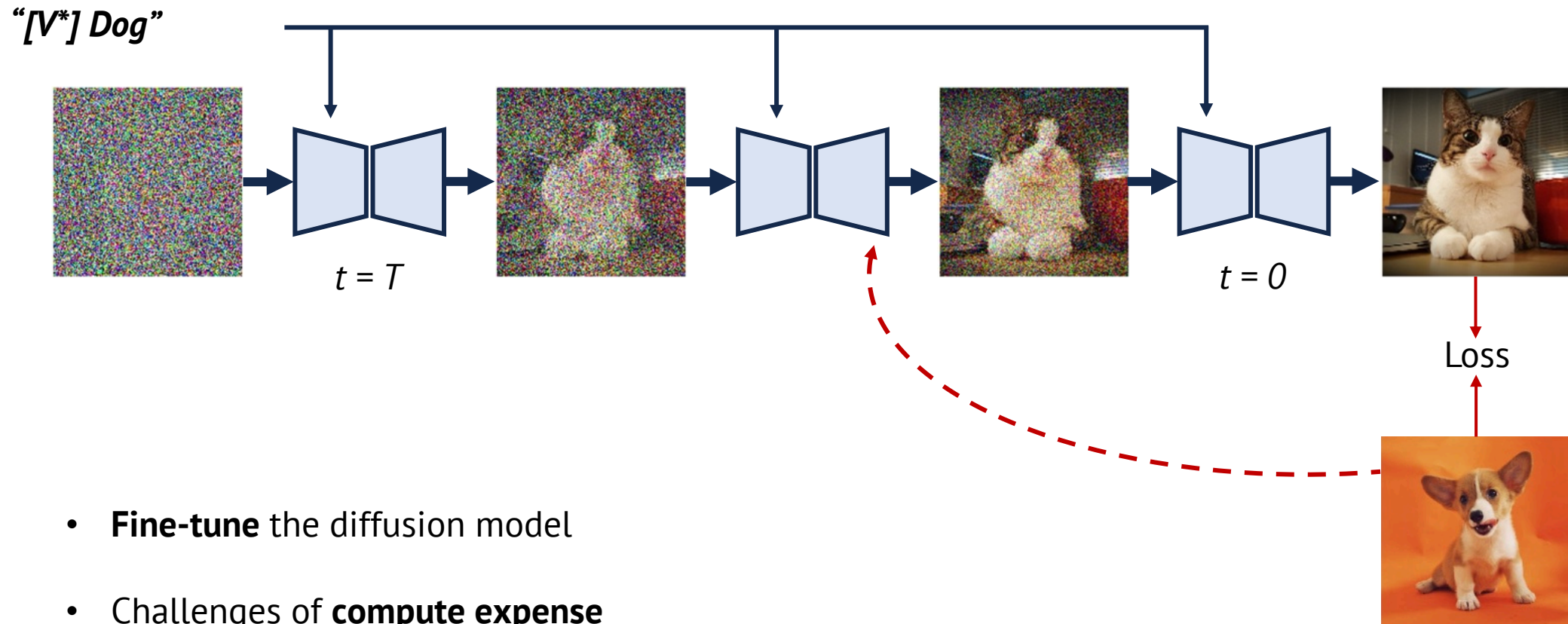


in a bucket

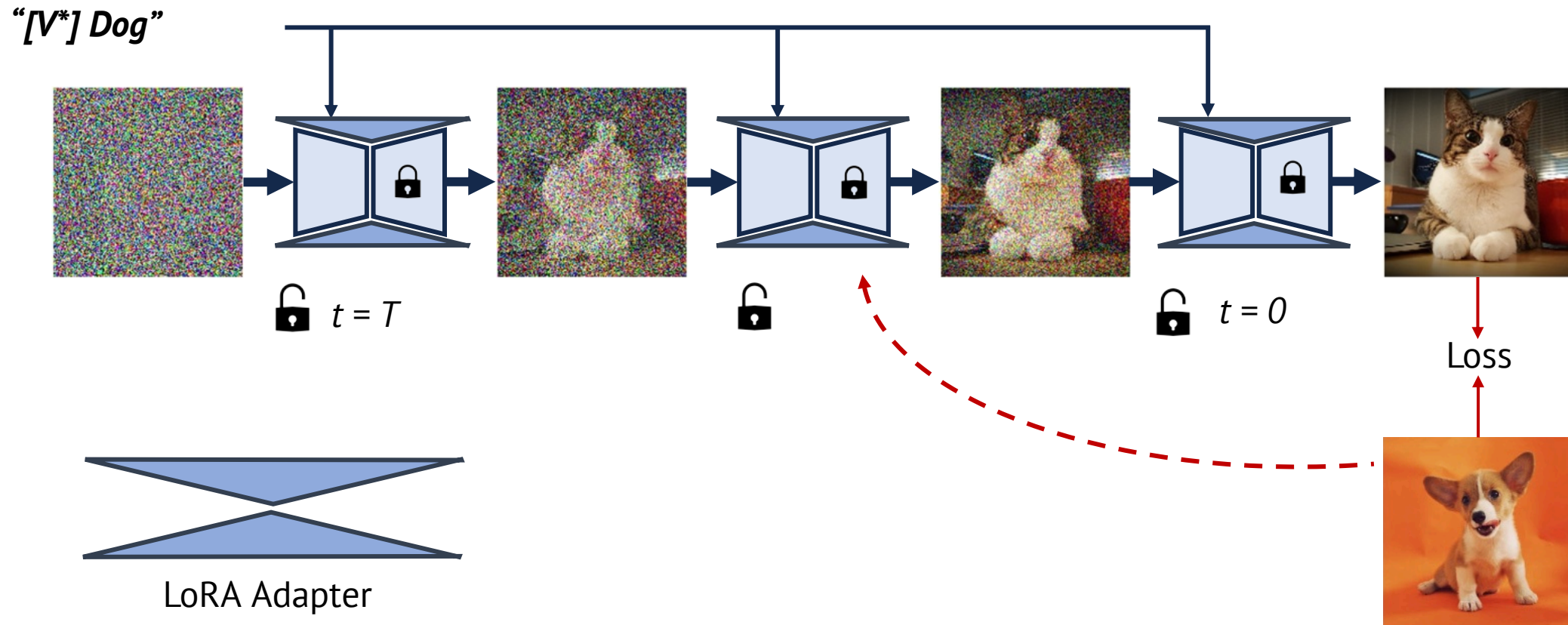


getting a haircut

DreamBooth: Local Customization of Diffusion Model

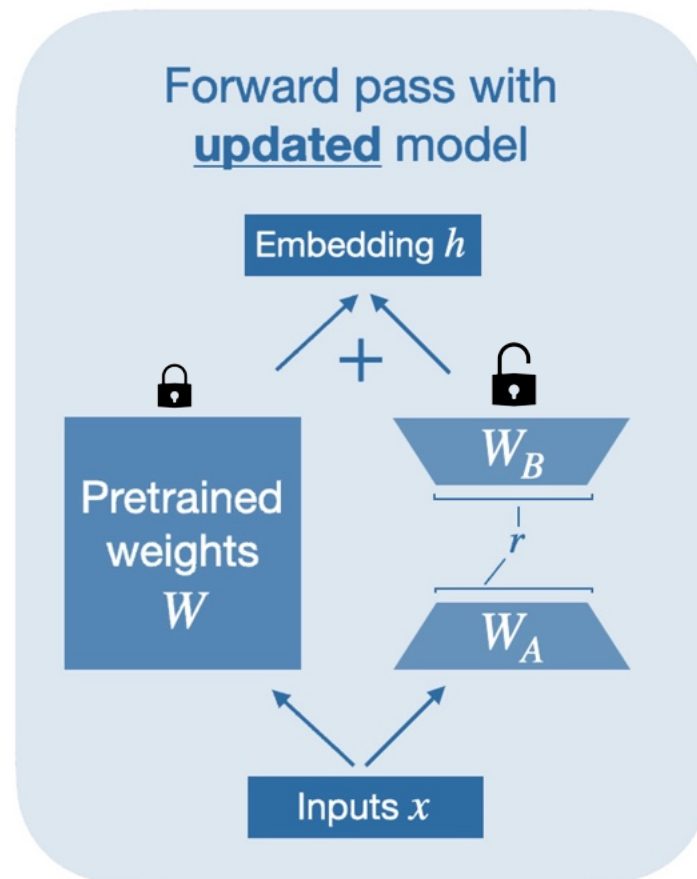
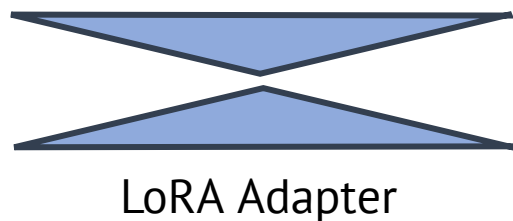


DreamBooth with Low Rank Approximation (LoRA)



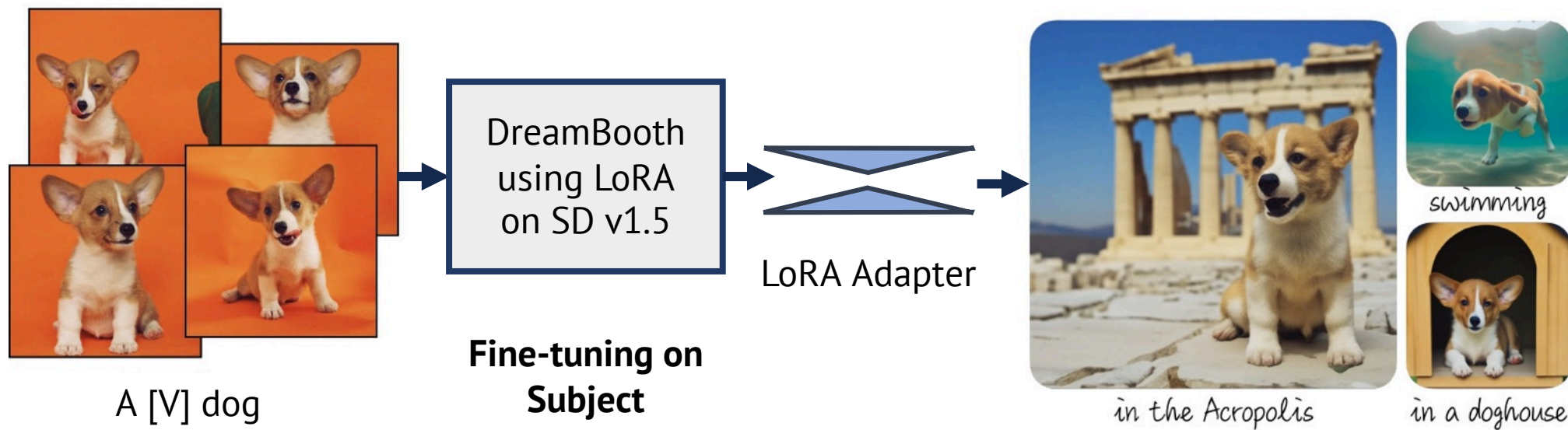
Low Rank Approximation (LoRA)

LoRA weights, W_A and W_B , represent ΔW

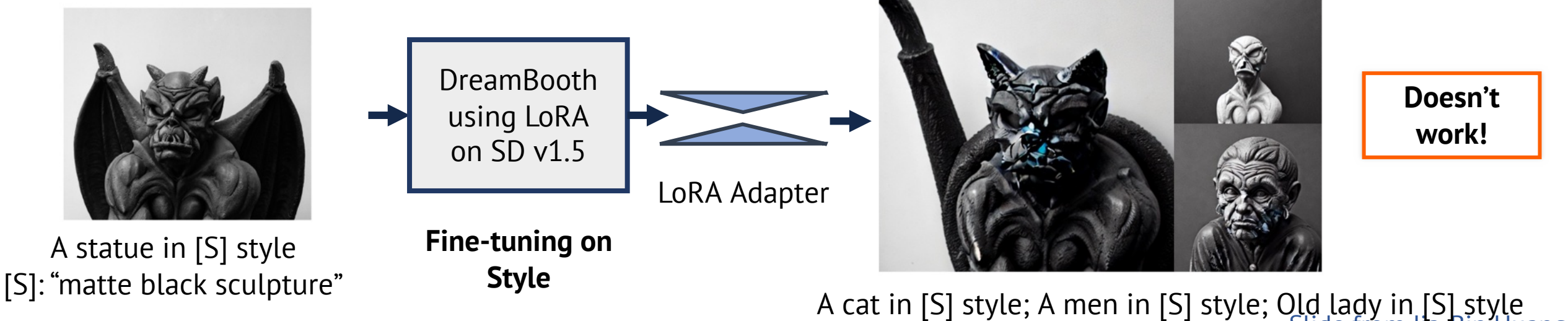
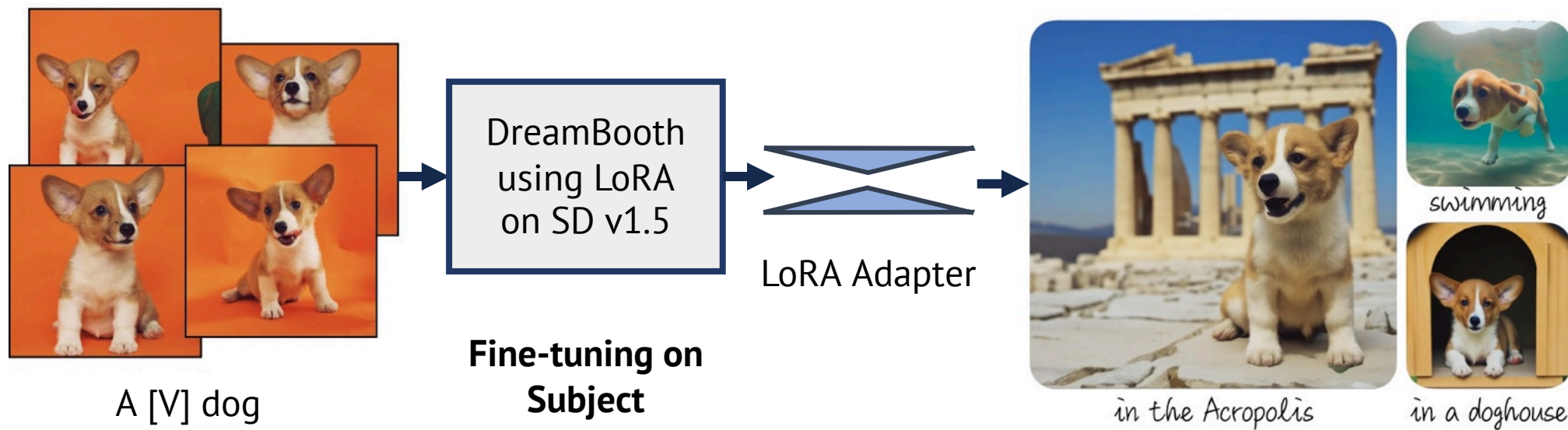


**How to use LoRA
Fine-tuning for
Stylization?**

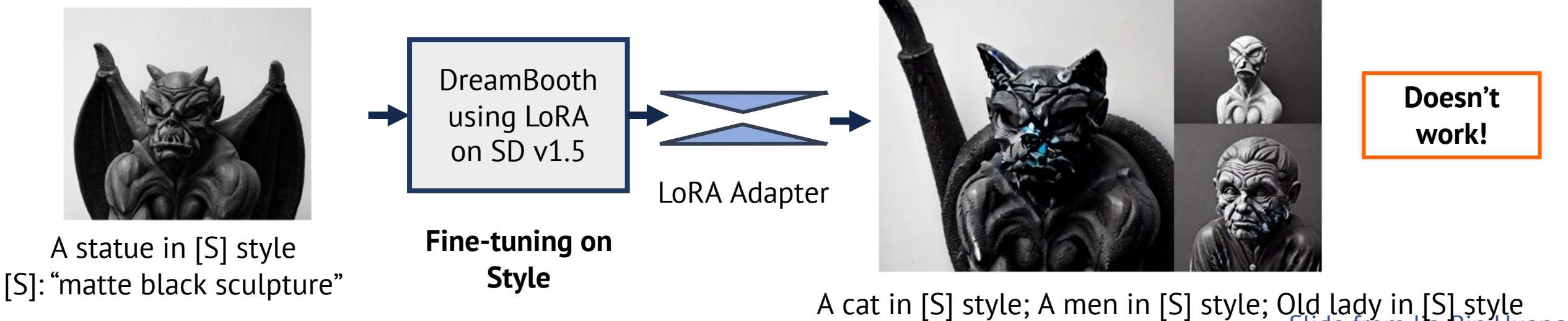
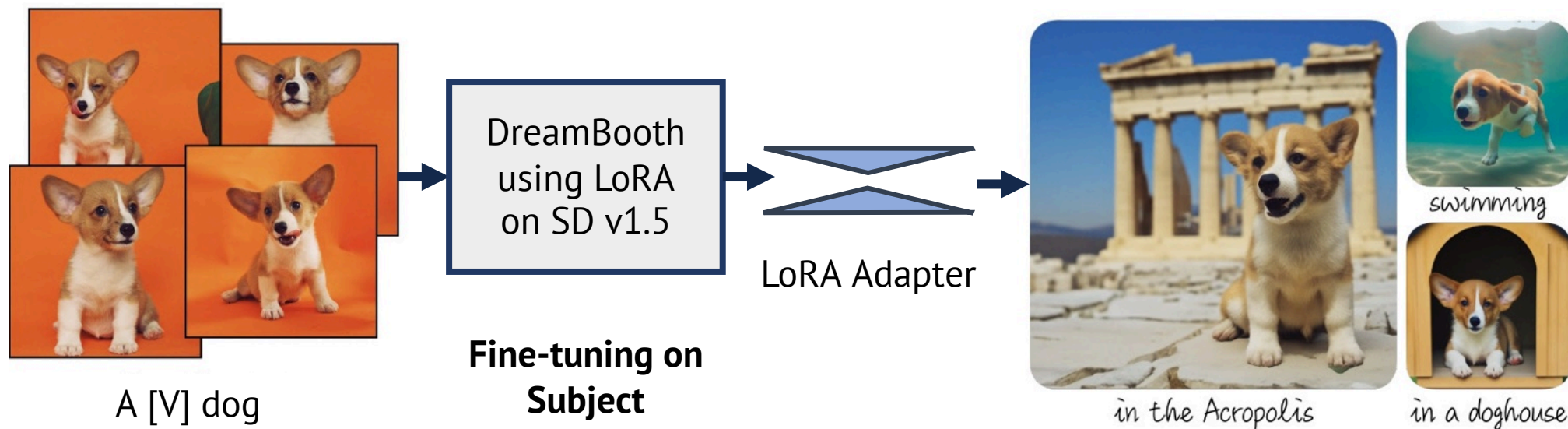
DreamBooth with Low Rank Approximation (LoRA)



DreamBooth with Low Rank Approximation (LoRA)



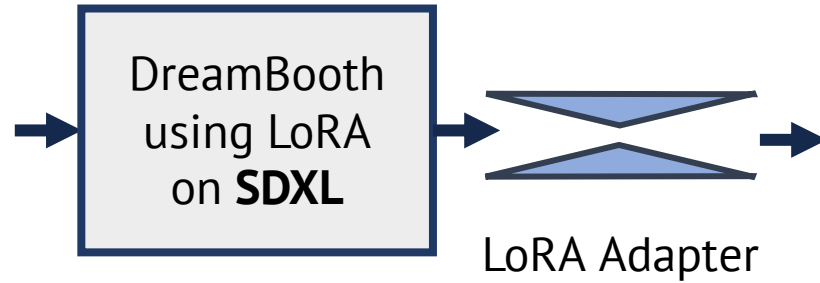
DreamBooth with Low Rank Approximation (LoRA)



LoRA on SDXL



A statue in [S] style
[S]: “matte black sculpture”



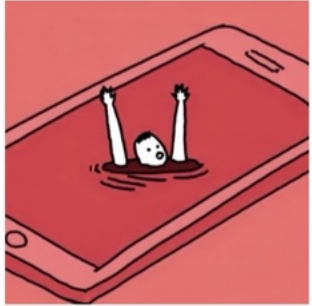
A cat in [S] style; A men in [S] style; Old lady in [S] style

**Works with
SDXL!**

DreamBooth LoRA on SDXL for Stylizations



Style Reference



cartoon line drawing



watercolor painting

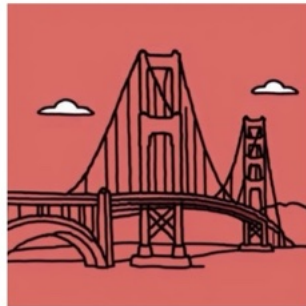


watercolor painting

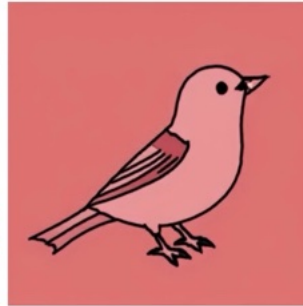
A bicycle in [S]
Style



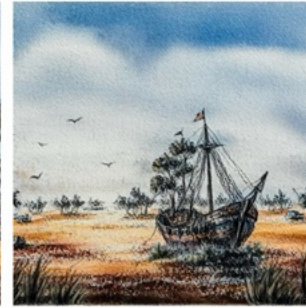
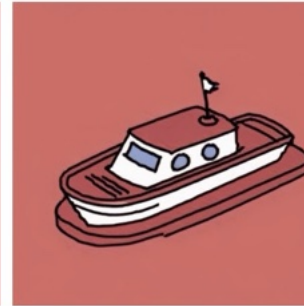
Golden gate
bridge in [S] Style



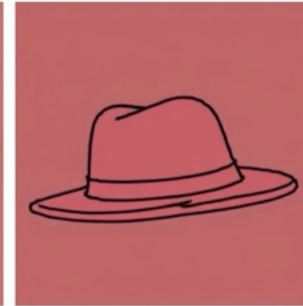
A bird in
[S] Style



A boat in
[S] Style



A hat in
[S] Style

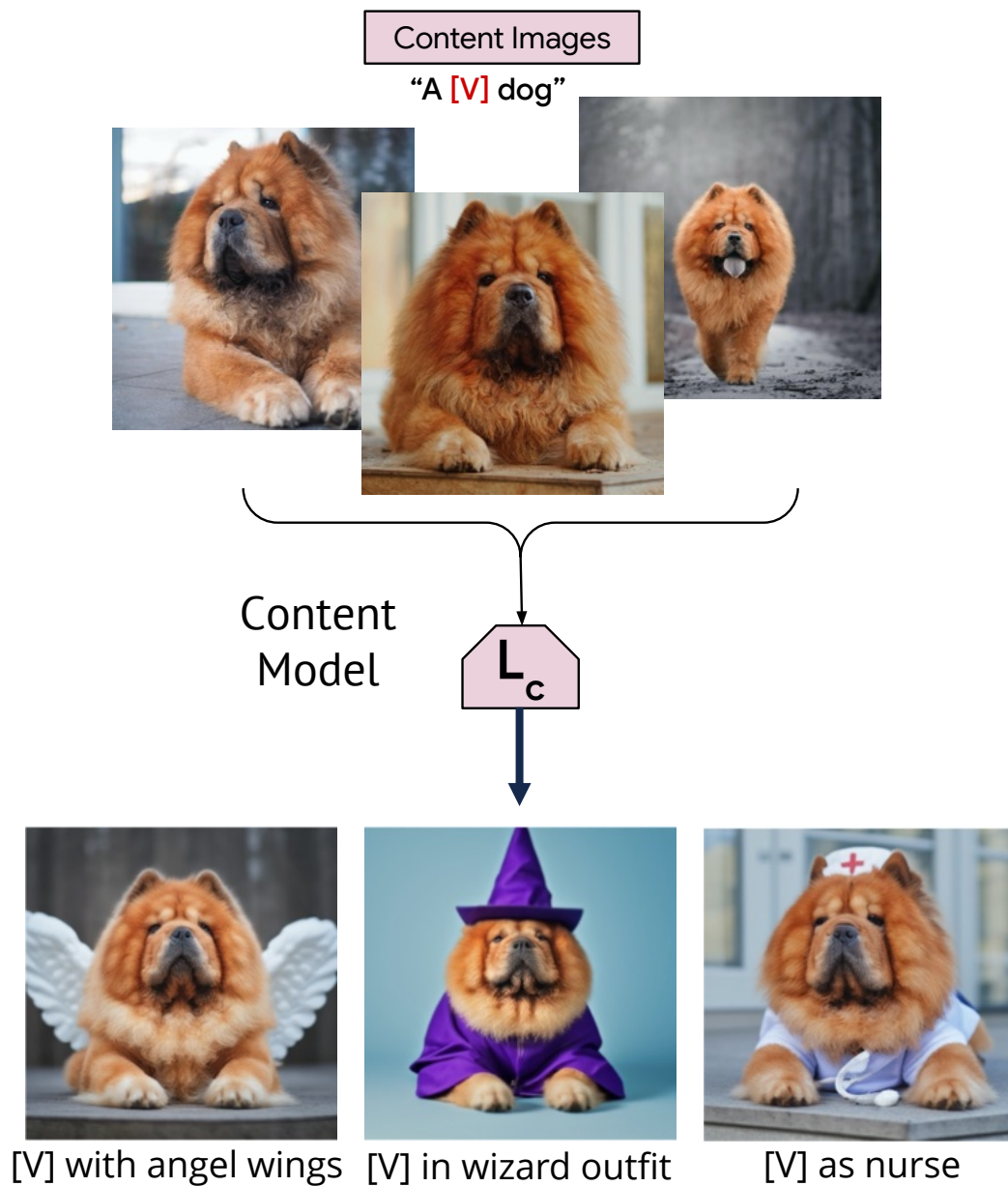


A piano in
[S] Style

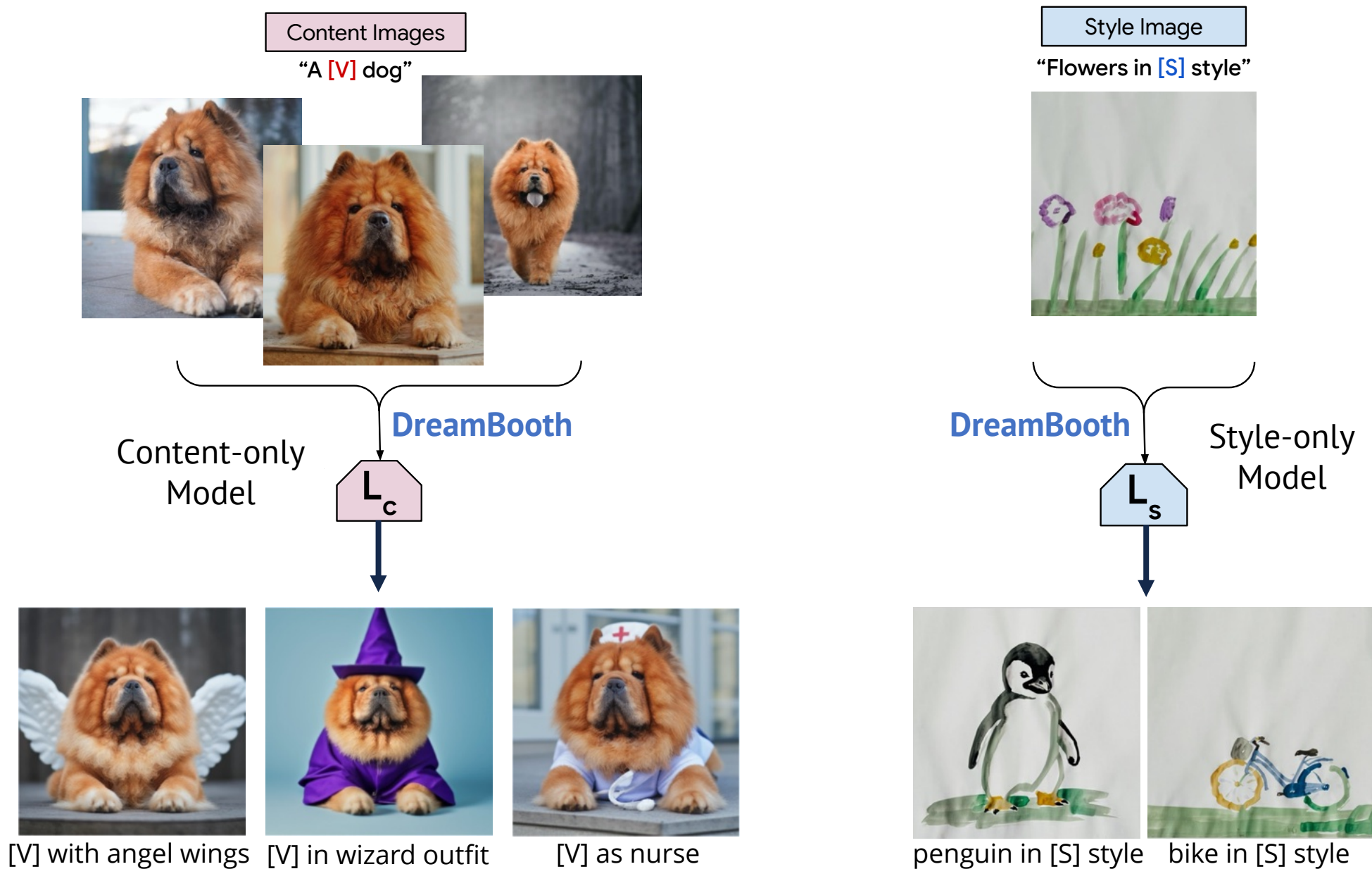


Stylizations obtained using DreamBooth on SDXL with LoRA

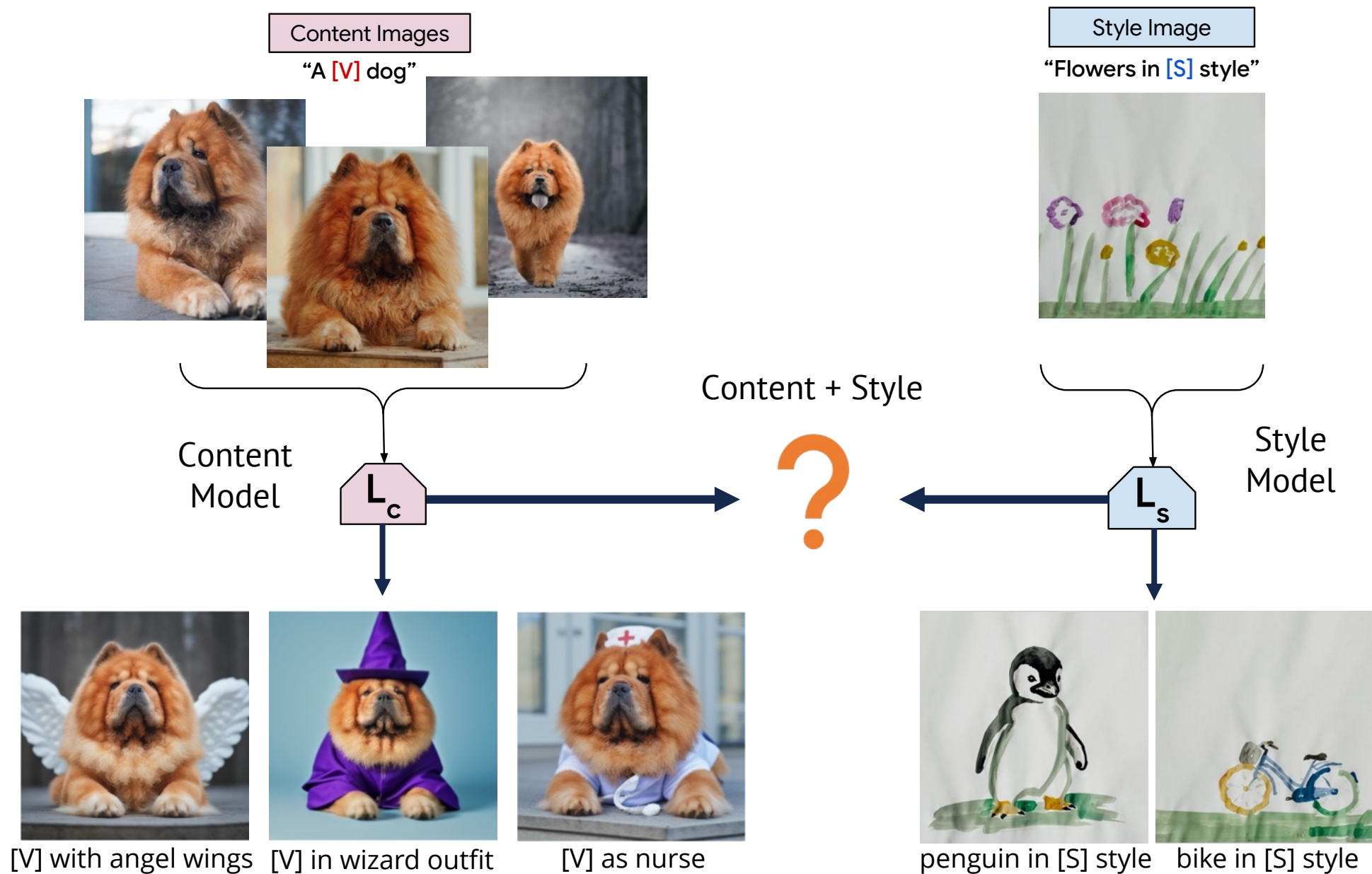
Can we Merge Content and Style Models?



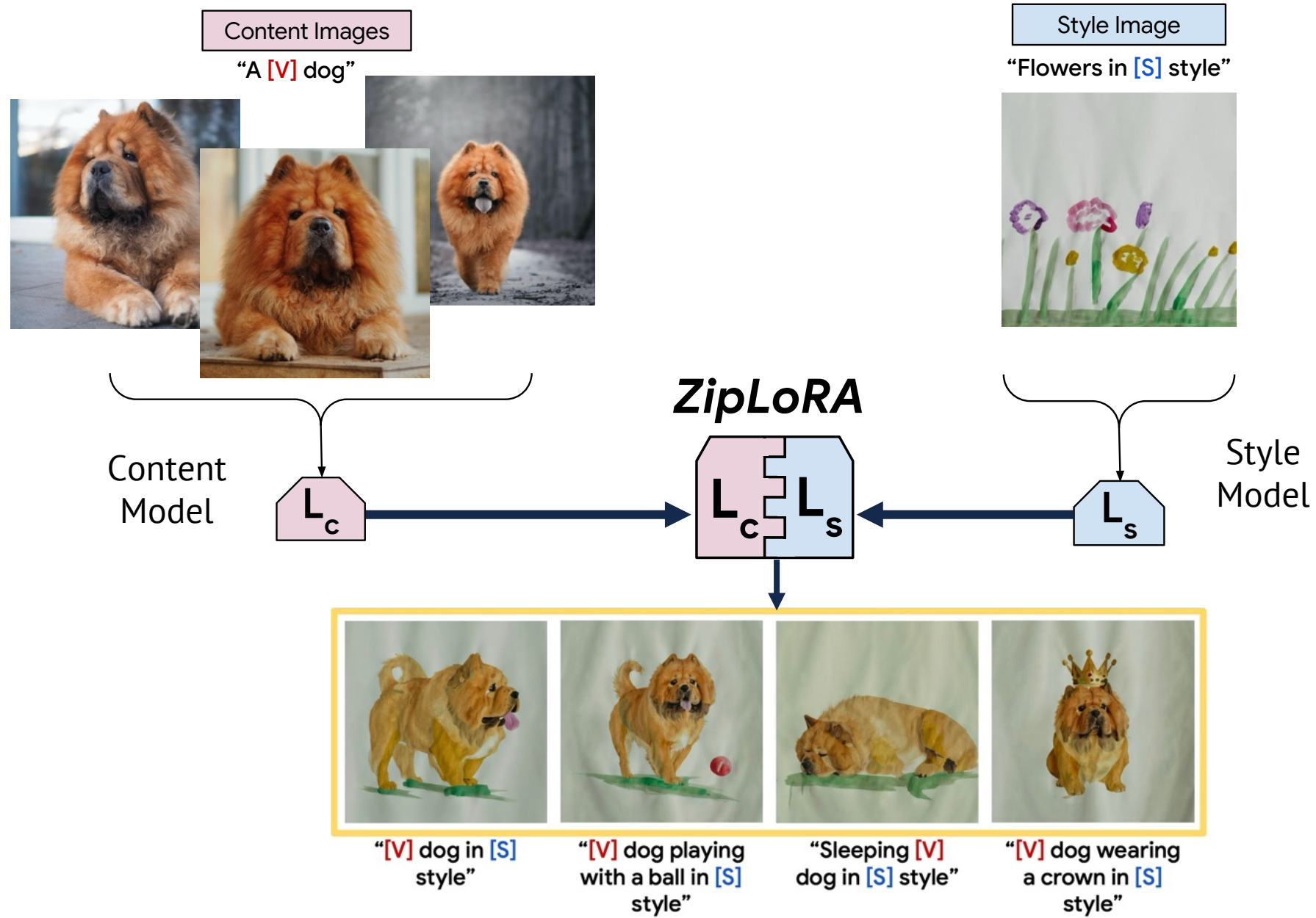
Can we Merge Content and Style Models?



Can we Merge Content and Style Models?

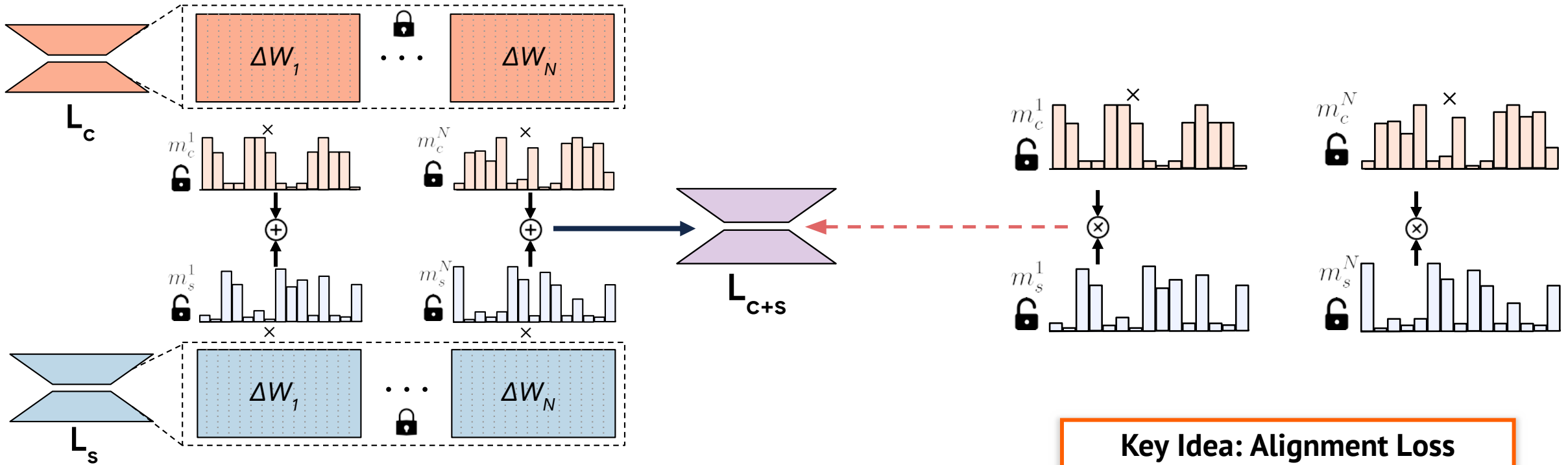


Can we Merge Content and Style Models?





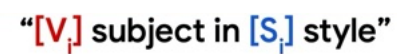
ZipLoRA: Alignment Loss



Key Idea: Alignment Loss

Make m_c and m_s orthogonal with each other!

↓ Subjects:
[V_i]



A [V] toy in	watercolor painting style	kid line drawing style	flat cartoon illustration style
Direct arithmetic merge			
Joint Training			
StyleDrop			
Ours			



Please fill in the Feedback Form at:

<https://virajshah.com/sc395-feedback4>

Thank You!